

A course on embedded systems at the University of Cape Coast, Ghana

Uli Raich
Formally CERN, Geneva
now retired



African School of Fundamental
Physics and Applications

Long time ago ...

- Studied Mathematics and Physics at the University of Karlsruhe (Germany) to become a high school teacher
- Came to CERN as a doctoral student
- After getting my PhD from the University of Karlsruhe I stayed at CERN and worked in the accelerator field (Linear accelerators, accelerator control, beam diagnostics)
- Took part in a technical training course on micro processors, a totally new and exciting technology
- Was asked to participate in a course on microprocessors for physicists and engineers of the developing world at the Abdus Salam ICTP, Trieste as an instructor
- Prof. Salam himself initiated the course
- The course was so successful that it was pursued and continually updated during more than 30 years



Change in Computer over a lifetime

- When I was an undergraduate student I used the university mainframe computer occupying a big room and costing several 100 kUS\$
- As a doctoral student we had a minicomputer costing ~ 80 kUS \$

Specifications:

- 16 bit CPU
- 128 kBytes of RAM
- 600 Mbytes of hard disk
- 1 serial terminal
- Camac interface to control the entire linear accelerator



Microprocessors

- When I started to work on microprocessors in the early 1980's these were very simple devices containing just a single 8 bit CPU (1 MHz) and address and data lines + a few control lines to interface to external memory and I/O interfaces, typically : a serial and a parallel port.



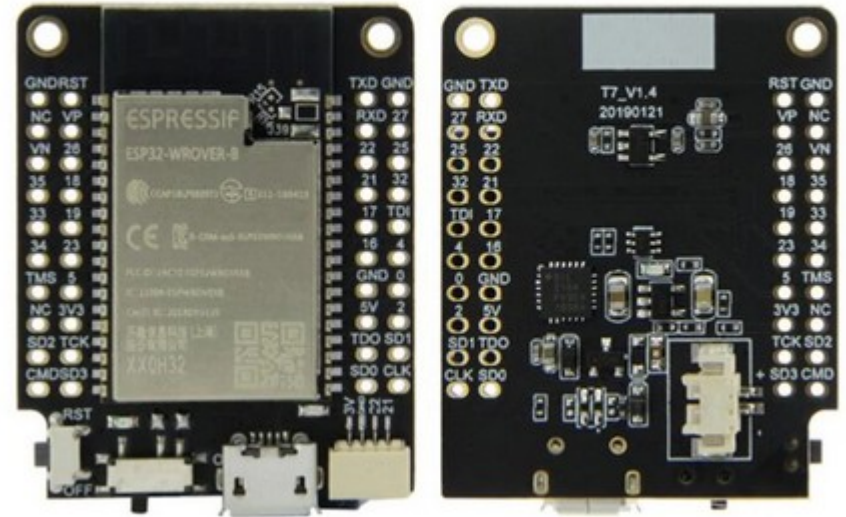
- The price for the chip was 176 US \$.
- The development board was sold for 300 US \$. You got 256 bytes of RAM, 2kBytes of EPROM and the serial and parallel port.
- Programming was done in assembly language or even straight machine code.
- **No Internet!**



The micro-controller I use today

- Dual core 32 bit CPU (80 – 240 MHz)
- 520 kB SRAM + 8 MB PSRAM
- 4MB flash
- Interfaces:
I2C, I2S, SPI, GPIO, ADC, DAC
- Can run on battery
- WiFi: 802.11 b/g/n
- BlueTooth and BlueTooth Low Energy
- Cost: 5.52 Euros

ESP32-WROVER-B



Students became lecturers



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Nii Quaynor

From Wikipedia, the free encyclopedia

For the Ghanaian rapper whose full name is Nii Addo Quaynor, see [Tinny \(musician\)](#).

Prof. Nii Narku Quaynor is a scientist and engineer who has played an important role in the introduction and development of the [Internet](#) throughout [Africa](#).

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Biography [edit]

Prof. Quaynor graduated in engineering science from [Dartmouth College](#) in 1972 and received a Bachelor of Engineering degree from the [Thayer School of Engineering](#) there in 1973. He then studied Computer Science, obtaining an M.S. from the [State University of New York](#) at StonyBrook in 1974 and a Ph.D. from the same institution in 1977. He attended Kinbu, [Adisadel College](#)^[citation needed] and [Achimota School](#) in Ghana

He is one of the founding members of the Computer Science Department at the [University of Cape Coast](#) in [Ghana](#), and continues to hold a professorship there.^[1] He is also a member of the Council of the University of

Nii Narku Quaynor



Prof. Nii Narku Quaynor

Born	Nii Narku Quaynor
Occupation	Computer Scientist
Known for	Developing telecommunications and Internet in Africa
Title	Professor

An offer

I had the idea to terminate my professional career with a stay at a university in the developing world and give back a bit of what I had received during the 30 years of microprocessor courses.

Then Nii asked me:

- Can you come to Cape Coast for 3 weeks to help the university set up a course on embedded systems?
- ... or may be 6 weeks?
- Well, best would be you come for a full semester of 4 months!



The Deal

I provide:

- Setup of the embedded systems lab with 15 experimental stations
- 2h of formal lectures per week for 12 weeks
- 4h of practical sessions per week

The university

- Provides the course material (lab hardware and Internet infrastructure)
- Pays the flight and living expenses
- Provides housing
- Frees at least one local lecturer to work with me on the course. This lecturer takes over the lab and further development of the course after my departure



The goal

- Have a working lab for 15 students with up to date development software on PC computers
- 12 experiments with exercise sheets and working solutions
- Documentation of the whole course on the WEB with the possibility of easy extension
 - Lecture slides
 - Exercise sheets and solutions that can be downloaded and executed on the hardware
 - Description of sensors and actuators including data sheets for interface chips and circuit diagrams
- Final course examination
- Transmission of knowledge to the local lecturers



Hard- and Software selection

On the hardware side we had 2 contenders:

- Arduino
- Raspberry Pi



Arduino advantages

The Arduino is essentially a standardized software development system (IDE, Integrated Development Environment) running on any PC or Mac. It uses its own dialect of C++ and works on a number of hardware platforms:

- Atmel AVR processors
- ST: STM32 ARM processors
- Espressif ESP8266 and ESP32 processors

Advantages:

- Very popular among universities and the hobbyists
- Very cheap hardware (typically less than 10 US \$ for the CPU card)
- Drivers for almost any sensor or actuator are available
- Uses plug-on shields



Arduino disadvantages

- Can only be programmed in its specific C++ dialect
- Only cross compilation is possible
- Internet access needs additional hardware (but is possible)
- No hard disk or equivalent





```
01-SimpleServo | Arduino 1.8.14
File Edit Sketch Tools Help
01-SimpleServo
#include <Servo.h>

static const int servoPin = 4;

Servo servo1;

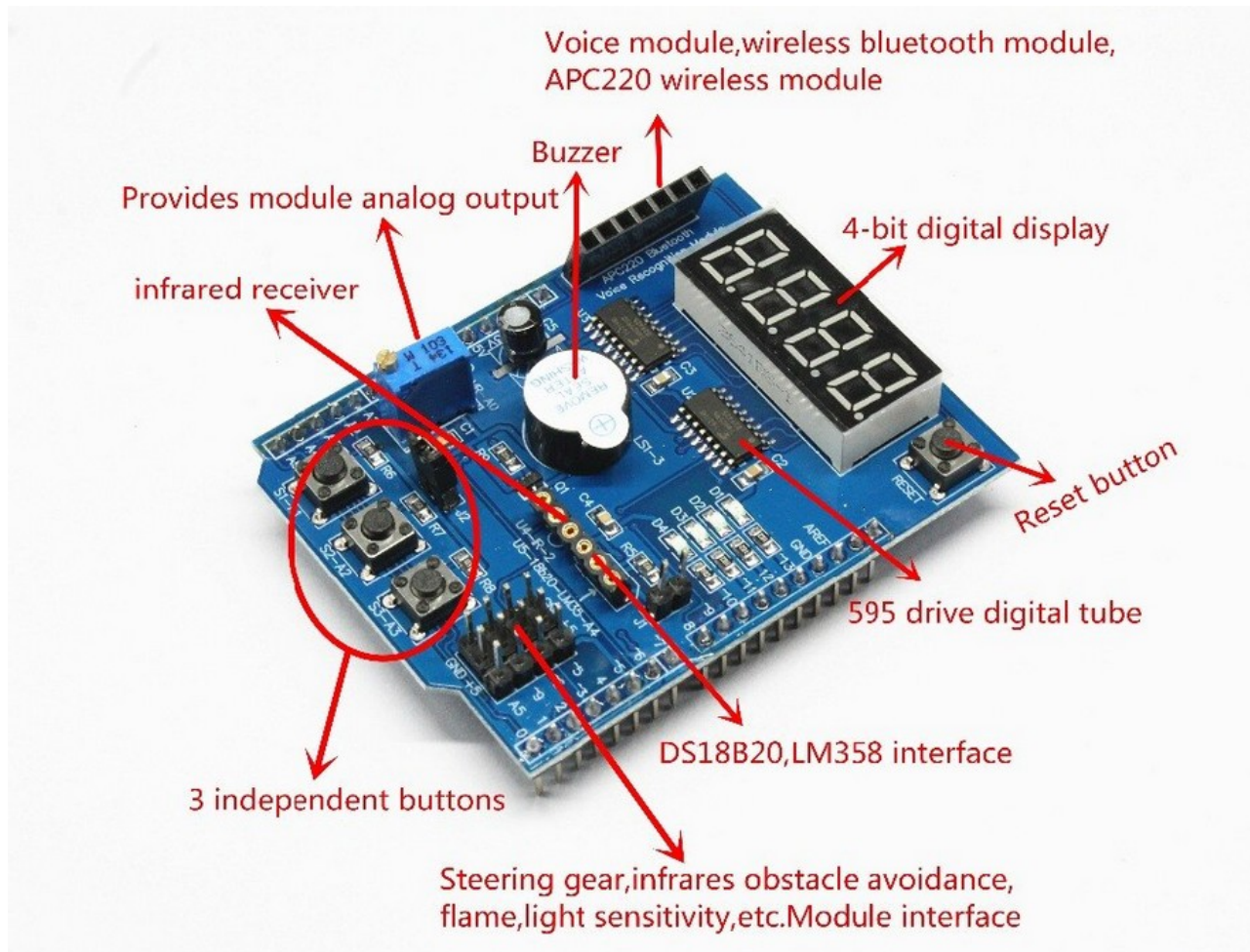
void setup() {
  Serial.begin(115200);
  servo1.attach(servoPin);
}

void loop() {
  for(int posDegrees = 0; posDegrees <= 180; posDegrees++) {
    servo1.write(posDegrees);
    Serial.println(posDegrees);
    delay(20);
  }

  for(int posDegrees = 180; posDegrees >= 0; posDegrees--) {
    servo1.write(posDegrees);
    Serial.println(posDegrees);
    delay(20);
  }
}

1 TTGO T-Watch, Enabled, Default (2 x 6.5 MB app, 3.6 MB SPIFFS), 2000000, None on /dev/ttyUSB0
```





