

Understand and Improving Higgs Measurements using Information Geometry

Felix Kling



19 June 2020
Joint INFN-UNIMI-UNIMIB Pheno Seminars

Motivation

Status of the Field:

- Higgs discovery: Standard Model complete
- no discovery of new physics yet

- maybe BSM physics will be obvious (di-X resonance at XXX GeV)
- maybe BSM physics is more subtle (Higgs couplings in dim6 SMEFT)



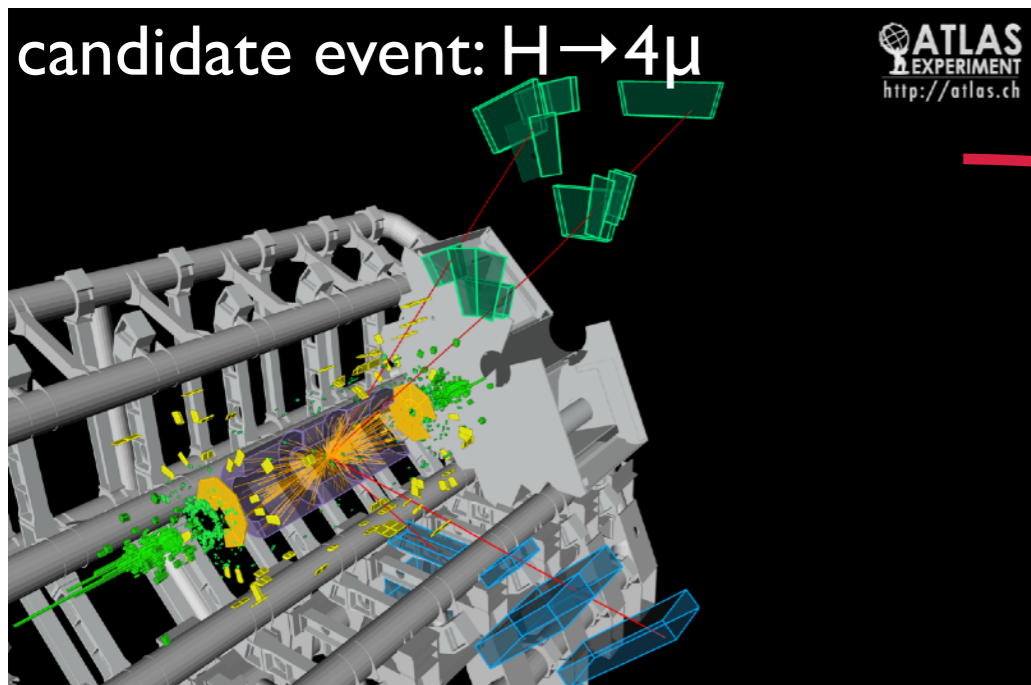
Motivation

Status of the Field:

- Higgs discovery: Standard Model complete
- no discovery of new physics yet
- maybe BSM physics will be obvious (di-X resonance at XXX GeV)
- maybe BSM physics is more subtle (Higgs couplings in dim6 SMEFT)

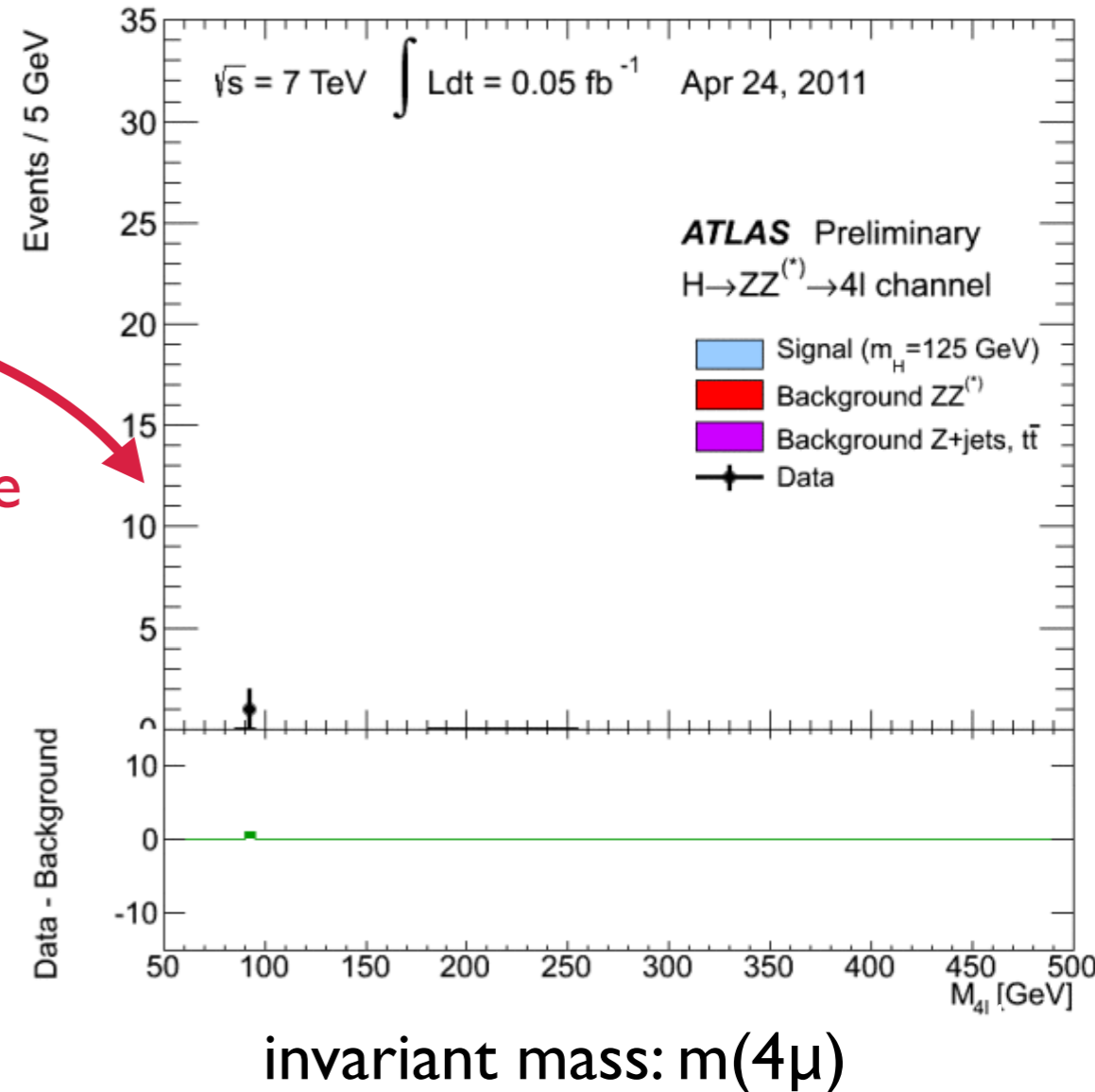


2012: discovery of the Higgs boson



collect many events

plot carefully chosen variable



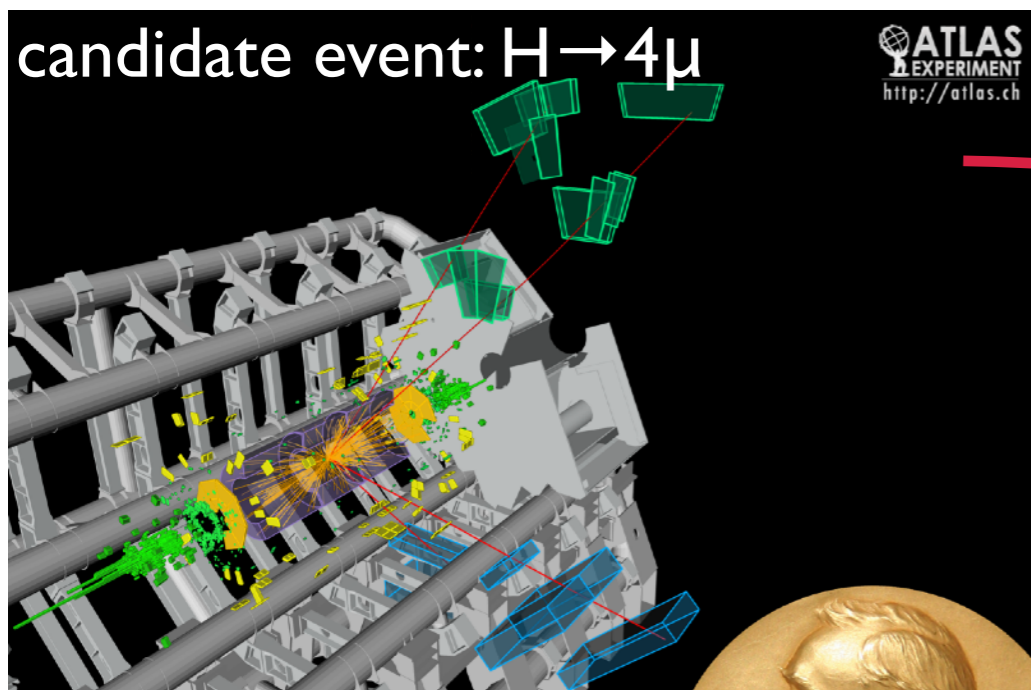
Motivation

Status of the Field:

- Higgs discovery: Standard Model complete
- no discovery of new physics yet
- maybe BSM physics will be obvious (di-X resonance at XXX GeV)
- maybe BSM physics is more subtle (Higgs couplings in dim6 SMEFT)



