

alpaka Parallel Programming – Online Tutorial

Lecture 30 – Portability with alpaka

Lesson 32: The Accelerator Concept



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Introduction

- alpaka's Accelerator concept is an important tool
- Accelerator hides hardware specifics behind alpaka's abstract API
- Chosen by programmer:

```
using Acc = acc::AccGpuCudaRt<Dim, Idx>;
```
- Used on both Host and Device
- Inside Kernel: contains thread state, provides access to alpaka's device-side API
- On Host: Meta-parameter for choosing correct physical device and dependent types

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Accelerators and devices

- Accelerator concept is an abstraction of concrete devices and programming models
- The programmer changes the accelerator in just one line of code
- In the background, an entirely different code path for the “new” device is chosen
- Accelerator provides portable access to device-specific functions

```
/* Before the code change */  
using Acc = acc::AccCpuOmp2Blocks<Dim, Idx>;
```

```
/* Kernels will run on CPUs */  
/* Parallelism provided by OpenMP 2.x */
```

```
/* After the code change */  
using Acc = acc::AccGpuHipRt<Dim, Idx>;
```

```
/* Kernels will run on AMD + NVIDIA GPUs */  
/* Parallelism provided by HIP */
```

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Grid navigation

- The Accelerator provides the means to navigate the grid:

```
// get thread index on the grid  
auto gridThreadId = idx::getIdx<Grid, Threads>(acc);
```

```
// get block index on the grid  
auto gridBlockIdx = idx::getIdx<Grid, Blocks>(acc);
```

```
// get thread index on the block  
auto blockThreadId = idx::getIdx<Block, Threads>(acc);
```

```
// get number of blocks on the grid  
auto gridBlockExtent = workdiv::getWorkDiv<Grid, Blocks>(acc);
```

```
// get number of threads on the block  
auto blockThreadExtent = workdiv::getWorkDiv<Block, Threads>(acc);
```

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Memory management and synchronization

- The Accelerator gives access to alpaka's shared memory (for threads inside the same block):

```
// allocate a variable in block shared static memory  
auto & mySharedVar = block::shared::st::allocVar<int, __COUNTER__>(acc);
```

```
// get pointer to the block shared dynamic memory  
float * mySharedBuffer = block::shared::dyn::getMem<float>(acc);
```

- It also enables synchronization on the block level:

```
// synchronize all threads within the block  
block::sync::syncBlockThreads(acc);
```

```
// synchronize some threads within the block and evaluate predicate  
block::sync::syncBlockThreadsPredicate(acc, predicate);
```

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Device-side functions

- Internally, the accelerator maps all device-side functions to their native counterparts
- Device-side functions require the accelerator as first argument:
 - `math::sqrt(acc, /* ... */)`; (Math functions)
 - `atomic::atomicOp<atomic::op::Or>(acc, /* ... */, hierarchy::Grids)`; (Atomics)
 - `rand::distribution::createNormalReal<float>(acc)`; (Random-number generation)
 - `time::clock(acc)`; (Clock cycles)



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