Raspberry Pi

Advantages:

- Very powerful hardware
- Internet access built in (Ethernet and WiFi)
- Runs Linux operating system and can be used as a standalone computer
 - Needs a screen, keyboard and mouse. Interfaces are available
- Programming can be done in any programming language supported by Linux
- Uses micro SD card for OS and storage of local files
- Very popular, with some 10 million units sold
- Good support by community



Raspberry Pi disadvantages

- Not all drivers are available (but most!) for all programming languages
- Higher price (~ 80 US \$)



The shopping list

Finally and despite its higher price we went for the Raspberry because of better performance and its use of standard programming languages

We used C for the course.

In addition to the system board we acquired:

- A kit with 37 sensors and actuators
- Stepping motor + controller
- ADC (Analogue to Digital Converter)
- DAC (Digital to Analogue Converter)
- Atmospheric pressure sensor
- 2 line LCD display

Several Arduinos were bought for student projects.



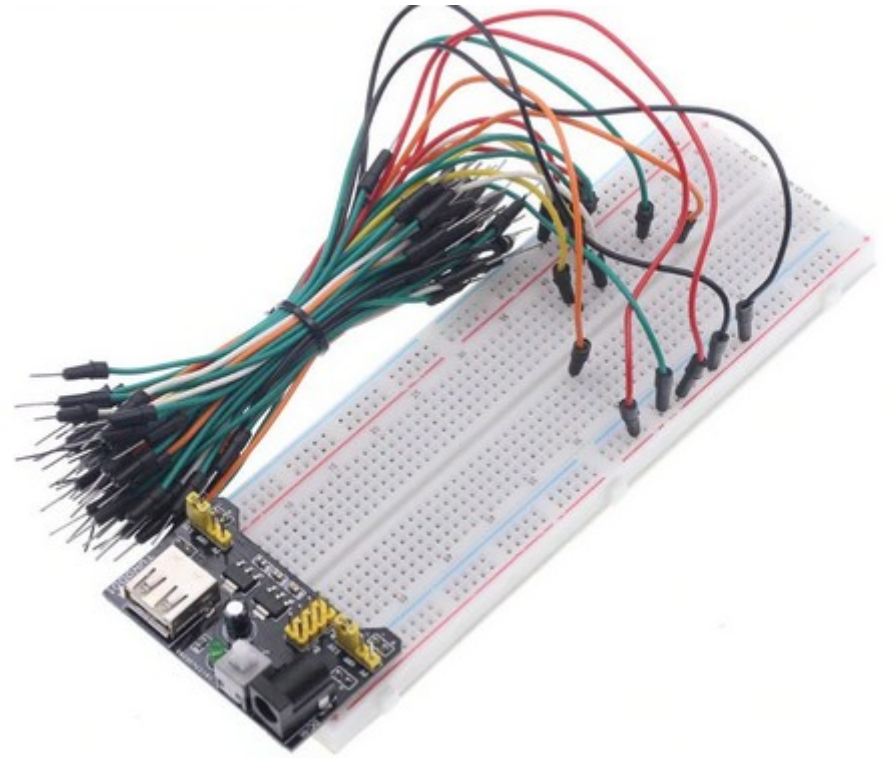
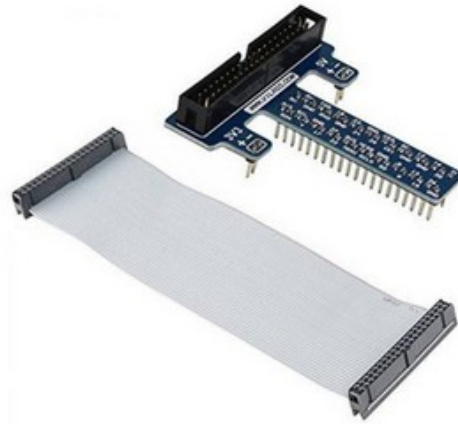
The Raspberry Pi

The Raspberry Pi is a small computer powerful enough to run a full blown Linux operating system. The 3rd version of this board features:




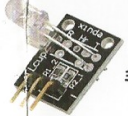
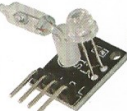


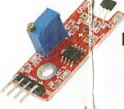
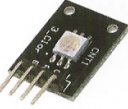
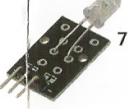
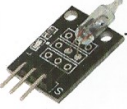
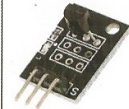


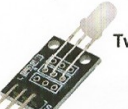

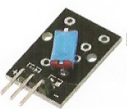
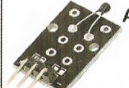

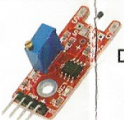
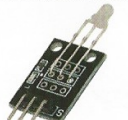
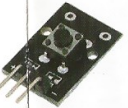
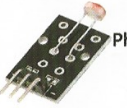
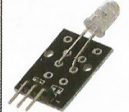

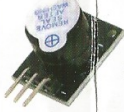

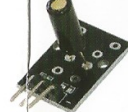
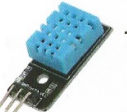


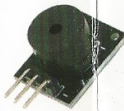



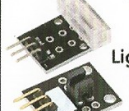
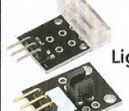
- A quad core 1.2 GHz Broadcom BCM2837 64 bit CPU
- 1 GByte of RAM
- Ethernet and WiFi network interfaces
- 4 USB-2 ports
- Full size HDMI
- a camera port
- Micro SD connector
- A 40 pin extended GPIO connector with GPIO, SPI and I2C bus interfaces



Connecting to the outside world

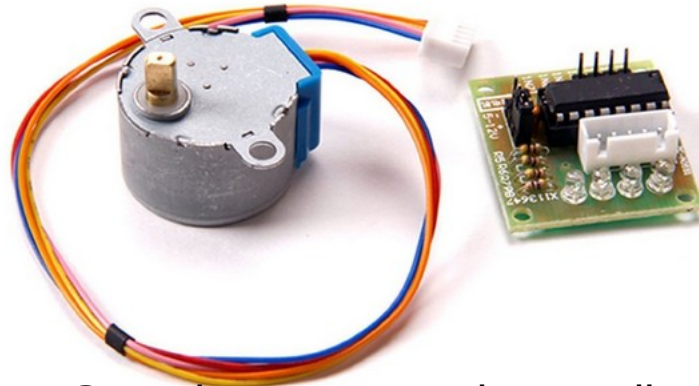
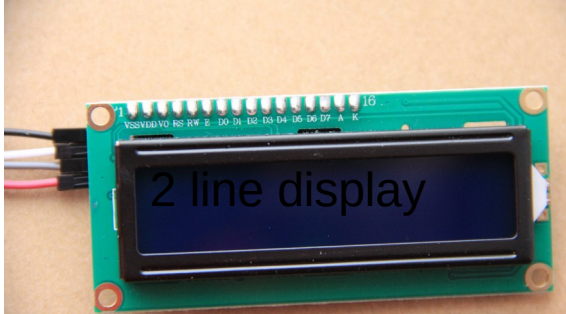
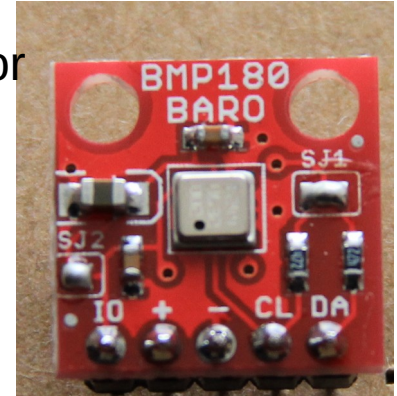