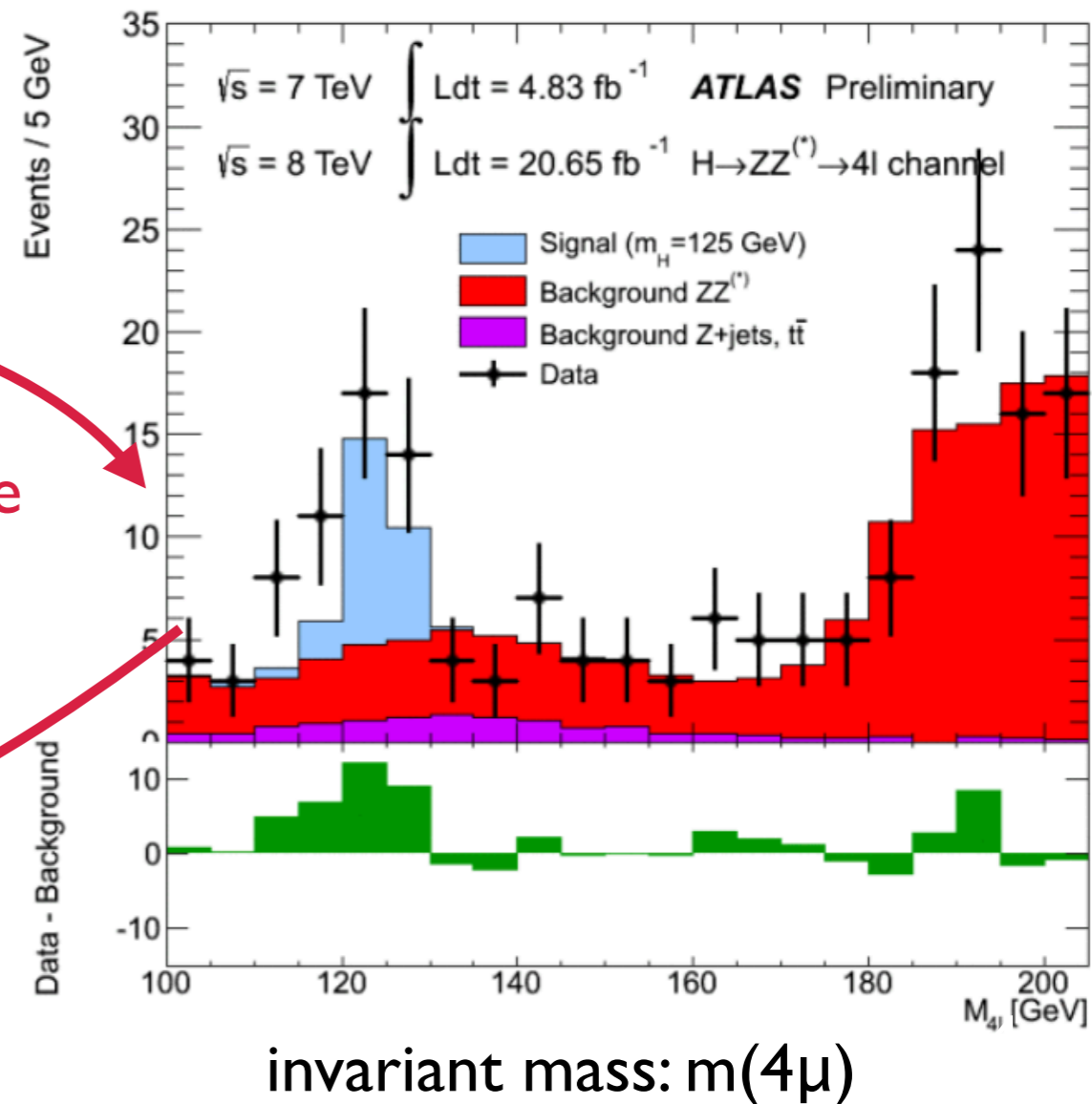
2012: discovery of the Higgs boson



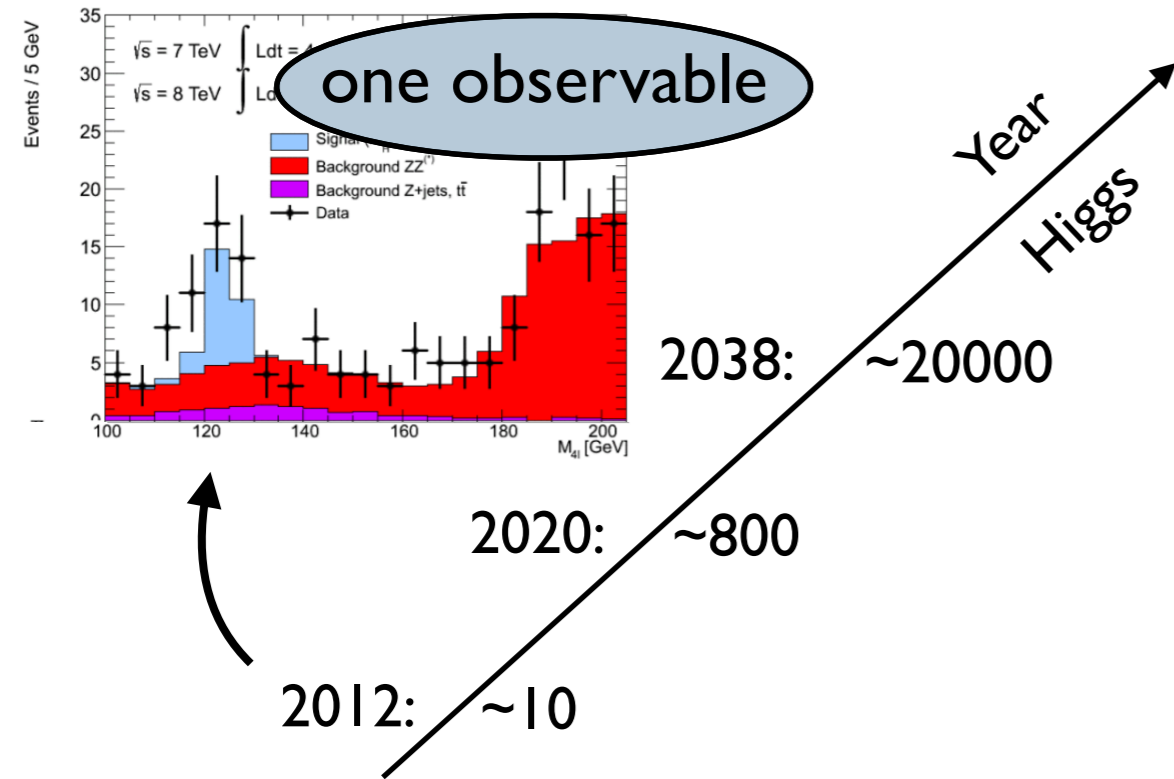
collect many events

plot carefully chosen variable

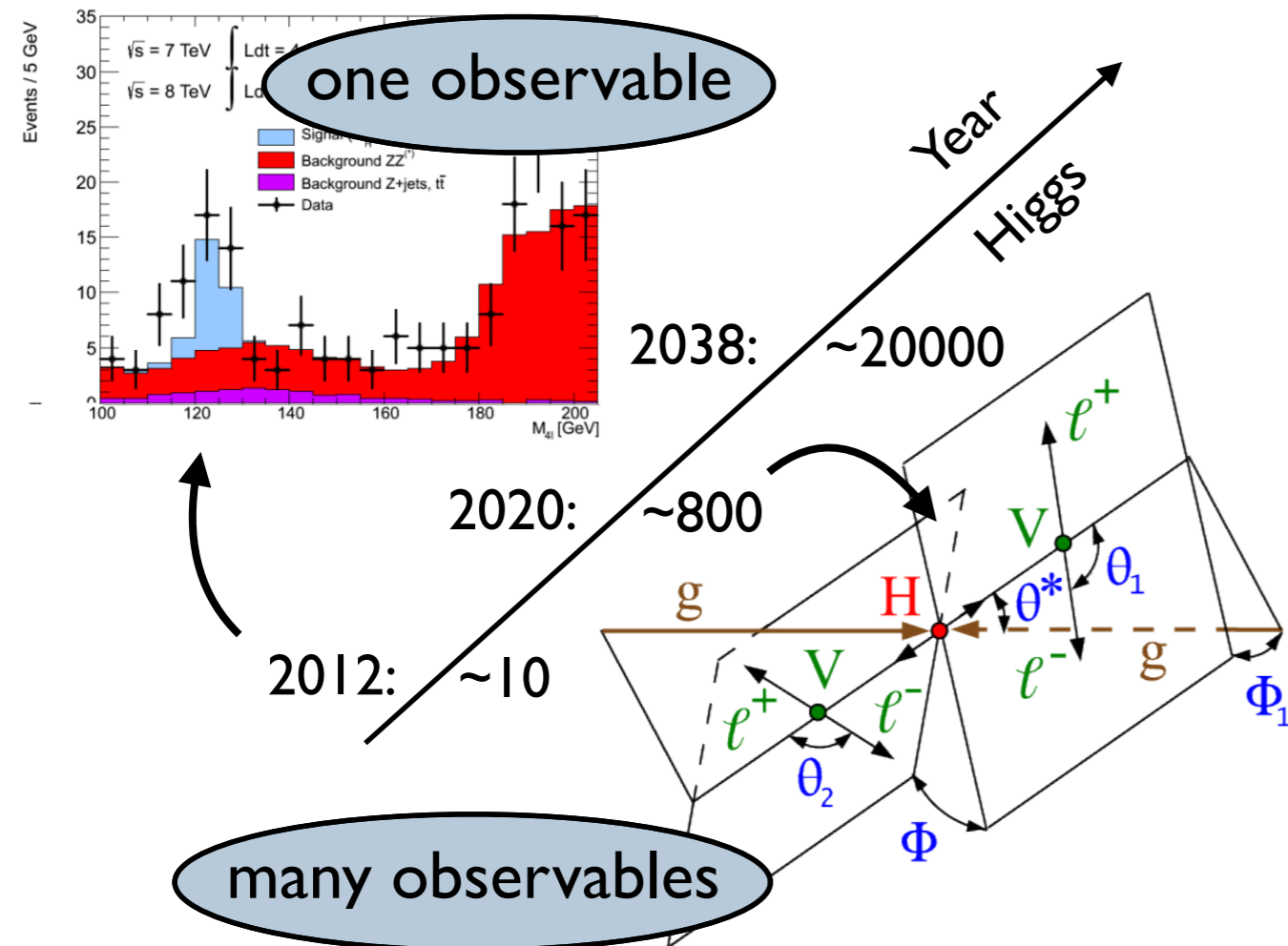
discovery



Theory in an Era of Data



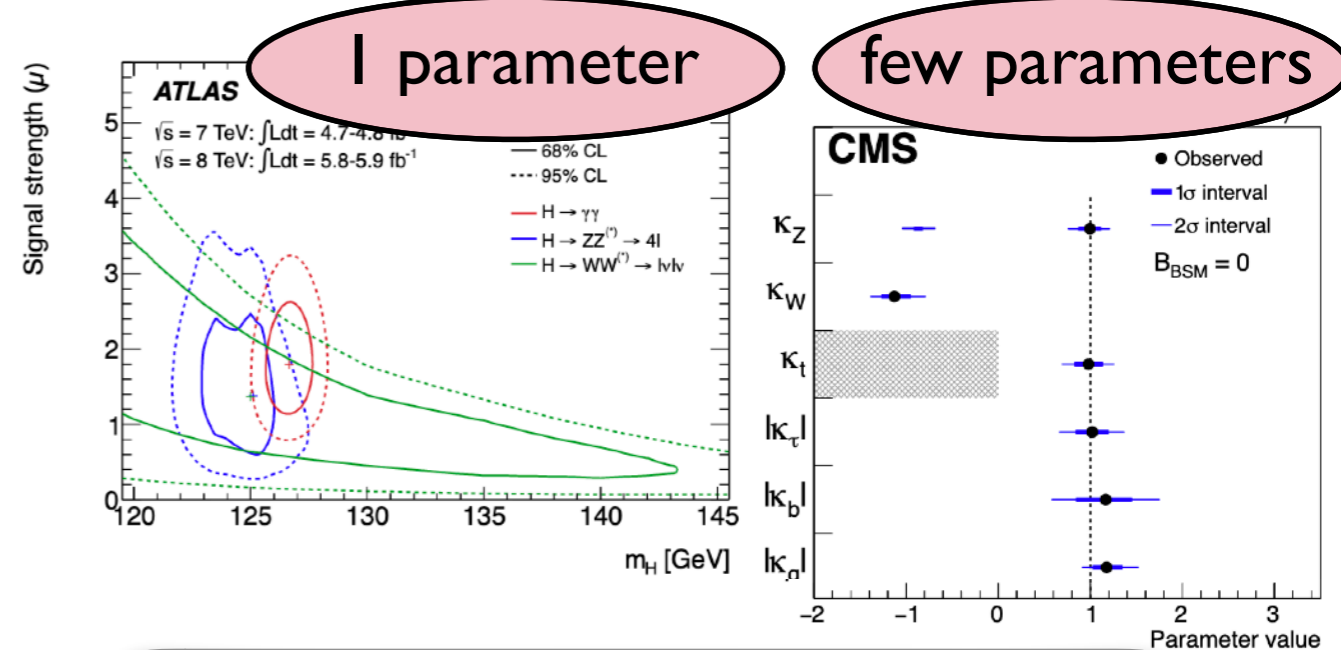
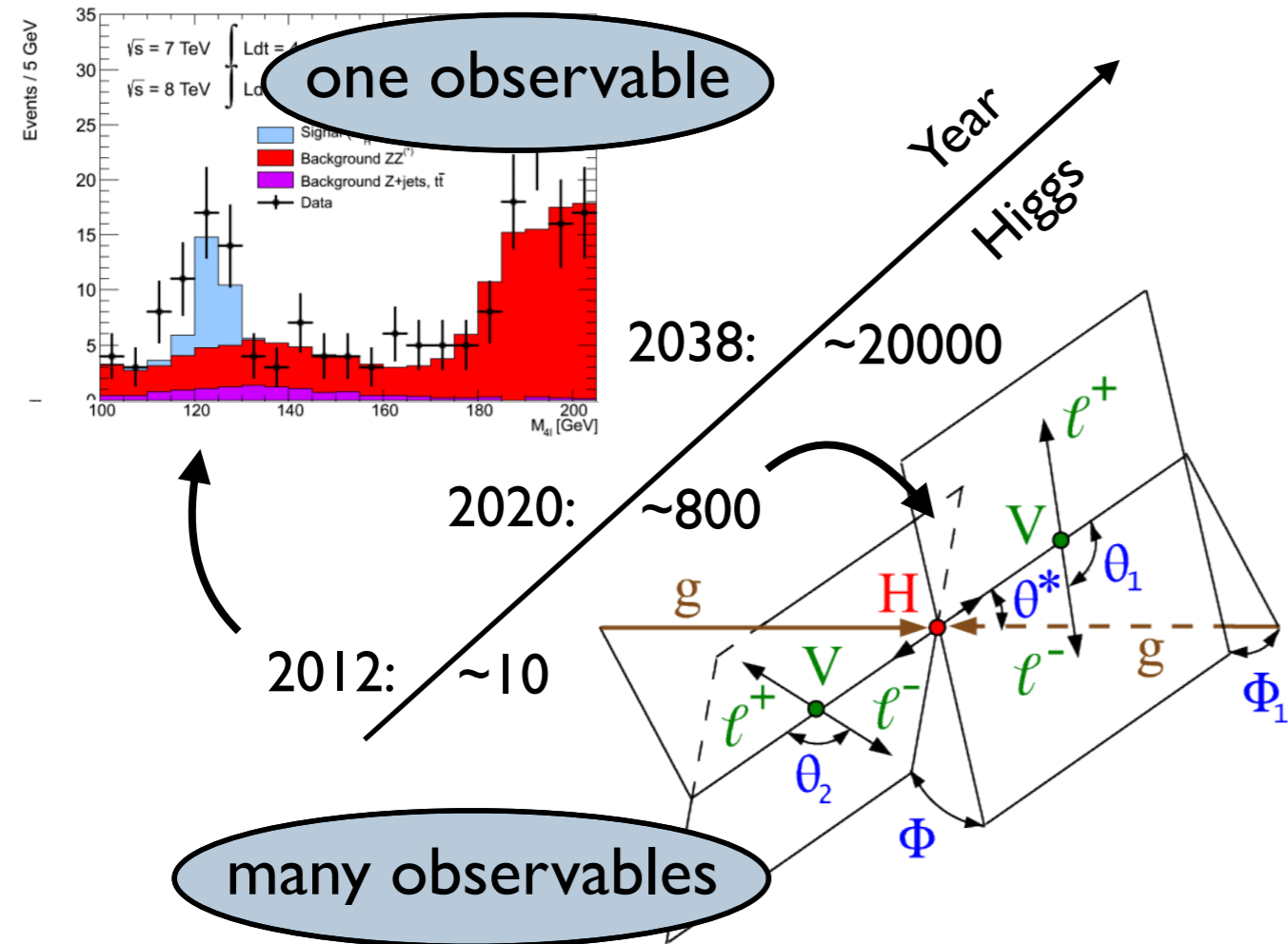
Theory in an Era of Data



Era of Data

large statistics
many observables

Theory in an Era of Data



$$\Delta\mathcal{L}_{SILH} = \frac{\bar{c}_H}{2v^2} \partial^\mu (H^\dagger H) \partial_\mu (H^\dagger H) + \frac{\bar{c}_T}{2v^2} (H^\dagger \overleftrightarrow{D}^\mu H) (H^\dagger \overleftrightarrow{D}_\mu H) - \frac{\bar{c}_6 \lambda}{v^2} (H^\dagger H)^3$$

$$+ \left(\left(\frac{\bar{c}_u}{v^2} y_u H^\dagger H \bar{q}_L H^c u_R + \frac{\bar{c}_d}{v^2} y_d H^\dagger H \bar{q}_L H d_R + \frac{\bar{c}_l}{v^2} y_l H^\dagger H \bar{L}_L H l_R \right) + \text{h.c.} \right)$$

$$+ \frac{i\bar{c}_W g}{2m_W^2} (H^\dagger \sigma^i \overleftrightarrow{D}^\mu H) (D^\nu W_{\mu\nu})^i + \frac{i\bar{c}_B g'}{2m_W^2} (H^\dagger \overleftrightarrow{D}^\mu H) (\partial^\nu B_{\mu\nu})$$

$$+ \frac{i\bar{c}_{HW} g}{m_W^2} (D^\mu H)^\dagger \sigma^i (D^\nu H) W_{\mu\nu}^i + \frac{i\bar{c}_{HB} g'}{m_W^2} (D^\mu H)^\dagger (D^\nu H) B_{\mu\nu}$$

