Towards ACTS KalmanFitter on GPUs

Xiaocong Ai

April 17, 2020



The observations so far

- What are working:
 - Template
 - Virtual function (works with CUDA, not with SYCL?)
 - Eigen works
 - Potential issue with dynamic-size matrix (coefficients are stored as a pointer to a dynamically-allocated array)
- What are NOT working:
 - std::function
 - Ordinary containers (e.g. std::vector, std::array) and algorithms (e.g. std::sort) in C++ STL are not usable
 - Use C array or Eigen::array/Eigen::matrix (static memory allocation)
 - Use explicit heap memory allocation where needed

ATLAS B field on GPUs

- Reminder of the object ownership: Acts::Grid → Acts::InterpolatedBFieldMapper → Acts::InterpolatedBFieldMap → Acts::EigenStepper → Acts::Propagator
- B field values stored at Acts::Grid requires large memory allocation (can only be done on heap)
 - std::vector is replaced by a pointer to a dynamically allocated memory

But cudaMemCpy of propagator from host to device won't copy the field values!

private:

/// set of axis defining the multi-dimensional grid
std::tuple<Axes...> m_axes;

/// linear value store for each bin
std::vector<T> m_values;



```
/// @brief default constructor
111
/// @param [in] axes actual axis objects spanning the grid
ACTS_DEVICE_FUNC Grid(std::tuple<Axes...> axes) : m_axes(std::move(axes)) {
   m_values = new T[size()];
/// Copy constructor
111
/// @param rhs is the source Grid
ACTS_DEVICE_FUNC Grid(const Grid &rhs) : m_axes(rhs.m_axes) {
   m_values = new T[rhs.size()];
  memcpy(m_values, rhs.m_values, sizeof(T) * rhs.size());
/// Assignment constructor
111
/// @param rhs is the source Grid
ACTS_DEVICE_FUNC Grid & operator=(const Grid & rhs) {
   m axes = rhs.m axes;
  m_values = new T[rhs.size()];
   memcpy(m_values, rhs.m_values, sizeof(T) * rhs.size());
  return (*this);
/// @brief default destructor
111
ACTS_DEVICE_FUNC ~Grid() { delete[] m_values; }
private:
```

```
/// set of axis defining the multi-dimensional grid
std::tuple<Axes...> m_axes;
```

```
/// pointer to linear value store for each bin
T *m_values;
```

ATLAS B field on GPUs

- The awkward way out:
 - Explicit allocation of grid values are done on device
 - Grid values are then copied from host to device
 - Inside CUDA kernel, explicitly make the member pointer of Grid object explicitly point to the grid values on device

GPUERRCHK(cudaMalloc(&d_propagator, sizeof(PropagatorType)));

// Run on device

```
int threadsPerBlock = 256;
```

```
int blocksPerGrid = (nTracks + threadsPerBlock - 1) / threadsPerBlock;
propKernel<<<blocksPerGrid, threadsPerBlock>>>(
```

```
d propagator, d pars, d opt, d ress, d gridValPtr, nTracks);
```

```
// Device code
```

propagator->propagate(tpars[i], *propOptions, propResult[i]);

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The results

- Results on GPUs are validated
- GPUs win over CPU@many threads execution when N_{tracks} > 30k at non-constant B field

Validation of results with starting Pos = $(0,0,0)$ and Mom = $(1, 0, 1)$ GeV/c at ATLAS BField	
prpagation positons on CPU	Propagation positions on GPU
<pre>v 0.383073 -2.92701e-05 0.383073 v 0.766147 -0.000131716 0.766147 v 1.14922 -0.000307337 1.14922 v 1.53229 -0.000556133 1.53229 v 1.91537 -0.000878105 1.91537 v 2.29844 -0.00127325 2.29844</pre>	v 0.383073 -2.92701e-05 0.383073
	v 0.766147 -0.000131716 0.766147
	v 1.14922 -0.000307337 1.14922
	v 1.91537 -0.000878105 1.91537
	v 2.29844 -0.00127325 2.29844
V 2.68151 -0.00174158 2.68151	v 2 68151 -0 00174158 2 68151

v 3.06459 -0.00228308 3.06459

v 3.44766 -0.00289775 3.44766

v 3.83073 -0.00358561 3.83073

Constant B Field



ATLAS B Field

v 3.06459 -0.00228308 3.06459

v 3.44766 -0.00289775 3.44766

v 3.83073 -0.00358561 3.83073

Propagation tests (ATLAS B Field, pT=0.1GeV/c, nSteps = 1000)

Intel Xeon Gold 6148 ('Skylake')
 Intel Xeon Gold 6148 ('Skylake') with OpenMP
 NVIDIA V100 ('Volta')



Discussion

- Can we survive without STL containers and algorithms?
 - CUDA: thrust library
 - SYCL: SyclParalleISTL
- How to handle dynamic memory allocation?
 - Seems each relevant class needs to have a user-defined constructor/destructor-like cudaMalloc/cudaMemCpy method that calls those methods of its data members recursively
- Attempted to-do-list
 - Construct a simple geometry with a list of (planar) surfaces which could barely do local<=>global transforms and boundary check
 - Simplify the concept of measurement, track parameter and track state
 - Finally, work out a KalmanFilter with barely updater (and smoother)

In general, GPUs implementation of the whole ACTS seems not realistic and worthwhile