Sensor Kit for Arduino

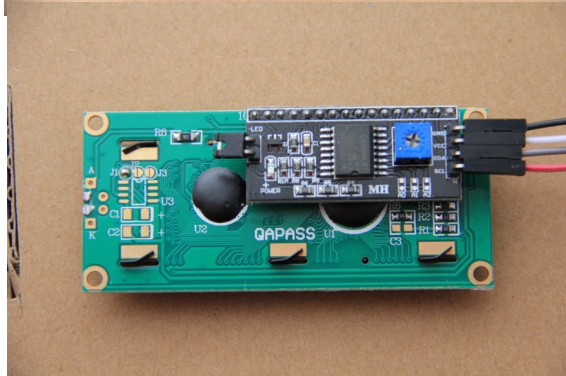
 joystick XY摇杆	 Flame 火焰传感器	 RGB LED 3色灯模块	 Heartbrat 手指测心跳	 Light Cup 魔术光杯	 Hall magnatic 霍尔磁力
 Relay 继电器	 Linear Hall 线性霍尔	 SMD RGB 3色RGB	 7 color flash 7彩闪烁	 Tilt switch 水银开关	 TEMP 18B20
 Big sound 高感度声音	 Touch 人体触摸	 Two-color LED 双色LED	 Laser emit 激光发射	 Ball switch 倾斜开关	 Analog temp 模拟温度
 Small sound 小麦克风	 Digital temp 数字温度	 Two-color 小双色	 Button 按键开关	 Photoresistor 光线	 IR emission 红外发射
 Tracking 循迹	 buzzer 有源蜂鸣器	 Reed switch 磁簧开关	 Shock 震动开关	 Temp and humldlty 温湿度	 IR receiver 红外接收
 Avoid 避障	 passive buzzer 无源蜂鸣器	 Mini Reed 迷你磁簧	 Rotary encoders 旋转编码器	 Analog Hall 模拟霍尔	 Tap module 敲击模块
					 Light blocking 光遮断

Additional sensors

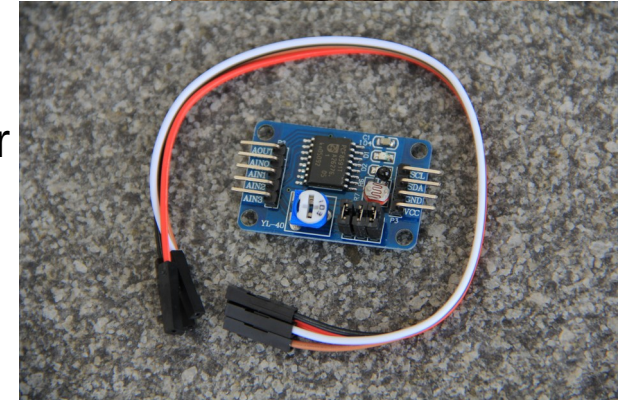
Barometric pressure sensor



Stepping motor and controller



DAC



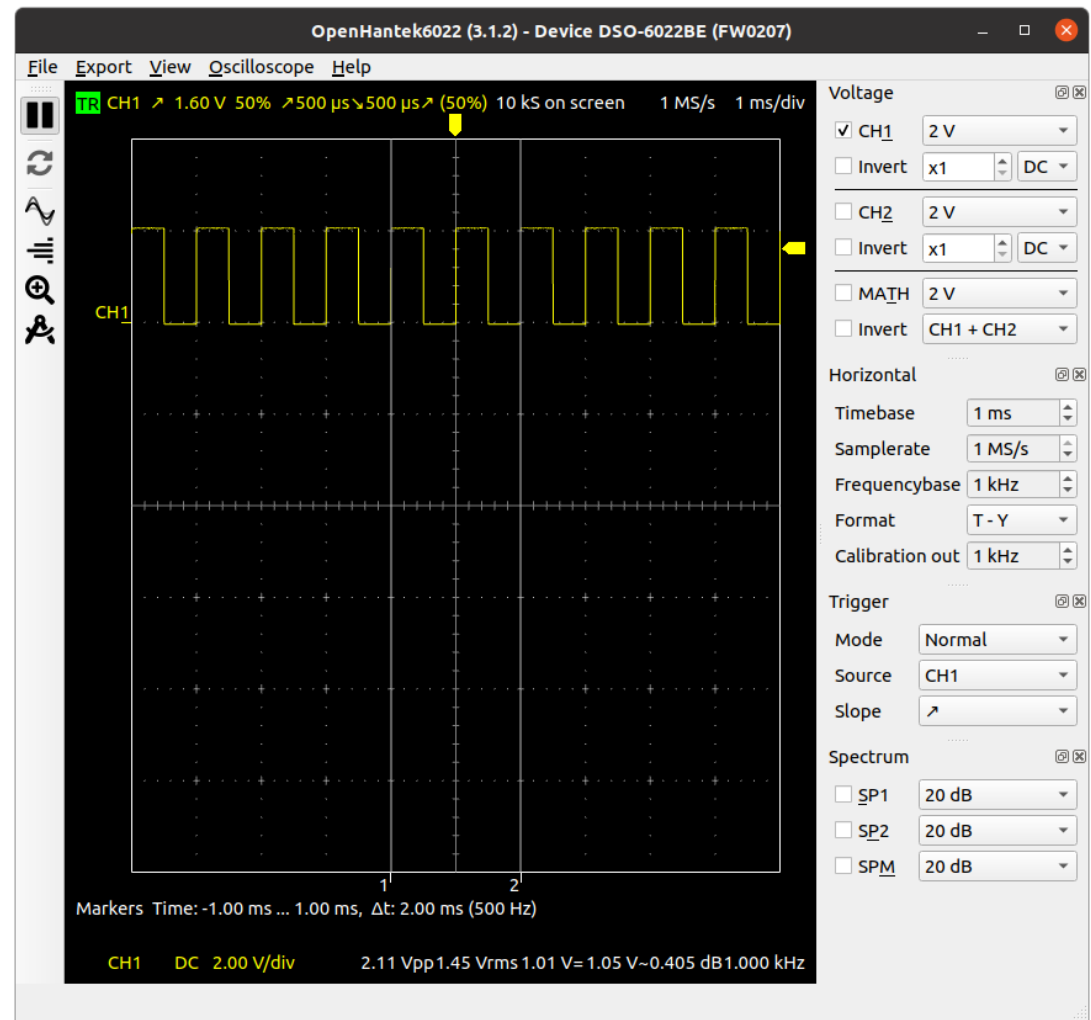
ADC with temperature and light sensor

A cheap oscilloscope

- 2 channels
- 20 MHz bandwidth
- USB interface
- PC used for interaction
- 2 probes
- Only DC coupling
- Cost: 50 Euros



Oscilloscope Software



The course layout

- Introduction
- The Linux operating system and its basic commands
- Introduction to C programming
- An additional lecture on C
- Development tools
- Bringing the Raspberry Pi to life
- Accessing the real world
- DHT11 temperature and humidity measurements
- Stepping motors
- Digital to analogue conversion
- The 2 line display
- Analogue to digital conversion and light intensity measurement



Documentation

- Documentation should be accessible through the WEB
- Should contain
 - Sensor data sheets
 - Lecture slides
 - Exercise sheets and solutions
 - Links to additional documentation
- Should be easy to provide and easy to modify
- Students should be able to provide their own doc

We use [TWiki](#)



A difficult start

- The course was foreseen to start in March
- The shopping list was ready in December and I had my kit for preparation in January
- I requested an official written invitation with the conditions
- By mid February no orders were made by the University and I had no invitation. We decided to postpone the course to September
- By June, still no invitation and no order. I set a limit to mid-July because I also had an invitation to lecture at the CERN school of accelerator.
- 2h before the limit I get an email that everything was settled but the department head, responsible to send the invitation would only come the next week.
- It took another 2 weeks and several reminders to get the invitation, but without conditions



A difficult start (2)

- I went to the Ghanaian embassy to get my visa and they asked me if I was sure about the authenticity of the invitation
- 2 weeks before departure, still no hardware order
- I send my flight dates to the university and get an answer that I could only come for 2 months because of budget restrictions. The department head had changed and the new one did not accept the agreements previously made
- I sent an email to Nii and the former department head telling them about the trouble
- The story goes up to the University's Vice chancellor and I finally get the ok for the dates initially foreseen
- Departure, and still no hardware orders



Arrival in Accra

The last two times I was in Africa I was promised to be picked up at the airport and nobody showed up.

This time it **worked!!!**

Ike, the local lecturer (and friend!) and his wife picked me up with a driver from the university and take me to the university guest house in Accra for the night.

Next day we visit Nii at his company premises and continue to Cape Coast

The promised housing is not ready and I am set up in the university guest house at UCC



Meeting again after 20 years



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The department



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Preparing the lab

The lab has 20 PCs of which 4 or 5 do not work and the others have totally heterogeneous OS.

We have the permission to install the newest Ubuntu Linux on all machines.