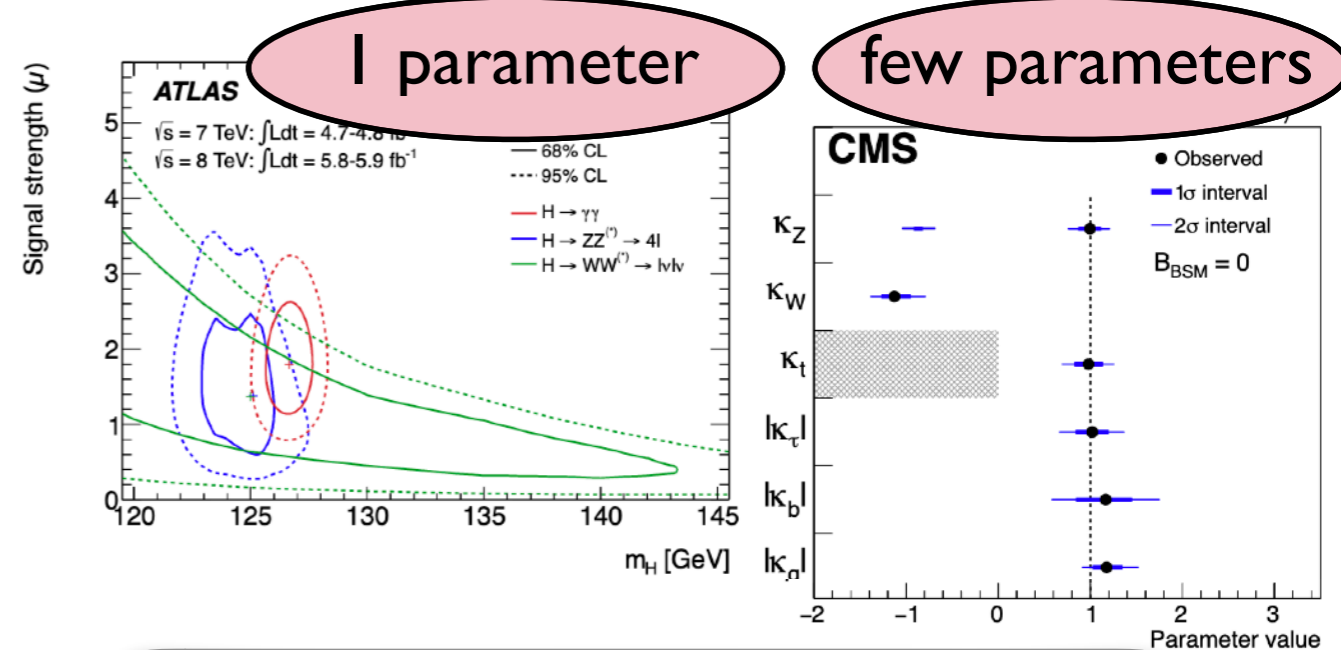
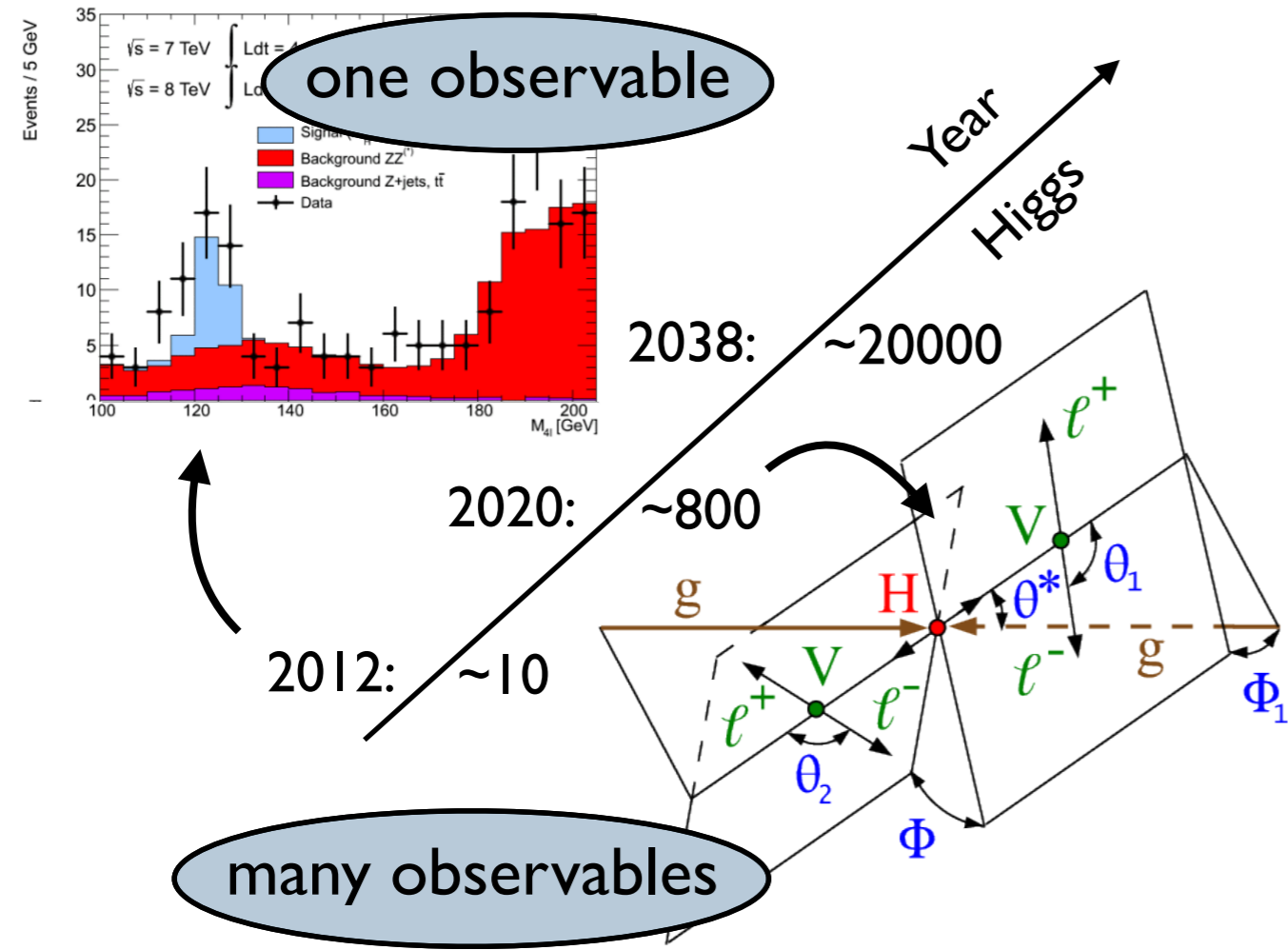
$$+ \frac{\bar{c}_\gamma g'^2}{m_W^2} H^\dagger H B_{\mu\nu} B^{\mu\nu} + \frac{\bar{c}_g g_S^2}{m_W^2} H^\dagger H G_{\mu\nu}^a G^{a\mu\nu}$$

many parameters

Era of Data
 large statistics
 many observables

Complex Theories
 e.g. SM effective field theory
 predict subtle kinematic features

Theory in an Era of Data



$$\Delta\mathcal{L}_{\text{SILH}} = \frac{\bar{c}_H}{2v^2} \partial^\mu (H^\dagger H) \partial_\mu (H^\dagger H) + \frac{\bar{c}_T}{2v^2} (H^\dagger \overleftrightarrow{D}^\mu H) (H^\dagger \overleftrightarrow{D}_\mu H) - \frac{\bar{c}_6 \lambda}{v^2} (H^\dagger H)^3$$

$$+ \left(\left(\frac{\bar{c}_u}{v^2} y_u H^\dagger H \bar{q}_L H^c u_R + \frac{\bar{c}_d}{v^2} y_d H^\dagger H \bar{q}_L H d_R + \frac{\bar{c}_l}{v^2} y_l H^\dagger H \bar{L}_L H l_R \right) + \text{h.c.} \right)$$

$$+ \frac{i\bar{c}_W g}{2m_W^2} (H^\dagger \sigma^i \overleftrightarrow{D}^\mu H) (D^\nu W_{\mu\nu})^i + \frac{i\bar{c}_B g'}{2m_W^2} (H^\dagger \overleftrightarrow{D}^\mu H) (\partial^\nu B_{\mu\nu})$$

$$+ \frac{i\bar{c}_{HW} g}{m_W^2} (D^\mu H)^\dagger \sigma^i (D^\nu H) W_{\mu\nu}^i + \frac{i\bar{c}_{HB} g'}{m_W^2} (D^\mu H)^\dagger (D^\nu H) B_{\mu\nu}$$

$$+ \frac{\bar{c}_\gamma g'^2}{m_W^2} H^\dagger H B_{\mu\nu} B^{\mu\nu} + \frac{\bar{c}_g g_S^2}{m_W^2} H^\dagger H G_{\mu\nu}^a G^{a\mu\nu}$$

many parameters

Era of Data
 large statistics
 many observables

Complex Theories
 e.g. SM effective field theory
 predict subtle kinematic features

How can we extract all the information from the data?

Outline

Some Statistic Concepts

Likelihoods, Optimal Observables and Fisher Information

Information Geometry in Theory

Parton Level and Matrix Elements

Information Geometry in Reality

Detector Effects and Machine Learning

Summary and Conclusion

Outline

Some Statistic Concepts

Likelihoods, Optimal Observables and Fisher Information

Information Geometry in Theory

Parton Level and Matrix Elements

Information Geometry in Reality

Detector Effects and Machine Learning

Summary and Conclusion

Likelihood Function

Simulation and Measurements



Likelihood Function $p(x|\theta)$

likelihood of an observation x as a function of the theory parameter θ

$$p_{\text{full}}(\{x\}|\theta) = \text{Pois}(n|L\sigma(\theta)) \times \prod_{i=1}^n p(x_i|\theta)$$

Likelihood Ratio $r(x|\theta_{\text{ref}},\theta)=p(x|\theta)/p(x|\theta_{\text{ref}})$

“how much more likely is data x described by theory θ than θ_{ref} ”

Neyman-Pearson Lemma:

The log-likelihood ratio $\log r(x|\theta_{\text{ref}},\theta)$ is the most powerful test statistic to discriminate between two hypotheses θ_{ref} and θ .

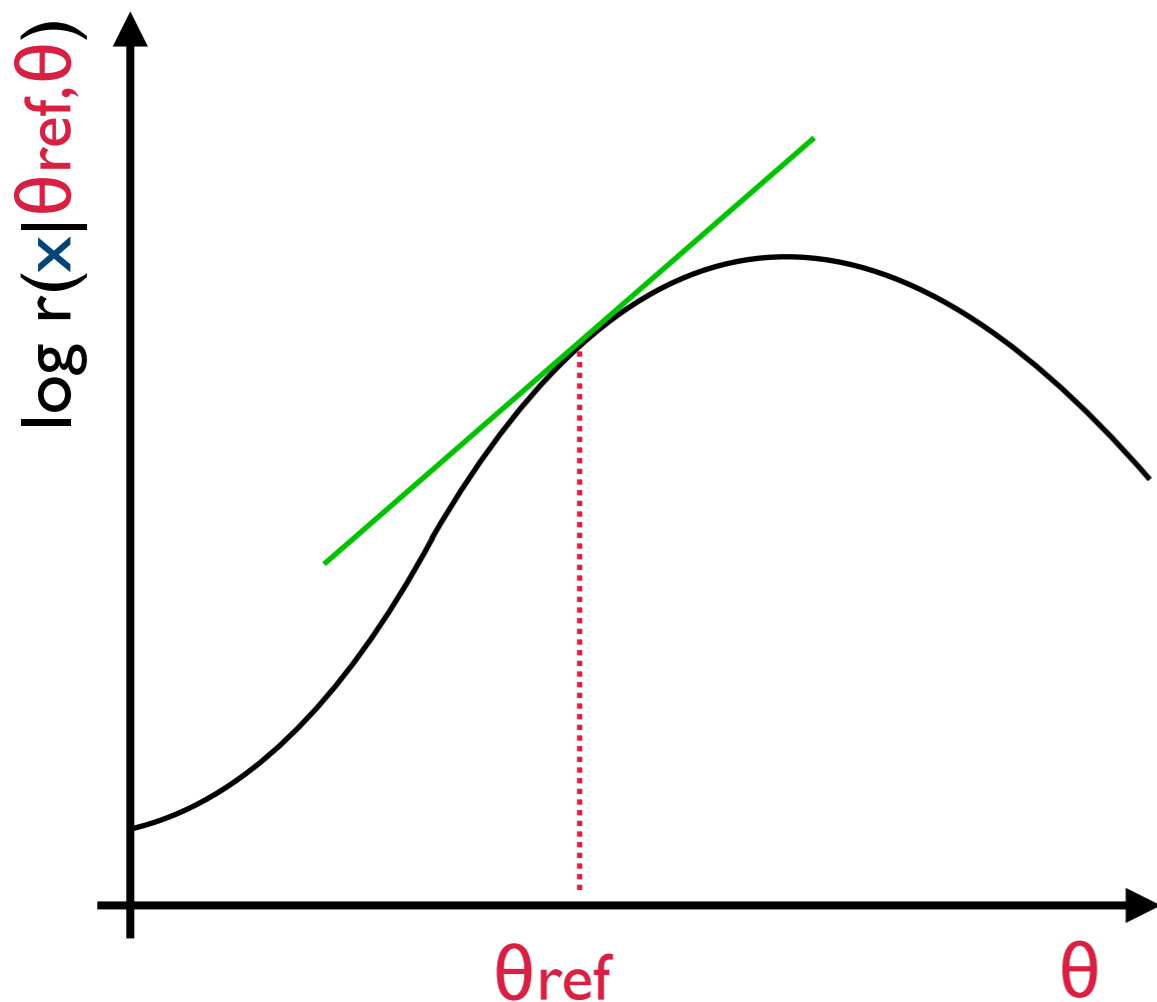
Optimal Observables

Score: $t(\mathbf{x}|\theta) = d \log p(\mathbf{x}|\theta) / d\theta$

How much does the data \mathbf{x} change, when I change my theory θ

Scores as Optimal Observables

- expand LLR around θ_{ref} : $\log r(\mathbf{x}|\theta) = \log r(\mathbf{x}|\theta_{\text{ref}}) + t(\mathbf{x})|_{\theta_{\text{ref}}} \cdot (\theta - \theta_{\text{ref}}) + \dots$



- close to θ_{ref}
 - * score is sufficient statistics
 - * knowing $t(\mathbf{x})|_{\theta_{\text{ref}}}$ is as powerful as knowing $r(\mathbf{x}|\theta)$
 - * $t(\mathbf{x})|_{\theta_{\text{ref}}}$ are optimal observables
- in SMEFT: $t(\mathbf{x})|_{\text{SM}}$ is sensitive to interference

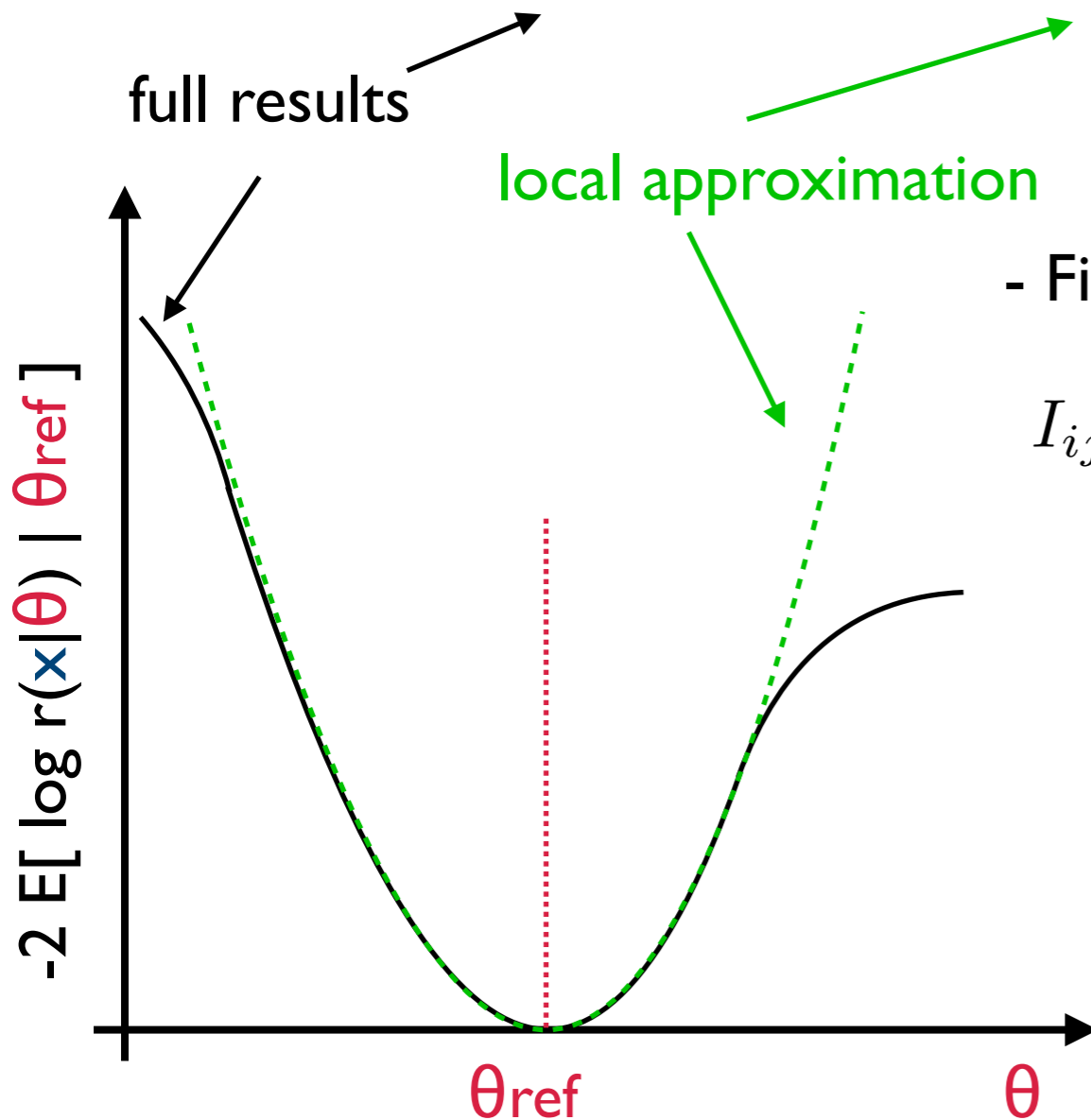
Fisher Information

[F. Edgeworth 1908; R. Fisher 1925; ...]

Fisher Information

- expand expected LLR around θ_{ref} :

$$\mathbb{E}[-2 \log r_{\text{full}}(x|\theta)|\theta_{\text{ref}}] = I_{ij}(\theta_{\text{ref}}) \times (\theta - \theta_{\text{ref}})_i (\theta - \theta_{\text{ref}})_j + \dots$$



- Fisher Information

$$I_{ij}(\theta_{\text{ref}}) = \mathbb{E} \left[\frac{\partial \log p_{\text{full}}(x|\theta)}{\partial \theta_i} \frac{\partial \log p_{\text{full}}(x|\theta)}{\partial \theta_j} \Big| \theta_{\text{ref}} \right]$$

$$= \mathcal{L} \frac{\partial_i \sigma(\theta) \partial_j \sigma(\theta)}{\sigma(\theta)} + \frac{\mathcal{L} \sigma(\theta)}{n} \sum_{x \sim p(x|\theta_{\text{ref}})} t_i(x) t_j(x)$$

↑
scores

Fisher Information

[C. R. Rao 1945; H. Cramér 1946]

Cramer Rao Bound

The possible precision of a measurement is bounded from below by the inverse of the Fisher Information

$$\text{cov}[\hat{\theta}|\theta_0] \geq I_{ij}^{-1}(\theta_0)$$

*The Fisher information encodes the maximum sensitivity of **observables** to **theory parameters** for a given experiment*

Other useful properties of the Fisher Information

- * simple: $n \times n$ matrix (for n theory parameters)
- * independent of parameterizations of x
- * covariant under $\theta \rightarrow \theta'$
- * additive between experiments / phase-space
- * easy to include systematics
- * defines metric on theory parameter space

See [J. Brehmer, K. Cranmer, FK, T. Plehn 1612.05261]

Outline

Some Statistic Concepts

Likelihoods, Optimal Observables and Fisher Information

Information Geometry in Theory

Parton Level and Matrix Elements

Information Geometry in Reality

Detector Effects and Machine Learning

Summary and Conclusion

Fisher Information at Parton Level

Likelihood Function

- at parton level, we can simply calculate the likelihood function using matrix elements
 - * $p(\mathbf{x}|\theta) \sim |\mathcal{M}(\mathbf{x}|\theta)|^2 \times \text{phase space factor}$
 - * $r(\mathbf{x}|\theta_{\text{ref}},\theta) \sim |\mathcal{M}(\mathbf{x}|\theta)|^2 / |\mathcal{M}(\mathbf{x}|\theta_{\text{ref}})|^2$
- MC generators generate a set of events with momenta \mathbf{x} with weights $\Delta\sigma(\mathbf{x}|\theta)$
 - * $p(\mathbf{x}|\theta) = \Delta\sigma(\mathbf{x}|\theta) / \sigma(\theta)$
 - * $r(\mathbf{x}|\theta_{\text{ref}},\theta) = \Delta\sigma(\mathbf{x}|\theta) / \Delta\sigma(\mathbf{x}|\theta_{\text{ref}})$

EFTs and Morphing

- EFT Lagrangian: $L = L_{\text{SM}} + \sum (f_i/\Lambda^2) \times \mathcal{O}_i$
- the matrix element is a quadratic function of the Wilson coefficients:
 - * $\Delta\sigma(\mathbf{x}|\theta) = \Delta\sigma_{\text{SM}}(\mathbf{x}) + \theta \Delta\sigma_{\text{dim6}}(\mathbf{x}) + \theta^2 \Delta\sigma_{\text{dim8}}(\mathbf{x})$
- morphing: evaluate $\Delta\sigma(\mathbf{x}|\theta)$ for 3 different θ to obtain quadratic function
 - * use reweighing: $\Delta\sigma(\mathbf{x}|\theta) = \Delta\sigma(\mathbf{x}|\theta_{\text{ref}}) * |\mathcal{M}(\mathbf{x}|\theta)|^2 / |\mathcal{M}(\mathbf{x}|\theta_{\text{ref}})|^2$

Fisher Information

- can be easily calculated using MC:

$$I_{ij}(\theta) = \sum_{\text{events}} I_{ij}(x|\theta) = \mathcal{L} \sum_{\text{events}} \frac{1}{\Delta\sigma(x|\theta)} \frac{\partial\Delta\sigma(x|\theta)}{\partial\theta_i} \frac{\partial\Delta\sigma(x|\theta)}{\partial\theta_j}$$

- possible to include efficiencies, backgrounds with same final state, mass smearing

See [J. Brehmer, K. Cranmer, FK, T. Plehn |1612.05261]

Physics Example

Which observables are sensitive Higgs CP?

Higgs-Gauge Coupling

- WBF and ZH production, H>4l decay
- same hard process
- different final state (charge measurement)

Theory Language:

- dim-6-operators of **SMEFT**:
- operators such as $L = L_{\text{SM}} + \sum (f_i/\Lambda^2) \times \mathcal{O}_i$
- CP-even: $\mathcal{O}_{WW} \sim (\phi^\dagger \phi) W_{\mu\nu} W^{\mu\nu}$
- CP-odd: $\mathcal{O}_{W\tilde{W}} \sim (\phi^\dagger \phi) W_{\mu\nu} \tilde{W}^{\mu\nu}$
- goal: measure Wilson coefficients: $\theta = f_i$

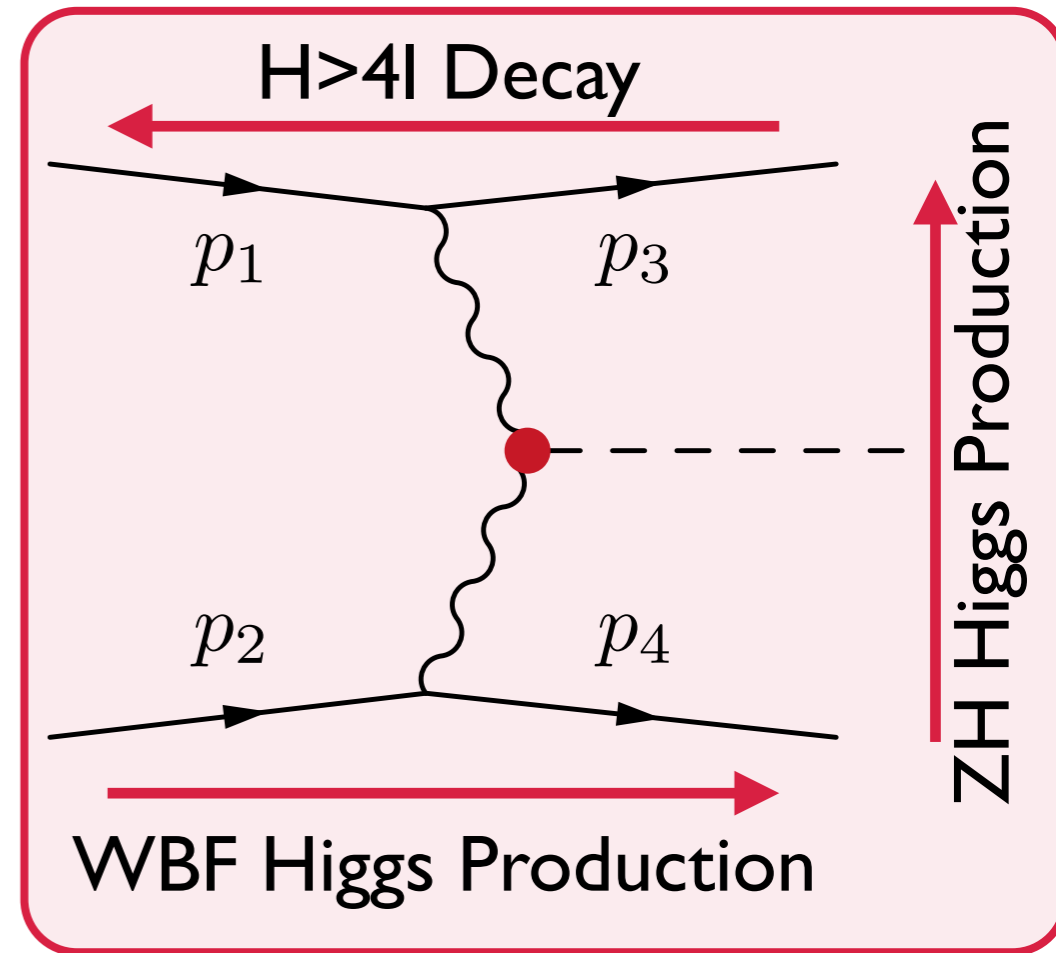
Observables: 4 independent 4-momenta

4 C-even and P-even scalar products

2 C-odd and P-even scalar products: p_i

1 C-even and P-odd $\epsilon_{\alpha\beta\gamma\delta} p_1^\alpha p_2^\beta p_3^\gamma p_4^\delta$

up to 3 CP sensitive observables



WBF	ZH	H>4l
	$\Delta p_{T, ll}, \Delta E_{ll}$	$\theta_{1,2}$
$\Delta \phi_{jj}^s$	$\Delta \phi_{ll}^s$	Φ

[WBF: Hankele, Klamke, Zeppenfeld hep-ph/0609075,
ZH: Christensen, Han, Li 1005.5393,
H>4l: Bolognesi et al. 1208.4018]

i) Total Information

What is the maximum precision to measure theory parameters?

- encoded in Fisher Information $I = \sum_{\text{all events}} I_{\text{event}}$

Example: WBF Higgs Production with $H \rightarrow \tau\tau$ in SMEFT

$$I_{ij}(\mathbf{0}) = \begin{pmatrix} f_W & f_{WW} & f_{W\tilde{W}} & \text{Im}f_{WW} \\ 715 & -191 & 1 & 0 \\ -191 & 321 & -1 & 0 \\ 1 & -1 & 359 & -81 \\ 0 & 1 & -81 & 23 \end{pmatrix} \begin{matrix} f_W \\ f_{WW} \\ f_{W\tilde{W}} \\ \text{Im}f_{WW} \end{matrix}$$

- **sensitivity** to CP-violating operator
- **large mixing** between CP-conserving operators
- **no mixing** between CP-conserving and CP-violating operators
- **re-scattering** can mimic CP-violation
- best case uncertainties: $\Delta\theta > 1\sqrt{I}$

→ calculate the maximum sensitivity of any LHC process

we assume 13 TeV LHC, $L=100 \text{ fb}^{-1}$, take into account ggF and Z+jets BG,
for more analysis details see 1612.05261, 1712.02350

ii) Importance of dim8 Operators

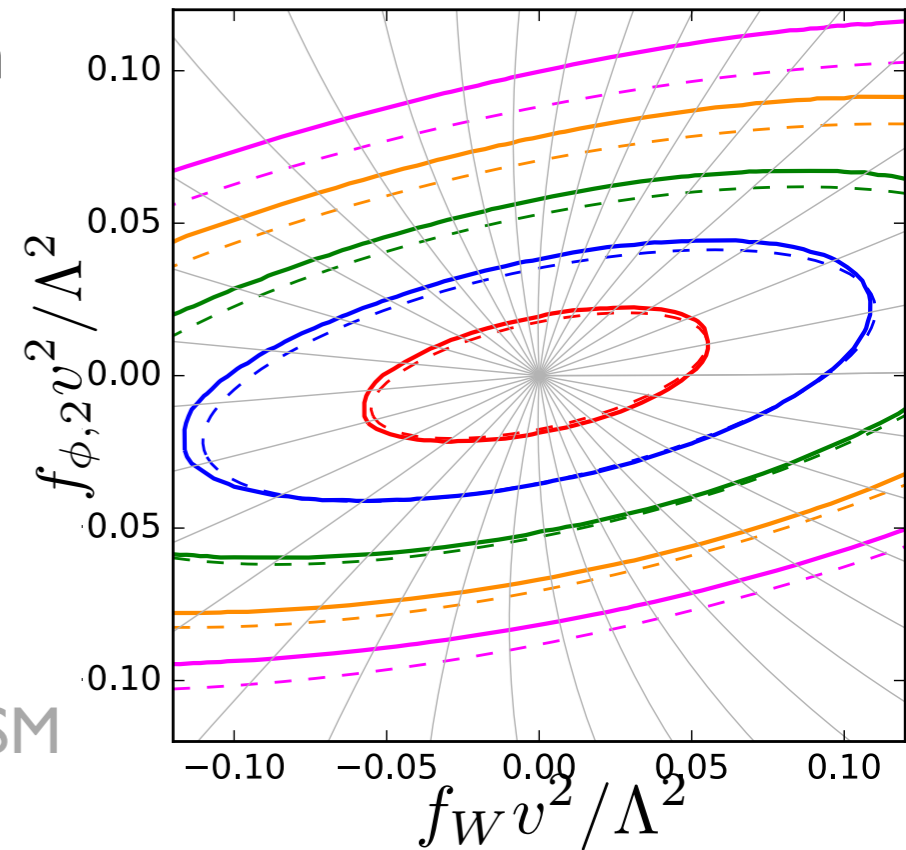
Geometric Interpretation of Fisher Information

- Distance Measure \sim unlikeliness to measure θ
if θ_{ref} is true 'in sigmas'

- local distance: $d^2 = I_{ij}(\theta_0)(\theta^i - \theta_0^i)(\theta^j - \theta_0^j)$
(dashed)

- global distance: $d = \min_{\theta(s)} \int_{s_a}^{s_b} ds \sqrt{I_{ij} \frac{d\theta_i}{ds} \frac{d\theta_j}{ds}}$
(solid)

Contours of distance $d=1,2,3,4,5$ from SM



- $I_{ij}(\theta_{\text{ref}})$ only sensitive to linear effects: $\Delta\sigma(\mathbf{x}|\theta) \sim \theta \Delta\sigma_{\text{dim6}}(\mathbf{x})$

- Information geometry for dim-6 operators $\theta_i = f_i^{d=6} v^2 / \Lambda^2$

$I_{ij}(\mathbf{0})$, local distances at SM

$$\Delta\sigma = \underbrace{\Delta\sigma_{SM} + \sum_i \frac{f_i^{d=6}}{\Lambda^2} \Delta\sigma_i}_{I_{ij}(\theta \neq 0), \text{ global distances}} + \sum_i \frac{f_i^{d=6} f_j^{d=6}}{\Lambda^4} \Delta\sigma_{ij} + \underbrace{\sum_i \frac{f_k^{d=8}}{\Lambda^4} \Delta\sigma_k}_{\text{always missing}} + \mathcal{O}(\Lambda^{-6})$$

$I_{ij}(\theta \neq 0)$, global distances

Difference between local/global distance



size of $\mathcal{O}(\Lambda^{-4})$ effects

iii) Differential Information

Where in phase space is the information?