Ike following me and helping me with the preparation

He takes over the lab and the course after my departure



First lecture

- Still no micro-controllers available
- Must start with introduction to Linux and C programming
- Lecture start was scheduled at 9:00 GMT but nobody was there
- I was explained that GMT means Ghana Man Time! So the students would start coming in at ~ 9:30 or 10:00
- Difficult for somebody who worked in Switzerland!
- Students had a 1 semester C++ course but were unable to align 20 lines of C++ code



The micro-controllers and sensors

After the first week we still have no lab! With Ike's and my devices we can equip 2 stations.

The physics department has 5 Raspberry Pis but no power supplies for them! We can borrow them but the Physics department wants another course for its students! This doubles my work load.

A CERN friend sends me this advice:

No matter how tremendous an obstruction may appear at a distance, you will find that if you go on in a certain way, it will disappear as you approach it, or that a way over, through, or around it will appear



Oguaa Fetu Afahye



Because of the festival I get kicked out of the guest house and suddenly my room was available

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The miracle

After a week and over a beer

Nii promises 1000 US \$ to start the lab.

The next day the university releases the budget for the lab.

The supplier in China can deliver immediately and 2 weeks later we have the material.



The lab material



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Bring up Raspbian

The operating system distribution is named **Raspbian**, a Debian based Linux distribution for the ARM processor

- The system is distributed in zip format
- Download to the PC and unzip → binary image with 2 partitions
- Copy the image to a micro SD card using Unix *dd*
- Install the micro SD card in the slot on the RPi
- Boot the system
- Upgrade the system to its latest revision with *apt* (Advance Package Tool)
- Run the configurator *raspi-config* to enable drivers for
 - GPIO, I2C, SPI, camera ...
- Create new users for the students
- Create an administrator account
- Configure the network
- Do all this with a monitor, USB keyboard and USB mouse connected



Lab preparations

The local area network is available but there are too few network connections to accommodate the Raspberry Pis.

- The switches are available but new network plugs and cables must be installed.
Done over the weekend in 2 days!
- The Raspberry Pis need fixed IP addresses to be easily accessible from any PC.
- Raspberry Pis are accessible through ssh or through the remote desktop
- We were working on the configuration literally until seconds before it was needed in the course!



Accessing the Raspberry Pi remotely

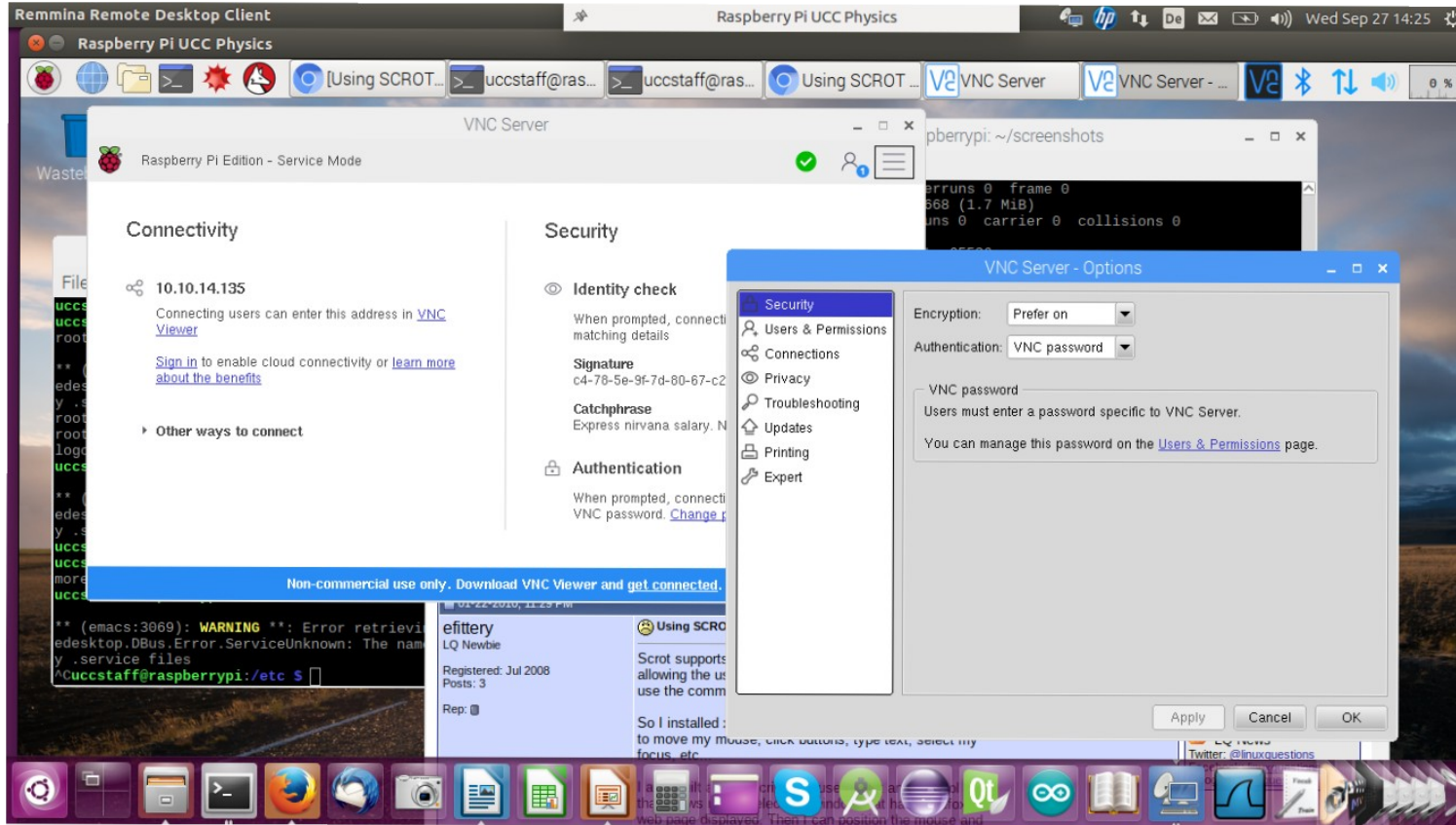
Of course we can access the RPI through its screen, keyboard and mouse but this needs a lot of equipment.

There are several ways to access the RPi remotely:

- Enabling the RPi VNC server and configuring it allows you to access the RPi with a remote desktop client on the PC
- The secure shell ssh allows you to create a remote terminal on the Rpi. With the option ssh -X you enable the X forwarding and you can use the PC as an X-terminal
- With scp you can copy files between PC and RPi
- With NFS you can use part of the PC disk for the RPi.



The remote desktop



An ssh example

```
Terminal
emacs@raspberrypi
File Edit Options Buffers Tools Complete In/Out Signals Help
(edit) Lecture7:AccessingTheRealWorld < UCC_Cours
(edit) Lecture7:Accessing x (edit) Lecture6:BringingT x
https://dcsit.twiki.ucc.edu.gh/do/edit/UCC_Co
Most Visited Download Getting Started Sport
uccstaff@raspberrypi:~$ ls
Desktop Downloads Pictures Templates screenshots
Documents Music Public Videos
uccstaff@raspberrypi:~$
uccstaff@raspberrypi: ~
uli@LaptopUli:~$ ssh -X uccstaff@10.10.14.135
uccstaff@10.10.14.135's password:
Linux raspberrypi 4.9.41-v7+ #1023 SMP Tue Aug 8 16:00:15 BST 2017 armv7l
The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/copyright.
It is inter
which will Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
---++
Last login: Wed Sep 27 13:59:11 2017 from 10.10.14.251
uccstaff@raspberrypi:~$ emacs
(process:3586): Gtk-WARNING **: Locale not supported by C library.
Using the fallback 'C' locale.
Gtk-Message: Failed to load module "canberra-gtk-module"
Gtk-Message: Failed to load module "canberra-gtk-module"
Comm
U: *- *shell* All L4 (Shell:run)
menu-bar buffer C-a
```



First exercise on the RPi

The OS on the RPi looks very similar to Ubuntu on the PC

- The students compile and try their programs on the RPi
- When copying the binary from the PC to the RPi it does not run, why?
- Native vs cross compilations (both are possible on our system)



The “Hello World“ program

Anybody who has learned C will have come across the

“Hello World” program:

```
/*  
 * Hello World! the most simple C program you could possibly write  
 */  
#include <stdio.h>          /* here printf is defined */  
int main() {  
    printf("Hello World!\n");  
}
```

In embedded systems however, this can become quite complex as you may have to configure a UART before being able to send text and you may have to set up a serial terminal emulator before being able to receive it.