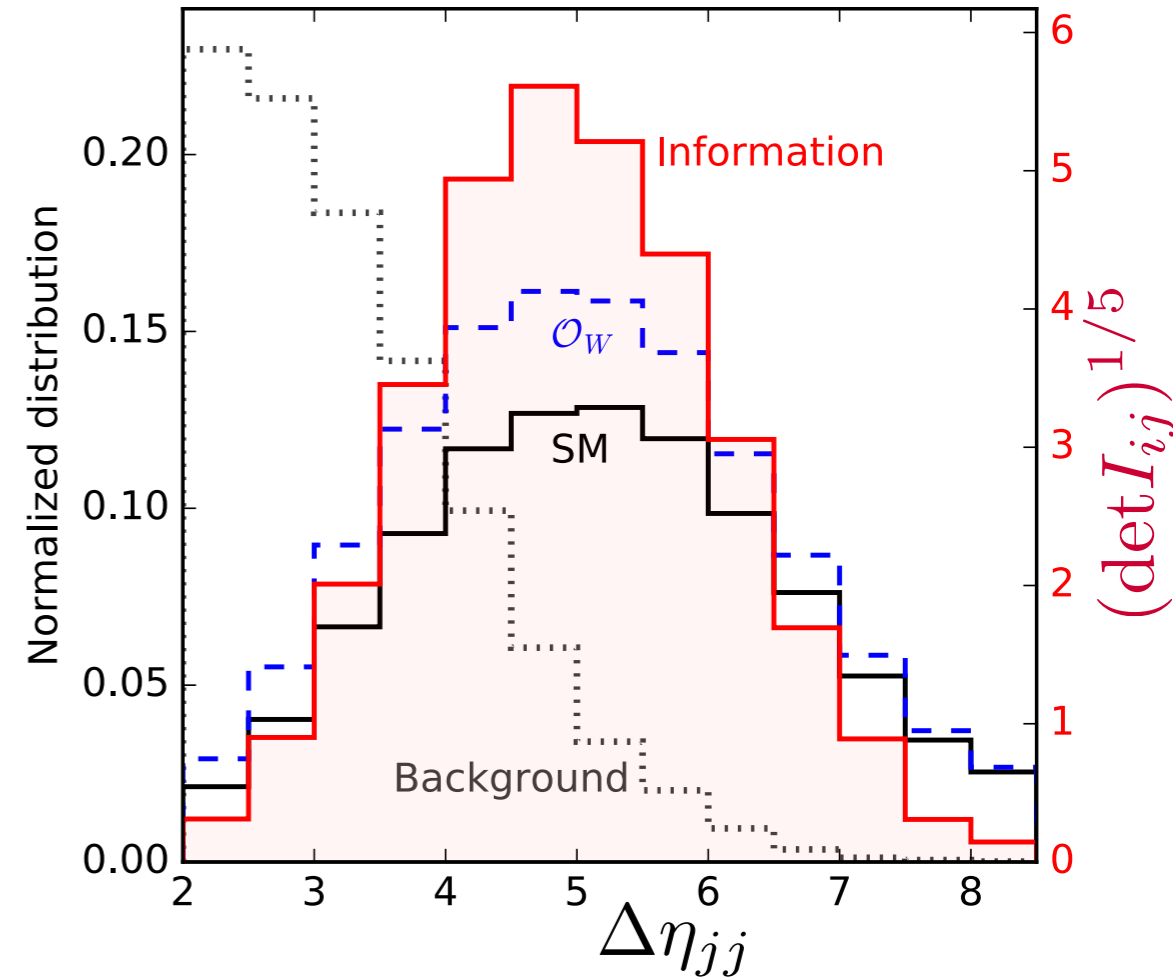
- binned kinematic distribution of information

$$I_{bin} = \sum_{events \in bin} I_{event}$$

Example: Jet Rapidity Difference in WBF

- smaller background at large $\Delta\eta_{jj}$
- momentum dependent operator
 - * largest effect at medium $\Delta\eta_{jj}$
- strong WBF cuts ($\Delta\eta_{jj} > 4.2$):
 - * lose information of dim-6 operators

→ identify relevant phase-space regions



iv) Information in Distributions

What are the most powerful observables?

- information of binned kinematic distribution

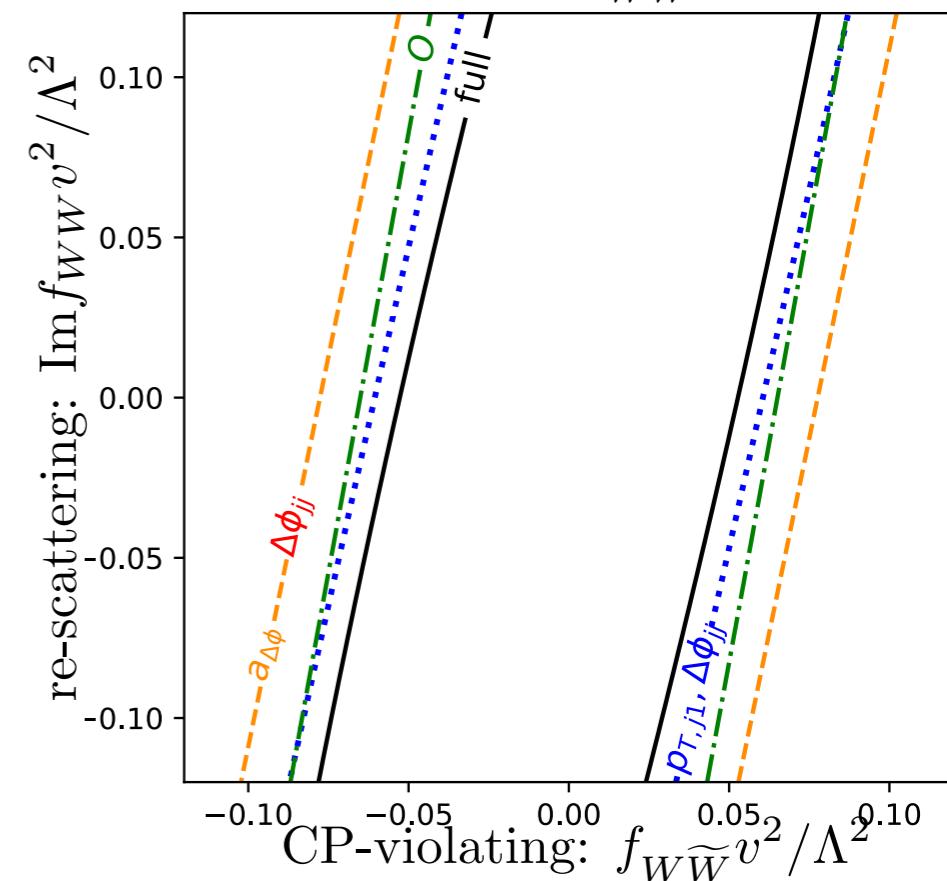
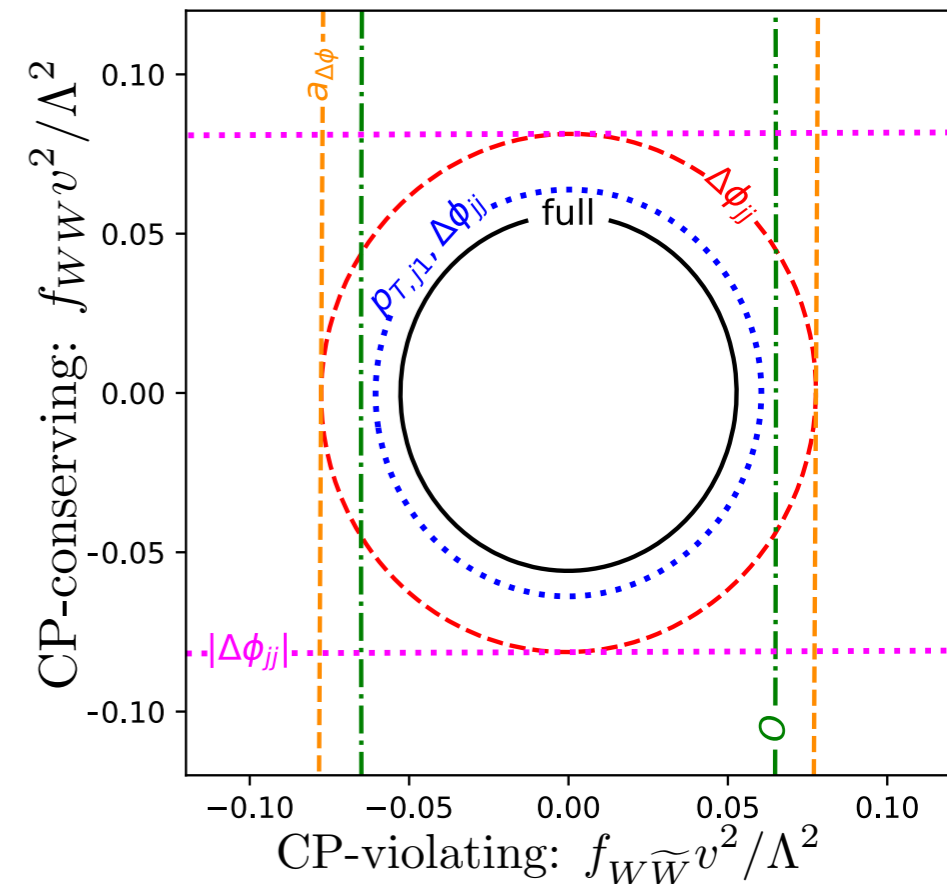
$$I = \sum_{bins} I_{bin}$$

- minimum measurement error $\Delta f \geq 1/\sqrt{I}$

Example: Higgs coupling measurement in WWF

- $|\Delta\phi_{jj}|$ sensitive to CP-conserving physics only
- **asymmetry** sensitive to CP-violating physics only
- **signed** $\Delta\phi_{jj}$ probes both
- **2D histogram** better, but still not close to **full** information
- re-scattering effects can mimic CP-violation
- **asymmetry** in $\Delta\phi_{jj}$ implies CP violation (in the absence of re-scattering)
- re-scattering small in SM

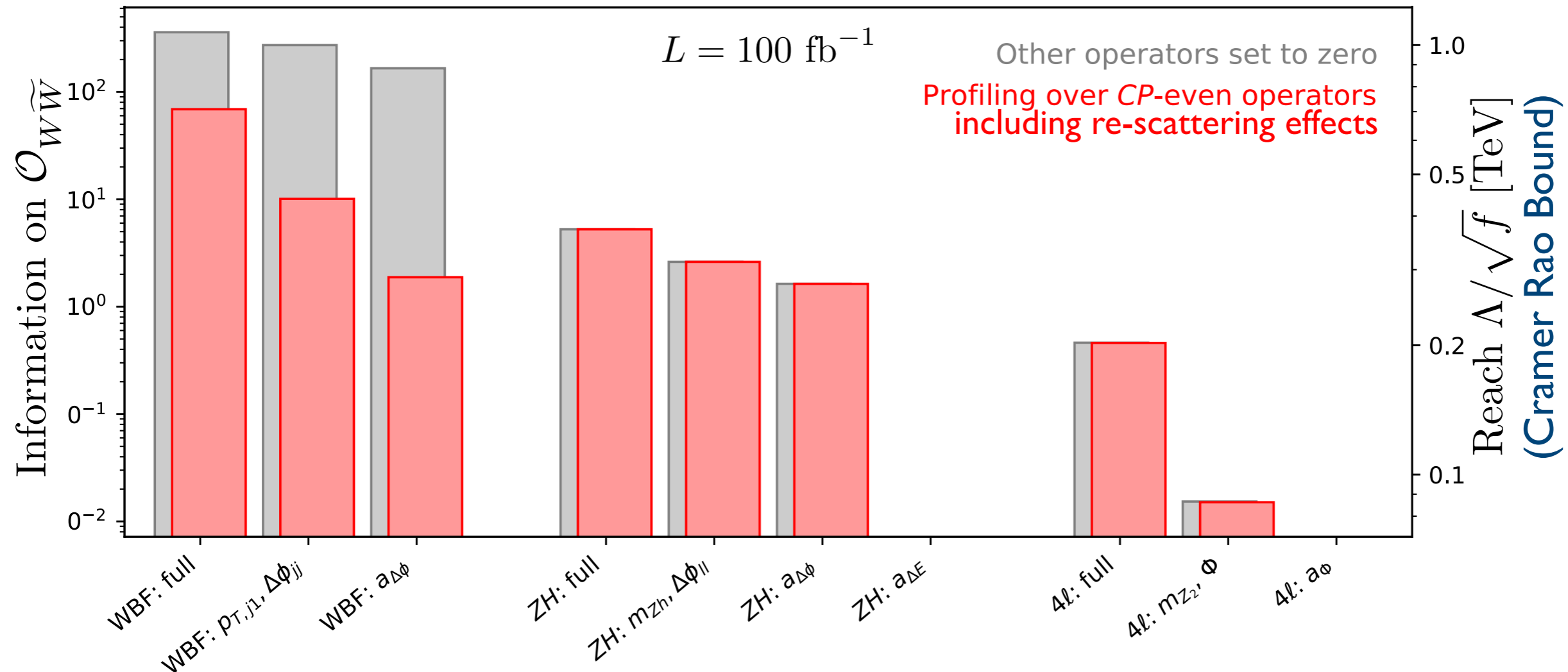
→ identify most powerful observables



v) Information in Analyses

How do histogram-based and multivariate analyses compare?

Example: Information on CP-violating Higgs couplings



- more sensitivity in WBF and ZH than $H \rightarrow 4l$ due to larger momentum transfer
- WBF requires additional theory assumption on re-scattering
- CP-information mostly captured in asymmetry of $\epsilon_{\alpha\beta\gamma\delta} p_1^\alpha p_2^\beta p_3^\gamma p_4^\delta \sim \Delta\phi$
- adding momentum transfer measures/multivariate analysis increase sensitivity

→ quantitatively compare histogram-based vs. multivariate analyses

Outline

Some Statistic Concepts

Likelihoods, Optimal Observables and Fisher Information

Information Geometry in Theory

Parton Level and Matrix Elements

Information Geometry in Reality

Detector Effects and Machine Learning

Summary and Conclusion

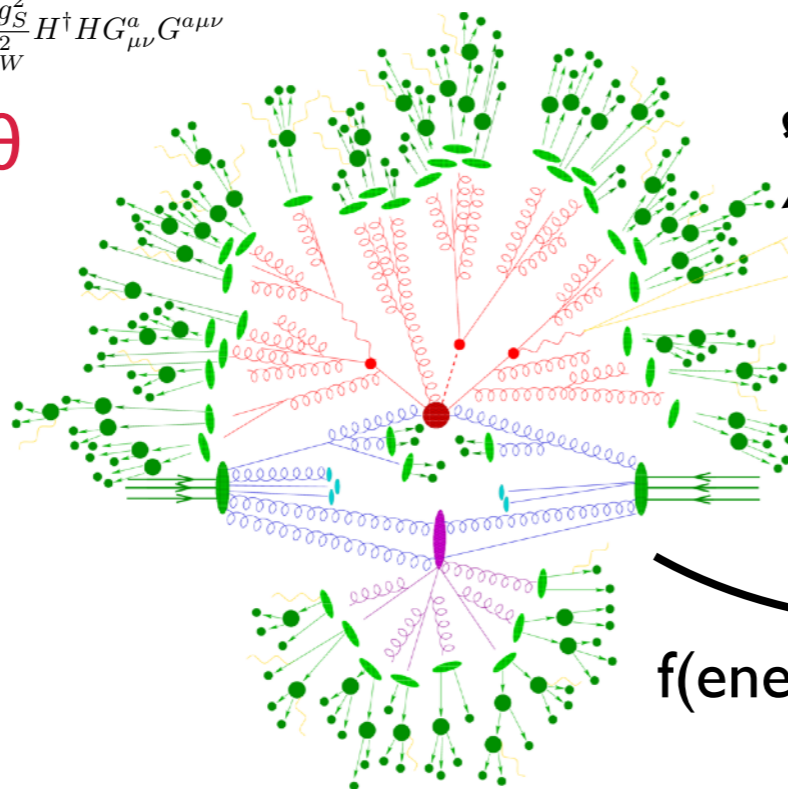
Simulation in Real Life

How can we compute the likelihood function?