The “Hello World” equivalent in embedded systems is the blinking LED



Accessing external hardware

The simplest possible example: blinking a LED

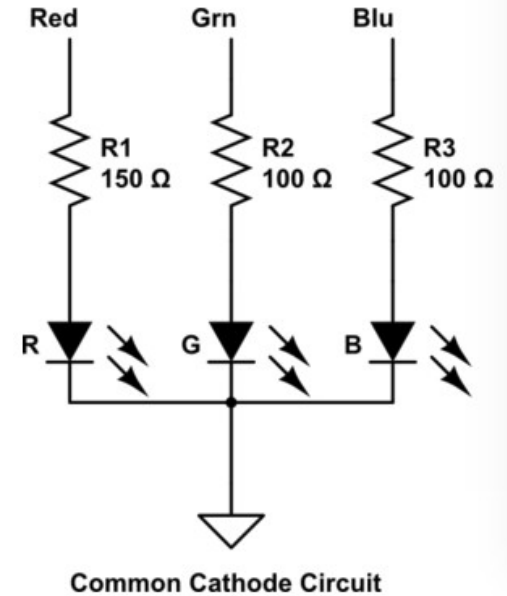
We need to:

- Setup the hardware:
 - Connect the LED cathode to a GPIO pin
 - Connect the anode to ground via a 330 Ω resistor
- Software:
 - Find a hardware access library
 - Program the GPIO pin to be output
 - Write the GPIO pin to switch the LED on
 - Delay the program for 500 ms
 - Write the GPIO pin to switch the LED off



The KY-016 rgb LED

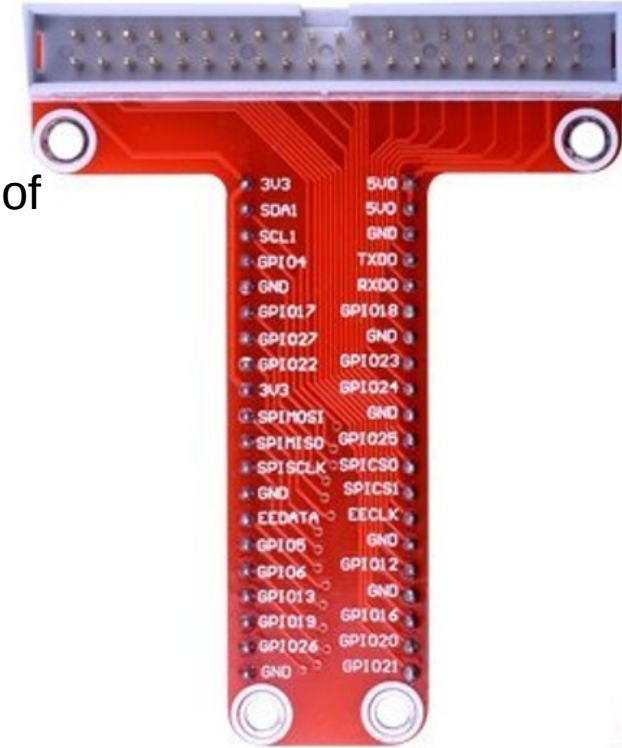
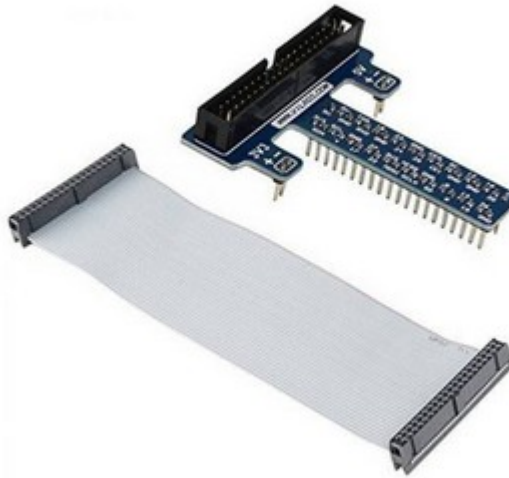
The standard rgb LED on an BY-016 board has the current limiting resistors already on board. The board uses a common cathode circuit, which means that it has a common ground and the rgb signals must be on Vcc to light the LED



The cobbler

How to make the hardware connections?

The cobbler tells us the signification of the pins



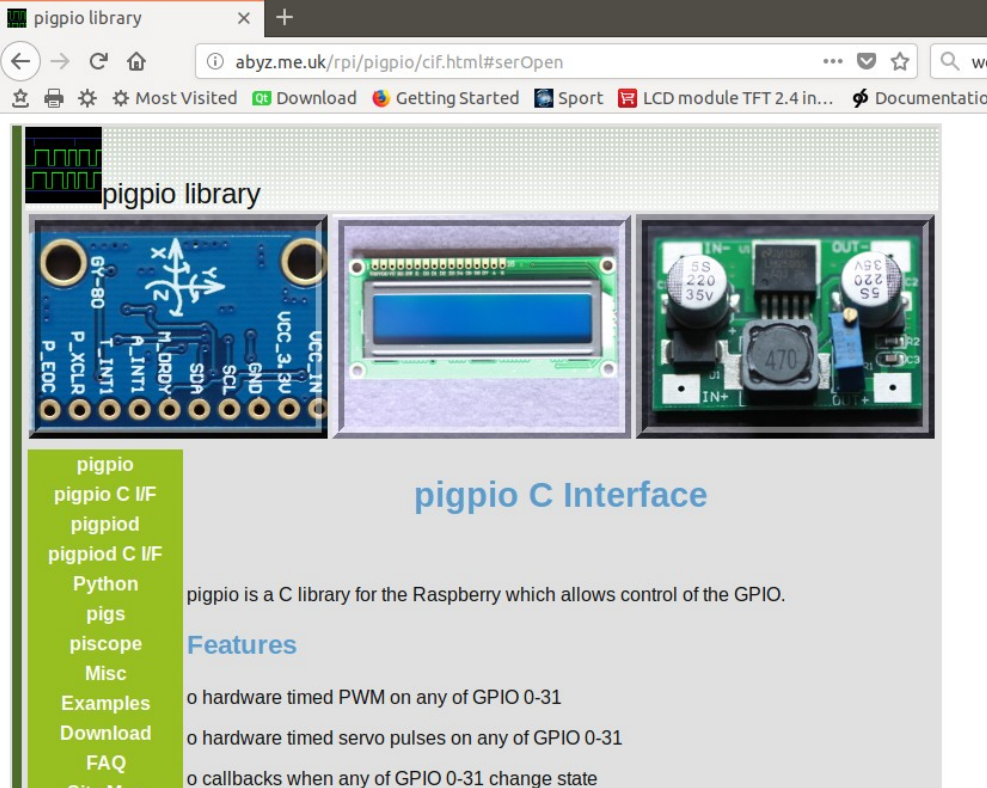
The pigpio library

It is possible to program the GPIO pins accessing the processor registers directly. However this is clumsy and complex.

→ use a library doing the hardware access for us.

pigpio uses a daemon for hardware access. The daemon is started by the super user.

Applications communicate with the daemon through sockets and do not need super user privileges.



The screenshot shows a web browser window with the URL `abyz.me.uk/rpi/pigpio/cif.html#serOpen`. The page title is "pigpio library". Below the title, there are three images: a Raspberry Pi board, a blue LCD screen, and a green PCB with electronic components. A green sidebar on the left contains a list of navigation links: pigpio, pigpio C I/F, pigpiod, pigpiod C I/F, Python, pigo, piscope, Misc, Examples, Download, FAQ, and C++ I/F. The main content area features the heading "pigpio C Interface" and a description: "pigpio is a C library for the Raspberry which allows control of the GPIO." Below this, a "Features" section lists: "o hardware timed PWM on any of GPIO 0-31", "o hardware timed servo pulses on any of GPIO 0-31", and "o callbacks when any of GPIO 0-31 change state".

Using pigpio

Usage

Include `<pigpiod_if2.h>` in your source files.

Assuming your source is in `prog.c` use the following command to build

```
gcc -Wall -pthread -o prog prog.c -lpigpiod_if2 -lrt
```

to run make sure the pigpio daemon is running

```
sudo pigpiod
```

```
./prog # sudo is not required to run programs linked to pigpiod_if2
```



The library calls for GPIO

All the functions which return an int return < 0 on error

OVERVIEW

ESSENTIAL

[pigpio_start](#)

Connects to a pigpio daemon

[pigpio_stop](#)

Disconnects from a pigpio daemon

BEGINNER

[set_mode](#)

Set a GPIO mode

[get_mode](#)

Get a GPIO mode

[set_pull_up_down](#)

Set/clear GPIO pull up/down resistor

[gpio_read](#)

Read a GPIO

[gpio_write](#)

Write a GPIO

blink program

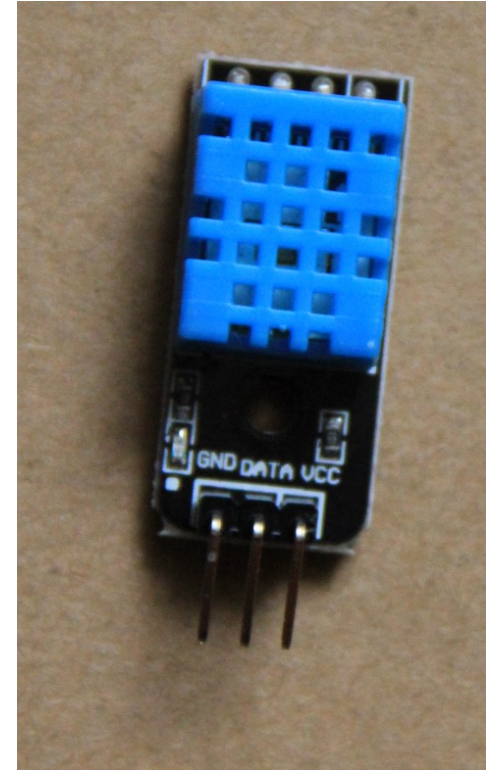


Other GPIO projects

The DHT11 temperature and humidity sensor

The DHT11 has only 3 pins:

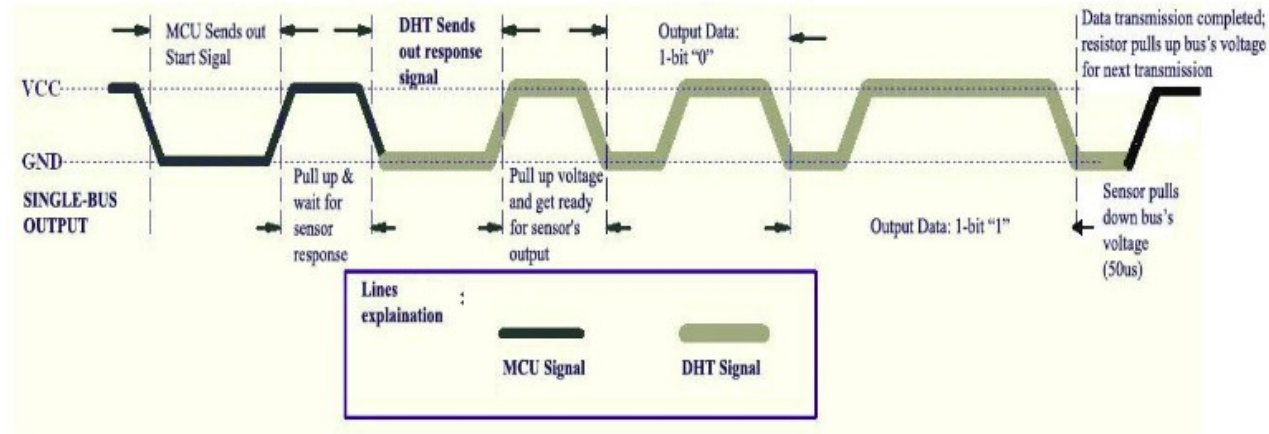
- Vcc
- Ground
- one data pin



Starting a measurement

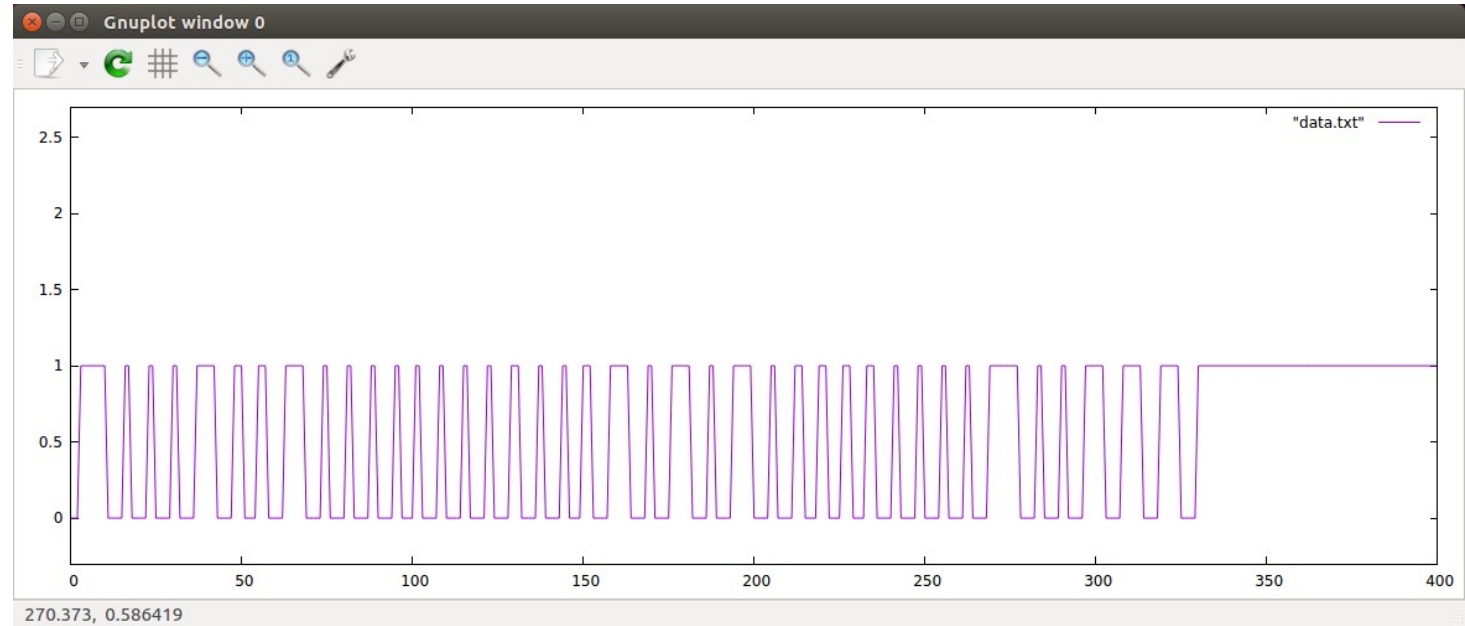
5.1 Overall Communication Process (Figure 2, below)

When MCU sends a start signal, DHT11 changes from the low-power-consumption mode to the running-mode, waiting for MCU completing the start signal. Once it is completed, DHT11 sends a response signal of 40-bit data that include the relative humidity and temperature information to MCU. Users can choose to collect (read) some data. Without the start signal from MCU, DHT11 will not give the response signal to MCU. Once data is collected, DHT11 will change to the low-power-consumption mode until it receives a start signal from MCU again.

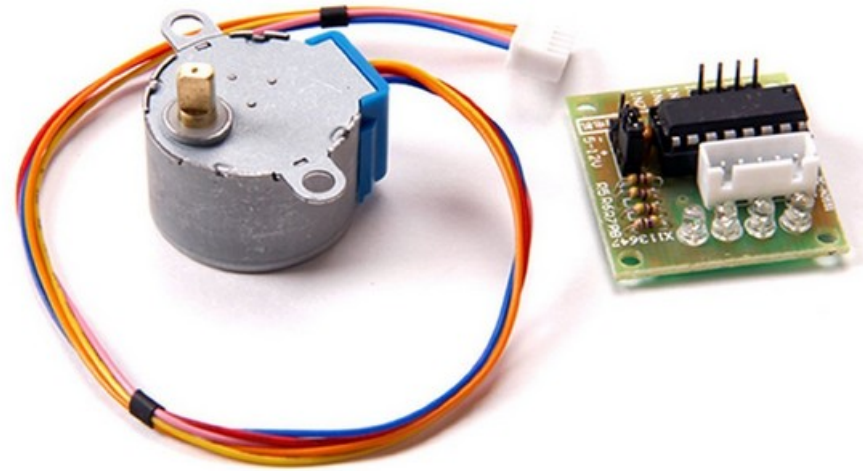
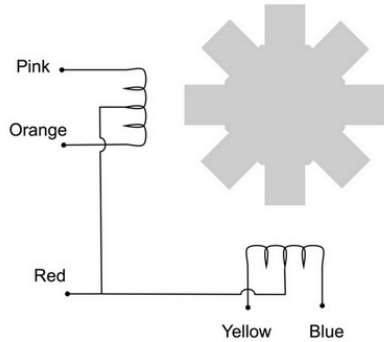


Trigger and Readout

- Program data line to output and send start signal
- Program data line to input and sample data line every $4\ \mu\text{s}$
- Interpret result



Stepping motor



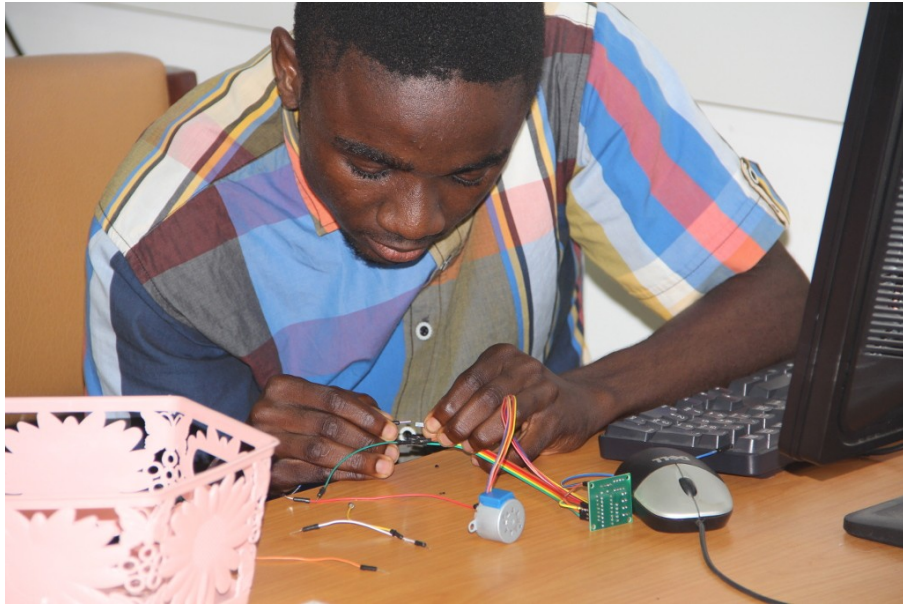
		Step 1	Step 2	Step 3	Step 4
In 1	coil 1 +	1	0	0	0
In 2	Coil 2 -	0	1	0	0
In 3	Coil 1 -	0	0	1	0
In 4	Coil 2 +	0	0	0	1

Here we need 4 GPIO signals which must we switched according to the table in order to move the motor by 4 steps