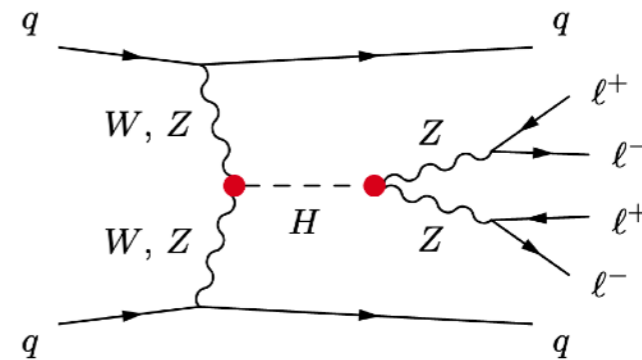
sophisticated tools model parts of process

$$\begin{aligned} \Delta\mathcal{L}_{SILH} = & \frac{\bar{c}_H}{2v^2} \partial^\mu (H^\dagger H) \partial_\mu (H^\dagger H) + \frac{\bar{c}_T}{2v^2} (H^\dagger \overleftrightarrow{D}' H) (H^\dagger \overleftrightarrow{D}_\mu H) - \frac{\bar{c}_6 \lambda}{v^2} (H^\dagger H)^3 \\ & + \left(\frac{\bar{c}_u}{v^2} y_u H^\dagger H \bar{q}_L H^c u_R + \frac{\bar{c}_d}{v^2} y_d H^\dagger H \bar{q}_L H d_R + \frac{\bar{c}_l}{v^2} y_l H^\dagger H \bar{l}_L H l_R \right) + \text{h.c.} \\ & + \frac{i\bar{c}_W g}{2m_W^2} (H^\dagger \sigma^i \overleftrightarrow{D}' H) (D^\nu W_{\mu\nu})^i + \frac{i\bar{c}_B g'}{2m_W^2} (H^\dagger \overleftrightarrow{D}' H) (\partial^\nu B_{\mu\nu}) \\ & + \frac{i\bar{c}_{HW} g}{m_W^2} (D^\mu H)^\dagger \sigma^i (D^\nu H) W_{\mu\nu}^i + \frac{i\bar{c}_{HB} g'}{m_W^2} (D^\mu H)^\dagger (D^\nu H) B_{\mu\nu} \\ & + \frac{\bar{c}_\gamma g'^2}{m_W^2} H^\dagger H B_{\mu\nu} B^{\mu\nu} + \frac{\bar{c}_g g_S^2}{m_W^2} H^\dagger H G_{\mu\nu}^a G^{a\mu\nu} \end{aligned}$$

model of nature θ



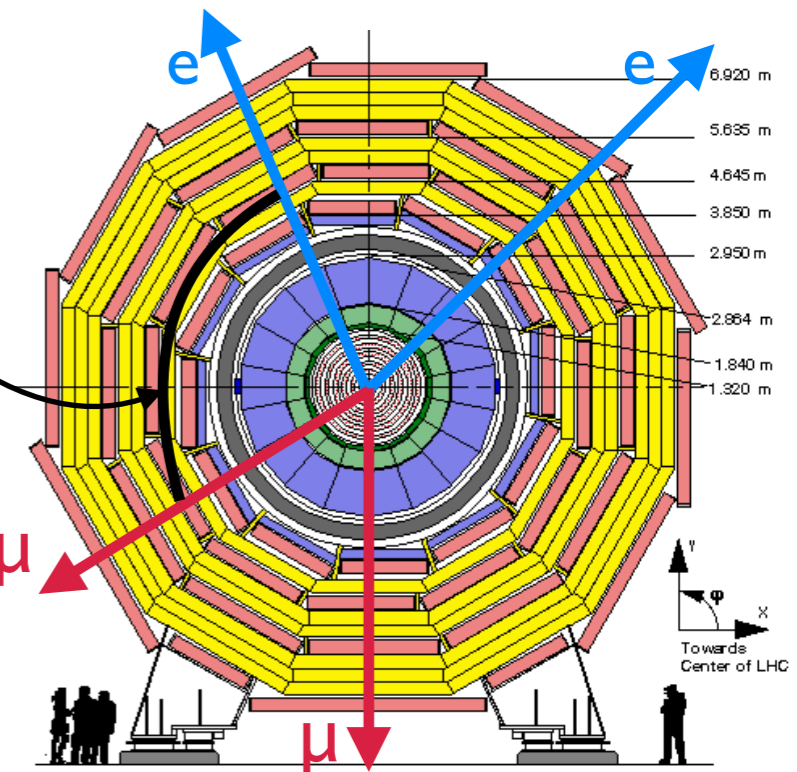
$f(\text{Higgs}|\text{model})$



$f(\text{pion}|\text{quark})$

$f(\text{energy deposit}|\text{pion})$

$\Delta\phi$



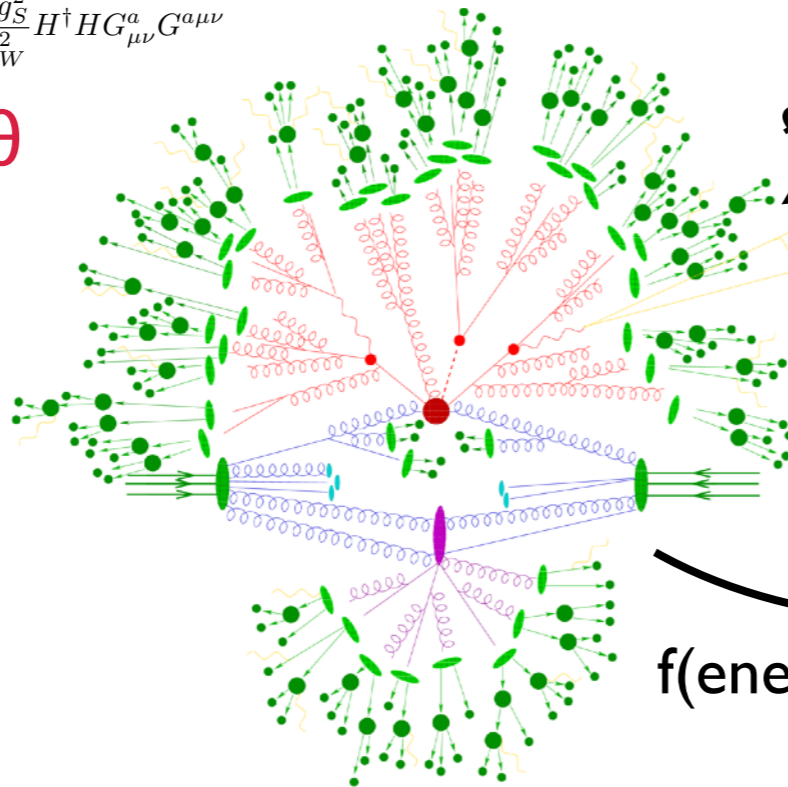
interesting observables x

Simulation in Real Life

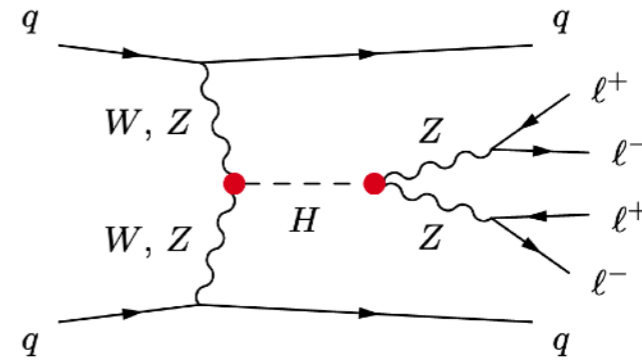
How can we compute the likelihood function?
sophisticated tools model parts of process

$$\begin{aligned} \Delta\mathcal{L}_{SILH} = & \frac{\bar{c}_H}{2v^2} \partial^\mu (H^\dagger H) \partial_\mu (H^\dagger H) + \frac{\bar{c}_T}{2v^2} (H^\dagger \overleftrightarrow{D}' H) (H^\dagger \overleftrightarrow{D}_\mu H) - \frac{\bar{c}_6 \lambda}{v^2} (H^\dagger H)^3 \\ & + \left(\frac{\bar{c}_u}{v^2} y_u H^\dagger H \bar{q}_L H^c u_R + \frac{\bar{c}_d}{v^2} y_d H^\dagger H \bar{q}_L H d_R + \frac{\bar{c}_l}{v^2} y_l H^\dagger H \bar{l}_L H l_R \right) + \text{h.c.} \\ & + \frac{i\bar{c}_W g}{2m_W^2} (H^\dagger \sigma^i \overleftrightarrow{D}' H) (D^\nu W_{\mu\nu})^i + \frac{i\bar{c}_B g'}{2m_W^2} (H^\dagger \overleftrightarrow{D}' H) (\partial^\nu B_{\mu\nu}) \\ & + \frac{i\bar{c}_{HW} g}{m_W^2} (D^\mu H)^\dagger \sigma^i (D^\nu H) W_{\mu\nu}^i + \frac{i\bar{c}_{HB} g'}{m_W^2} (D^\mu H)^\dagger (D^\nu H) B_{\mu\nu} \\ & + \frac{\bar{c}_\gamma g'^2}{m_W^2} H^\dagger H B_{\mu\nu} B^{\mu\nu} + \frac{\bar{c}_g g_S^2}{m_W^2} H^\dagger H G_{\mu\nu}^a G^{a\mu\nu} \end{aligned}$$

model of nature θ

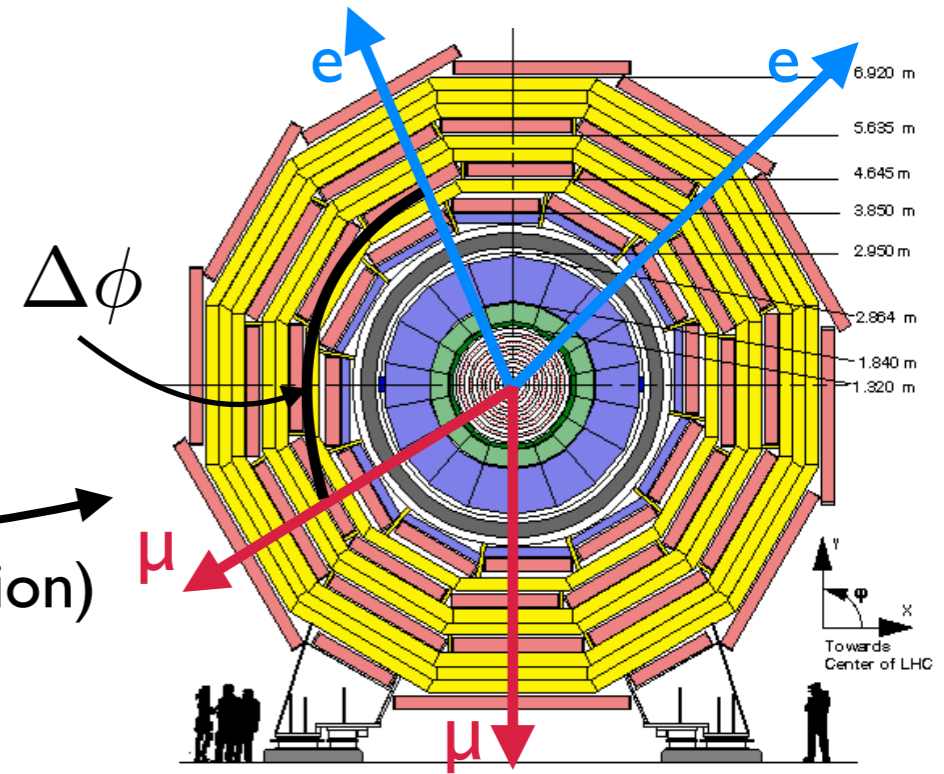


$f(\text{Higgs}|\text{model})$



$f(\text{pion}|\text{quark})$

$f(\text{energy deposit}|\text{pion})$



interesting observables x

we obtain events distributed according to $f(x|\theta)$
we cannot calculate $f(x|\theta)$

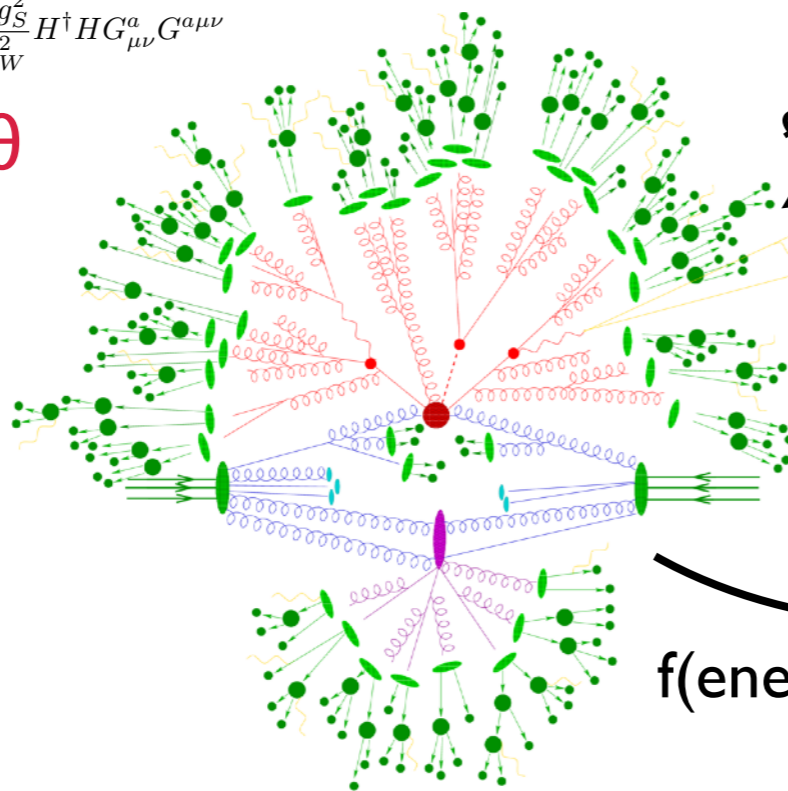
Simulation in Real Life

How can we compute the likelihood function?