Single phase forward stepping



Students at work



10. Oct. 2018



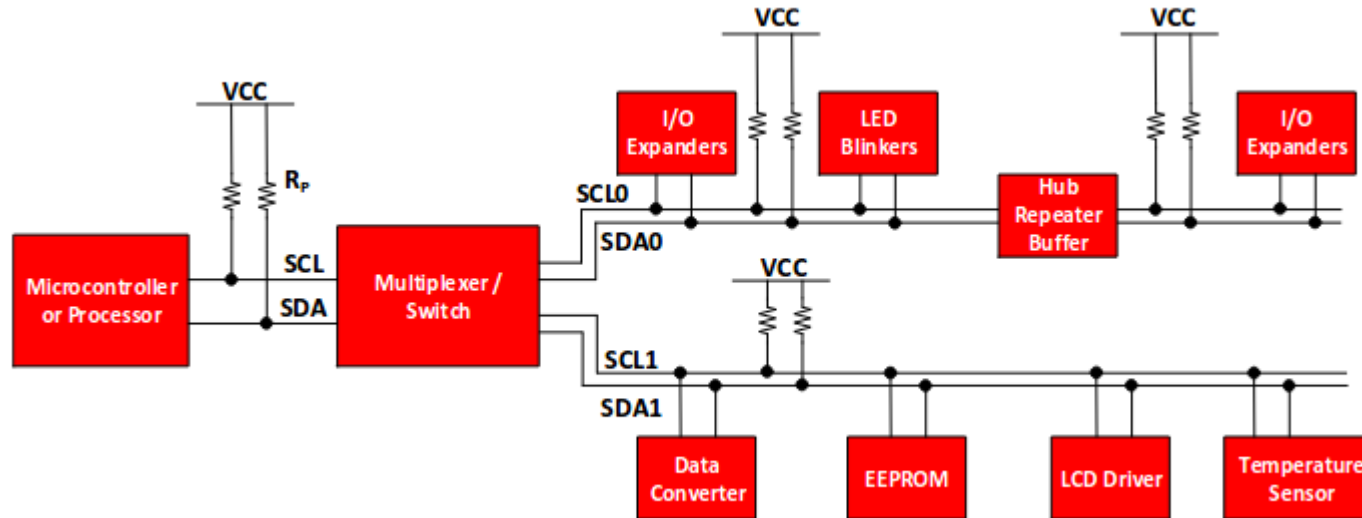
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The I2C bus

A 2 line serial bus

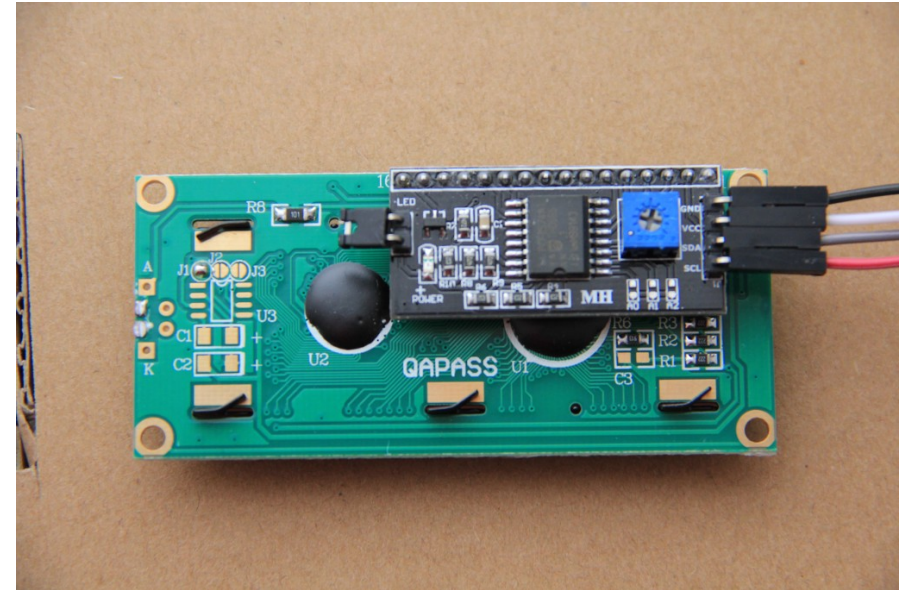
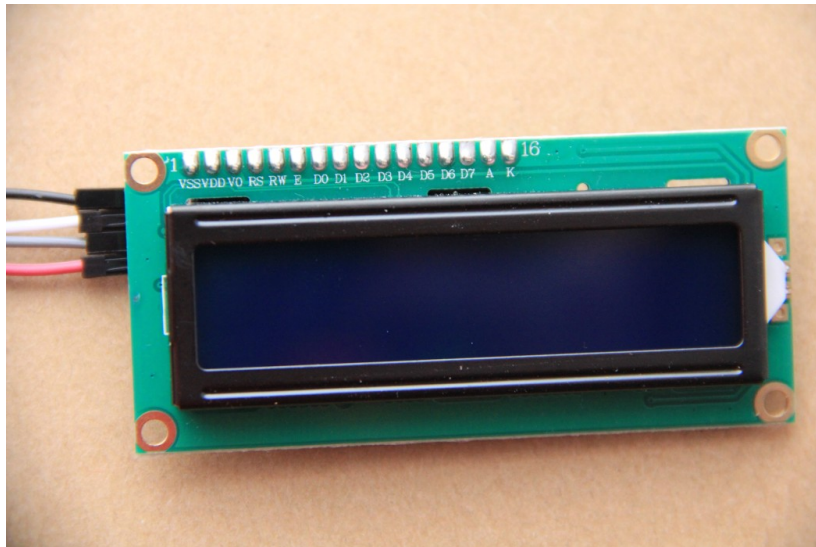
- SDA: data
- SCL: clock

Master sends 7 bit address + R/W followed by data

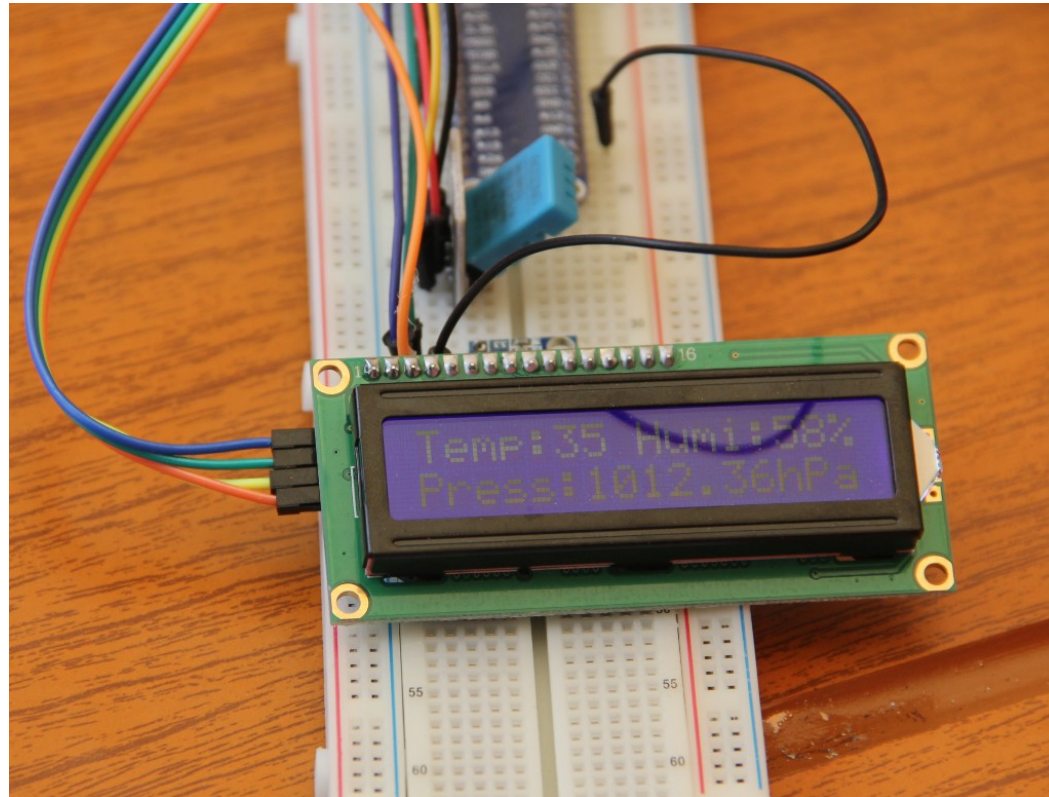


I2C I/O expander

Essentially a shift register allowing to drive a big number of I/O lines with just the 2 I2C signals



A simple weather station



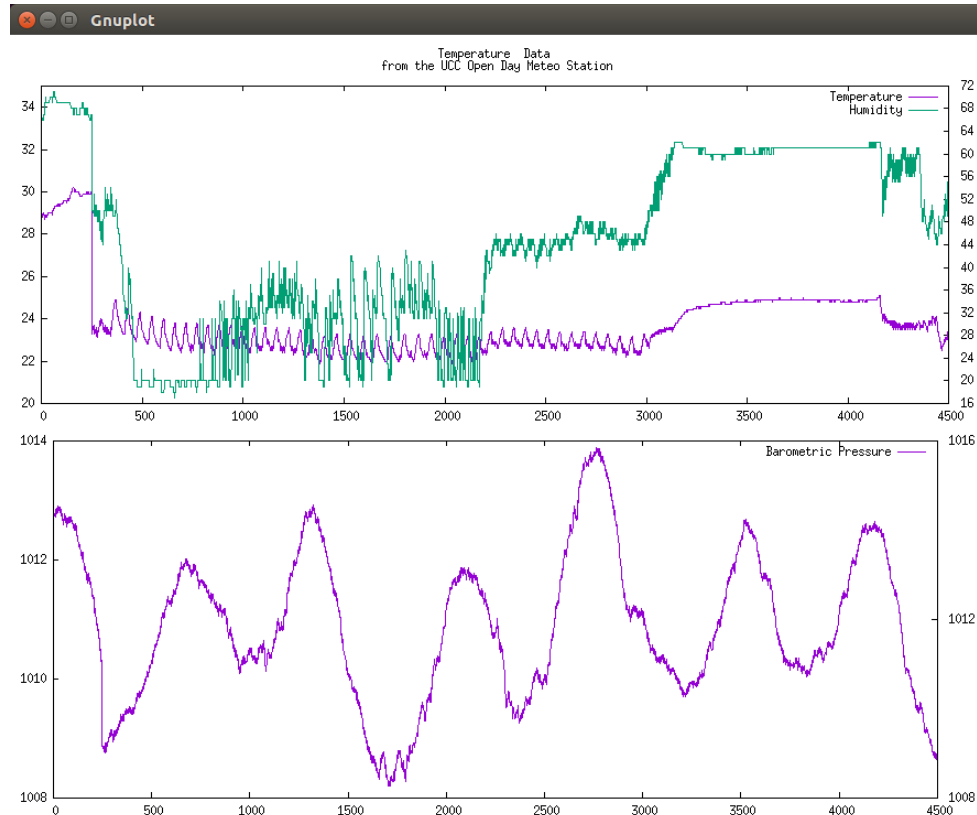
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Results from the weather station



Course exercises on the RPi

- LEDs
 - Blinking, SOS
- Stepping motors (single phase and double phase, half step, forward/backward)
- DHT-11 temperature and humidity measurements
- BMP-180 temperature and barometric pressure measurement
- LCD display driver using an I2C extender
- Digital to analogue converter
 - Create a signal level
 - Create a pulse generator for sine, sawtooth, rectangular and triangular signals
- Analogue to Digital converter: read a potentiometer voltage
- I2C Real time clock
- I2C EEPROM



Course exercises on the RPi

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I2C devices in the lab

- 8 bit Analog to digital converter board with
 - Potentiometer
 - Thermistor
 - Photo resistor
 - 1 digital to Analogue channel
- Digital to analogue converter
 - Created a pulse generator
- Real time clock
- EEPROM
 - Programmed some ASCII text and asked the students to find it
- LCD controller interface
- Barometric pressure and temperature sensor



Summary

- After initial difficulties the course went well
- I left a fully functional laboratory for 15 students
- The course was repeated by Ike in 2018 but without any updates
- Passing on experience to the other lecturers did **not** work
We had lecturer sessions but only a few lecturers came and those came only sporadically
- Ike had the intention to port the whole course to the Python language and during the last 2 weeks I started with that (having no clue about Python programming!) After my own work there was no more progress.
- We wanted to promote the course for other African universities, also without success up to now



The UCC Open Day

The university organizes an Open Day where the students show off [projects](#) prepared in the department

The department head asks me to prepare a few presentations

We have:

- A traffic light simulator using LEDs
- Name display: A visitor types his name which is then displayed in a welcome message on an LCD screen attached to the Rpi.
- A stepping motor control program
- A voltmeter
- A small meteorological station measuring
 - Temperature· air pressure, humidity
- A simple obstacle avoiding robot



Photo from the Open Day



10. Oct. 2018



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Physics and Applications

The robot

A simple robot:

2 active wheels with DC motors

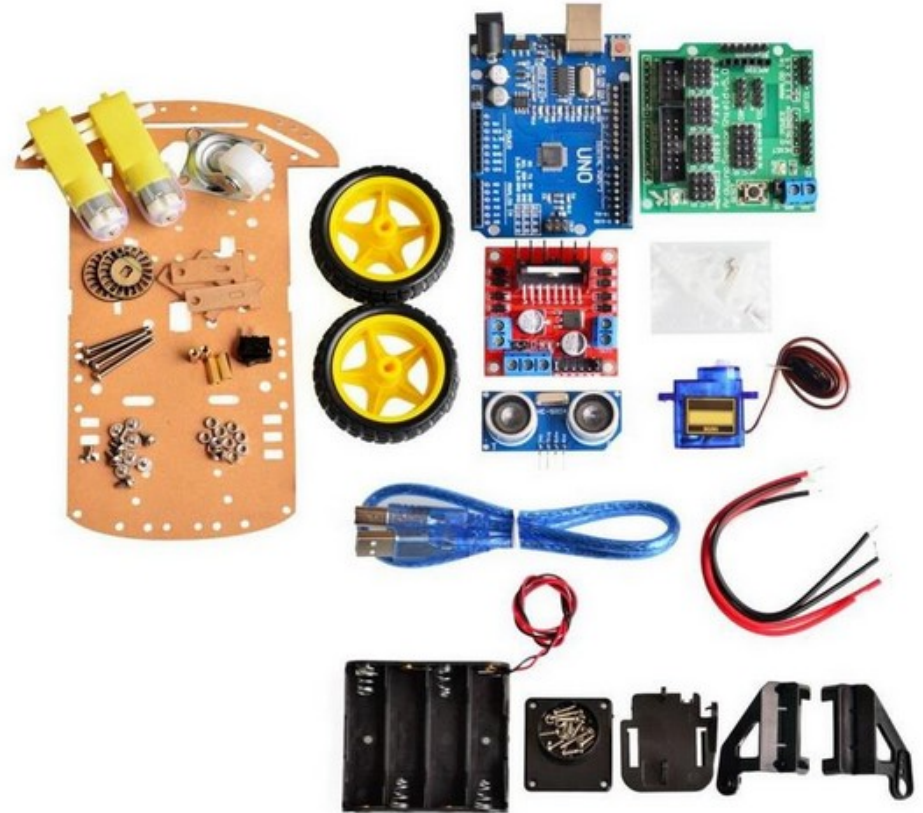
1 passive wheel

Ultra-sonic distance sensor mounted on a

Servo motor

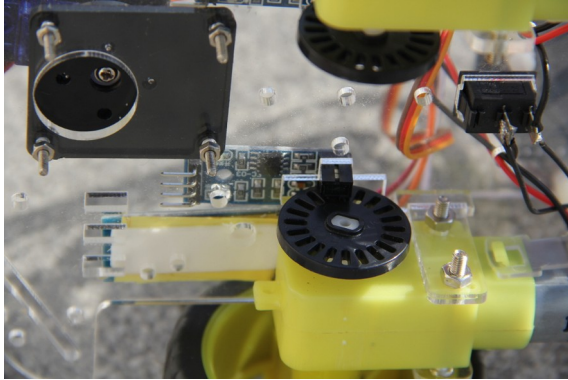
Arduino Uno controller

Total cost: < 20 Euros

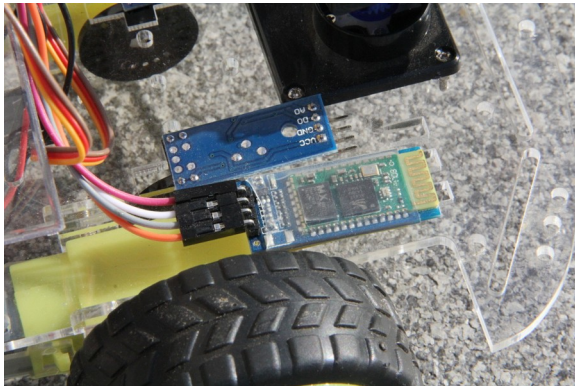


Robot Details

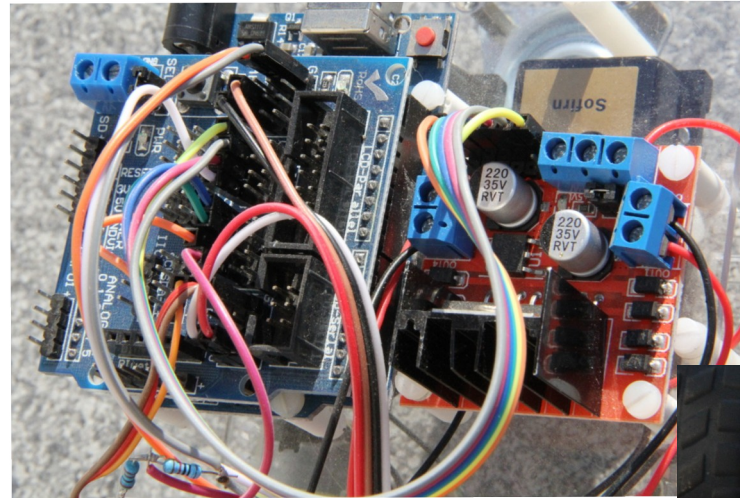
Encoder



BlueTooth transceiver



10. Oct. 2018



Arduino controller
and DC motor
driver

Ultra-sonic
distance sensor
on servo motor