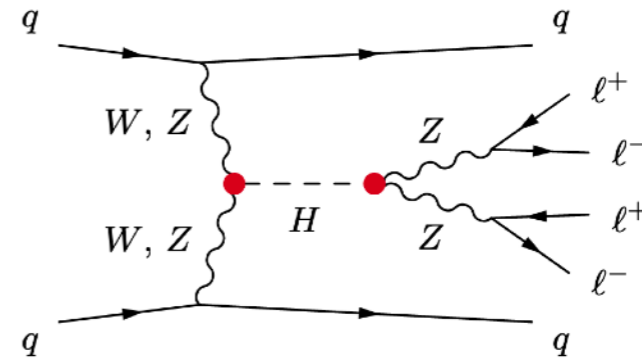
sophisticated tools model parts of process

$$\begin{aligned} \Delta\mathcal{L}_{SILH} = & \frac{\bar{c}_H}{2v^2} \partial^\mu (H^\dagger H) \partial_\mu (H^\dagger H) + \frac{\bar{c}_T}{2v^2} (H^\dagger \overleftrightarrow{D}^\mu H) (H^\dagger \overleftrightarrow{D}_\mu H) - \frac{\bar{c}_6 \lambda}{v^2} (H^\dagger H)^3 \\ & + \left(\frac{\bar{c}_u}{v^2} y_u H^\dagger H \bar{q}_L H^c u_R + \frac{\bar{c}_d}{v^2} y_d H^\dagger H \bar{q}_L H d_R + \frac{\bar{c}_l}{v^2} y_l H^\dagger H \bar{l}_L H l_R \right) + \text{h.c.} \\ & + \frac{i\bar{c}_W g}{2m_W^2} (H^\dagger \sigma^i \overleftrightarrow{D}^\mu H) (D^\nu W_{\mu\nu})^i + \frac{i\bar{c}_B g'}{2m_W^2} (H^\dagger \overleftrightarrow{D}^\mu H) (\partial^\nu B_{\mu\nu}) \\ & + \frac{i\bar{c}_{HW} g}{m_W^2} (D^\mu H)^\dagger \sigma^i (D^\nu H) W_{\mu\nu}^i + \frac{i\bar{c}_{HB} g'}{m_W^2} (D^\mu H)^\dagger (D^\nu H) B_{\mu\nu} \\ & + \frac{\bar{c}_\gamma g'^2}{m_W^2} H^\dagger H B_{\mu\nu} B^{\mu\nu} + \frac{\bar{c}_g g_S^2}{m_W^2} H^\dagger H G_{\mu\nu}^a G^{a\mu\nu} \end{aligned}$$

model of nature θ

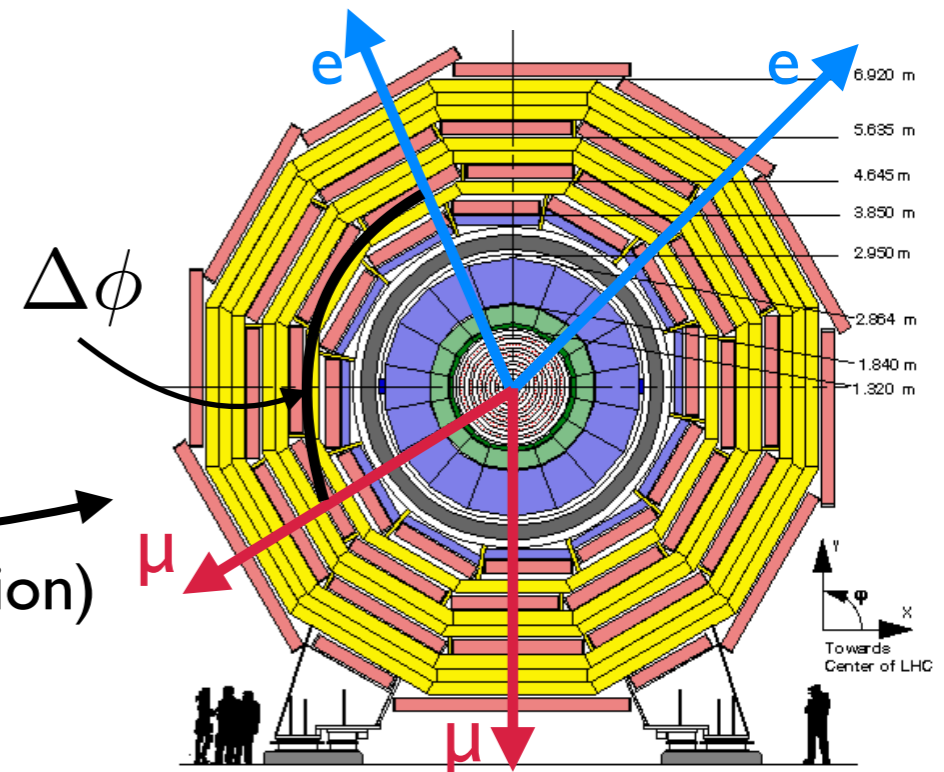


$f(\text{Higgs}|\text{model})$



$f(\text{pion}|\text{quark})$

$f(\text{energy deposit}|\text{pion})$



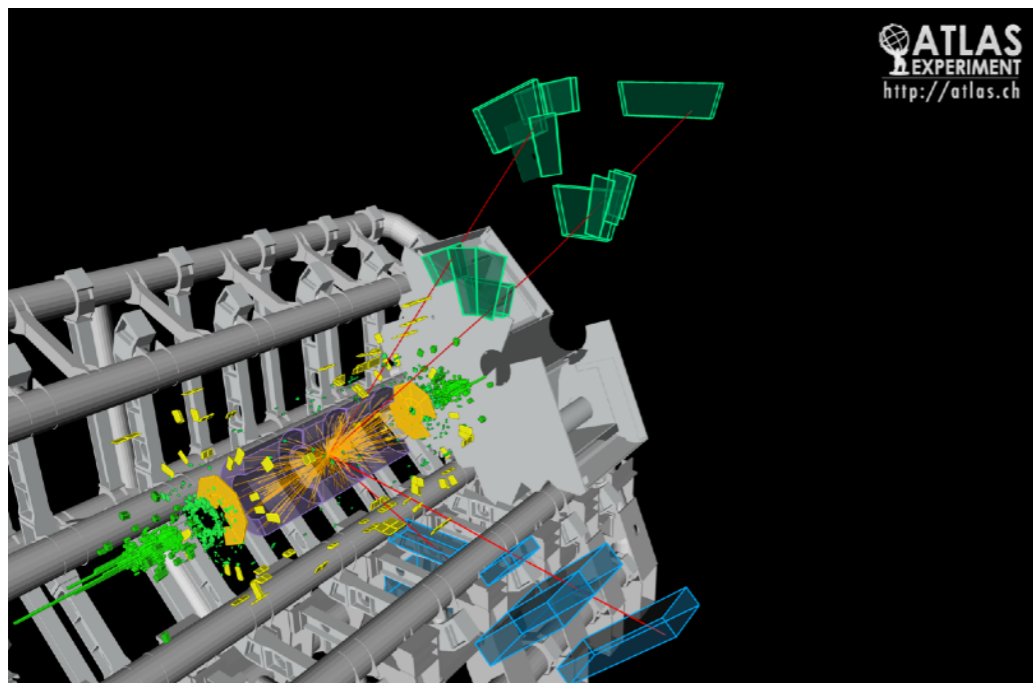
interesting observables x

we obtain events distributed according to $f(x|\theta)$
we cannot calculate $f(x|\theta)$

learn likelihood from simulated data - likelihood free inference

Inference in Real Life

Traditional Method: Histograms



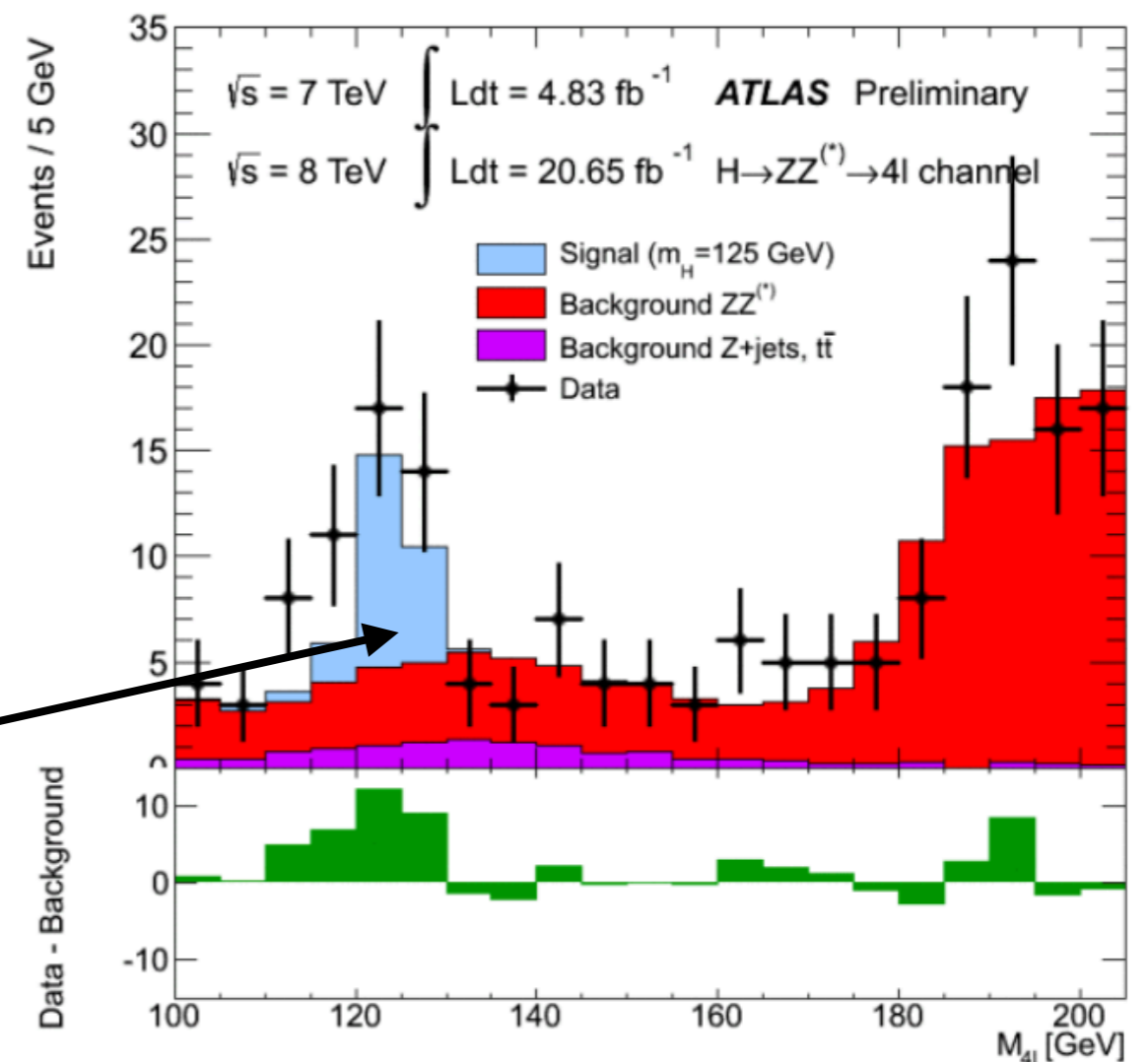
complex data: 10^8 sensors

+ very easy

- ignore all the information
in rest of the data

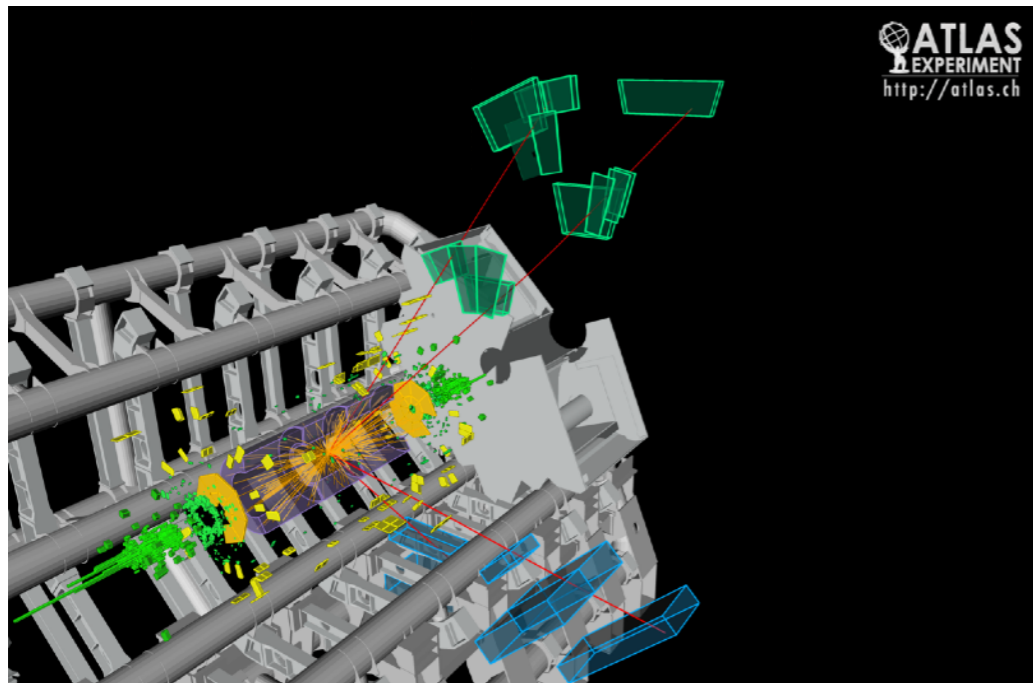
histogram $\leftrightarrow p(x|\theta)$

analyze one carefully
chosen summary statistics



Inference in Real Life

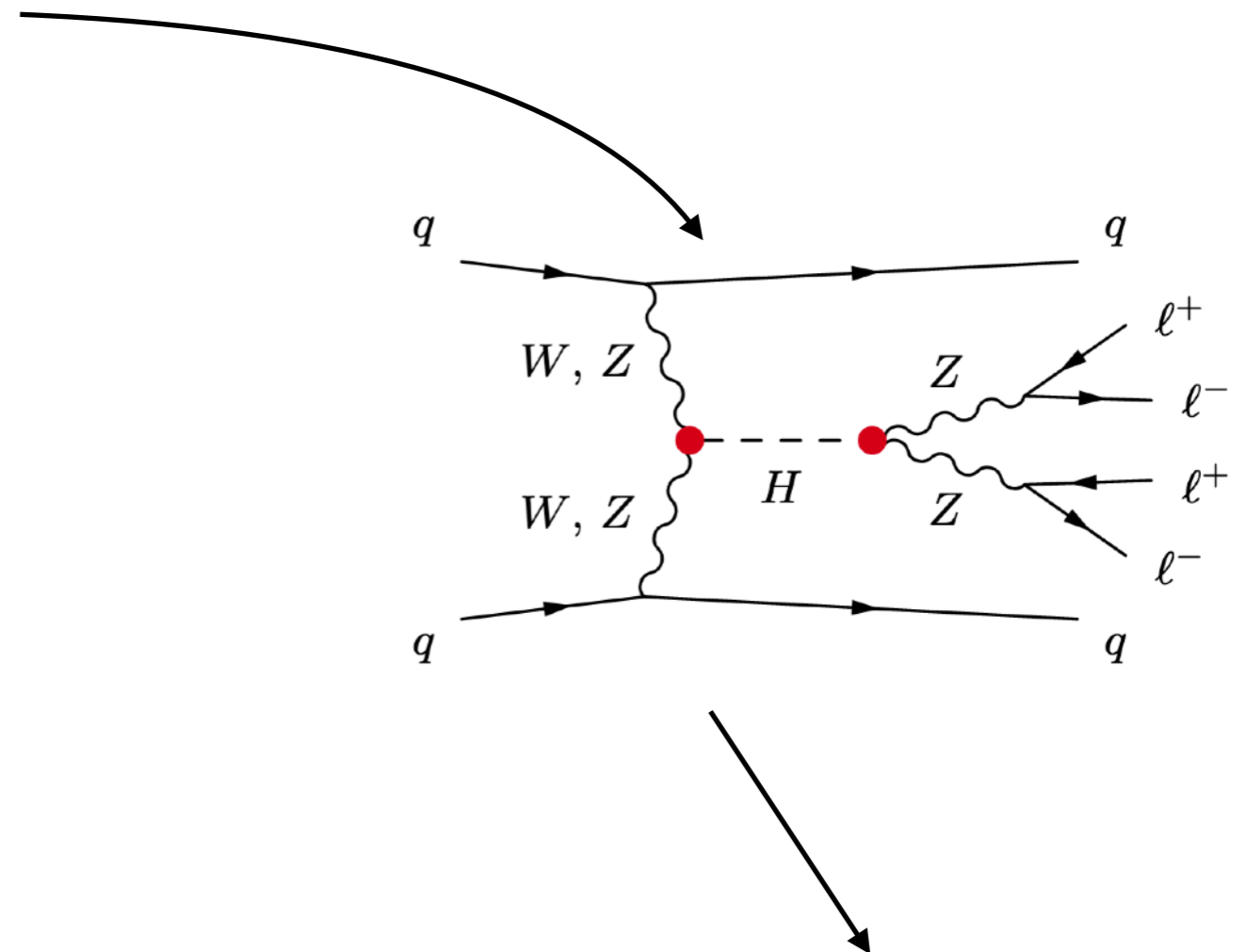
Multivariate Method: Matrix Elements



complex data: 10^8 sensors

- + works great at parton level:
 - * S' vs S is easy
- requires approximations in reality
 - * S vs BG can be hard

match to parton level event

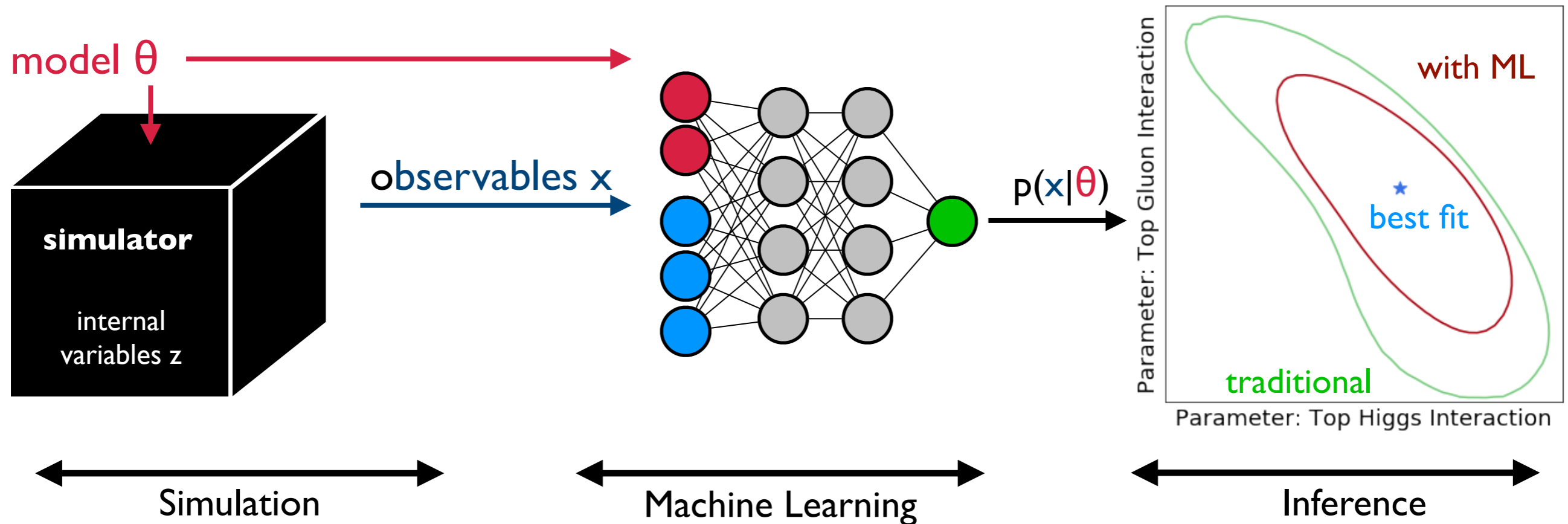


calculate matrix elements

$$p(x|\theta) \sim |M(x|\theta)|^2$$

Inference in Real Life

Multivariate Method: Machine Learning

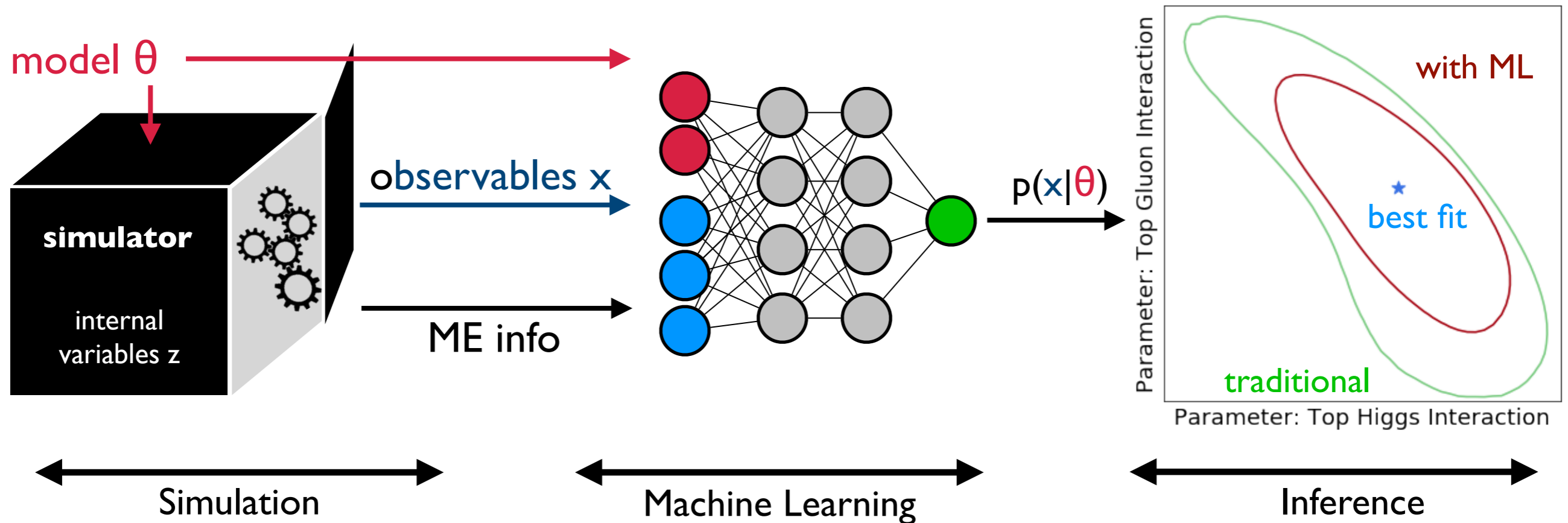


+ works great for S vs BG

- struggles with S' vs S
 - * large number of S'
 - * very similar S', S

Inference in Real Life

Multivariate Method: The MadMiner Approach



power of
machine learning

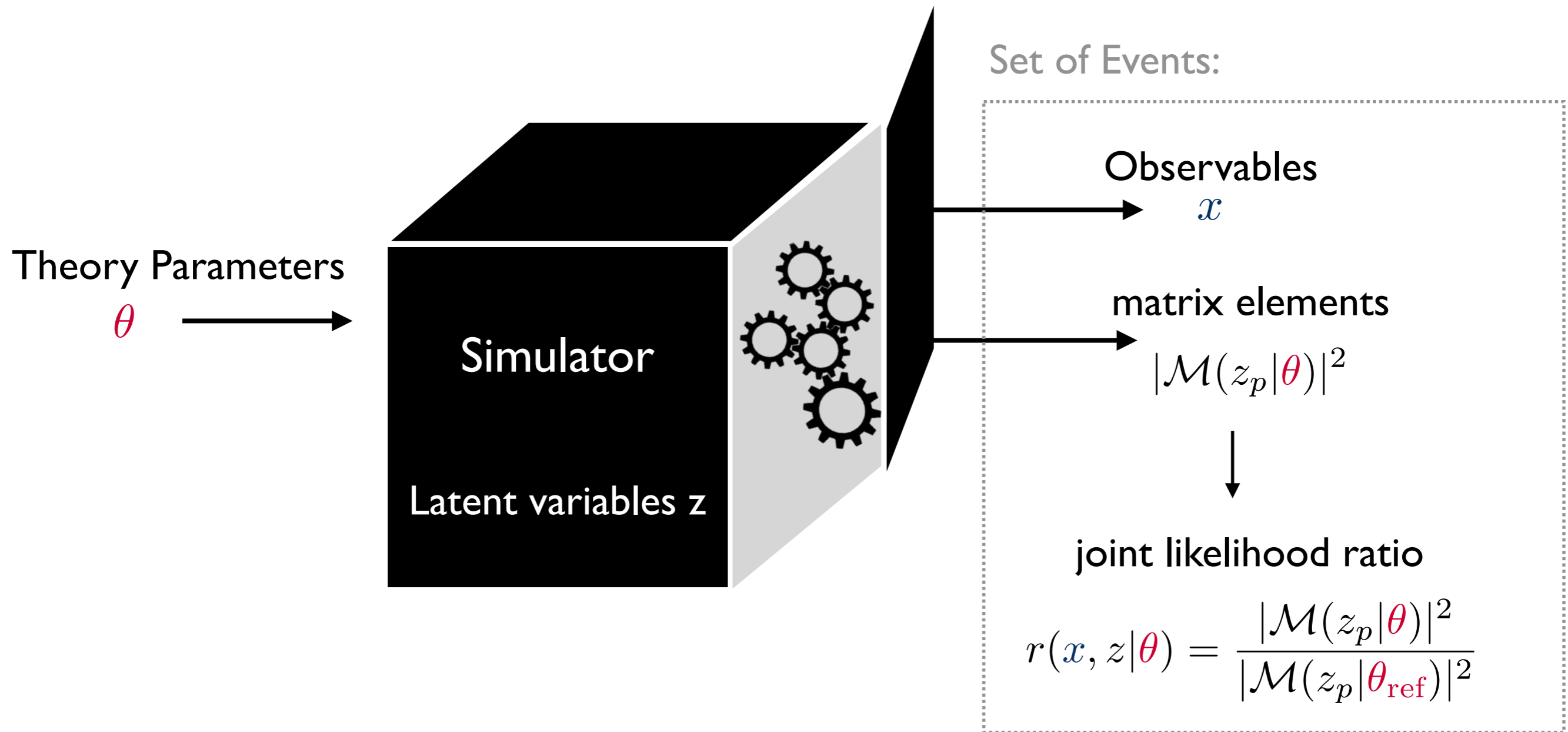
physics insight of
matrix element information

MadMiner

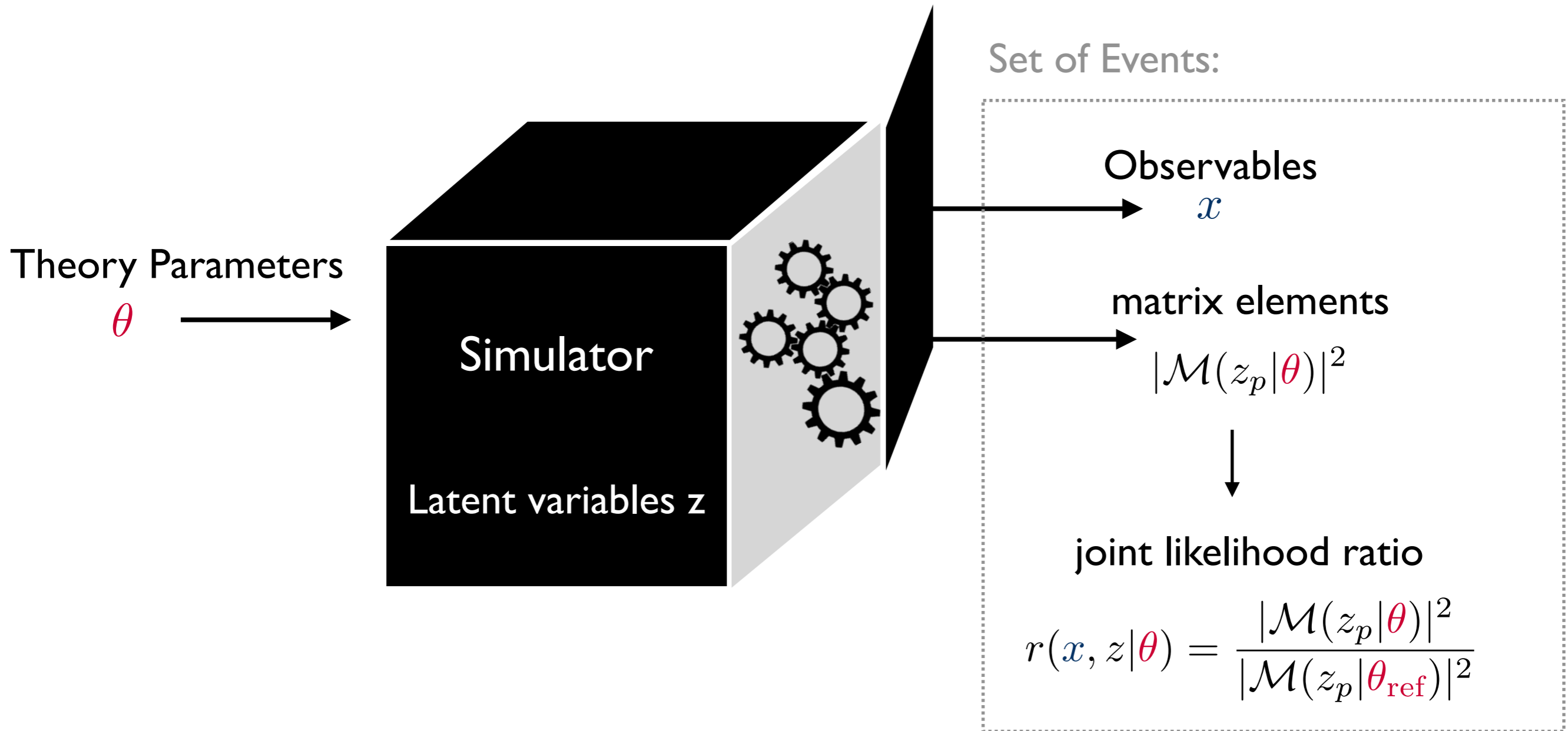
[J. Brehmer, K. Cranmer, G. Louppe, J. Pavez 1805.00013, 1805.00020, 1805.12244]

[J. Brehmer, FK, I. Espejo, K. Cranmer 1907.10621]

The MadMiner Approach



The MadMiner Approach



Problem Setup:

We want: Likelihood-ratio

$$r(x|\theta)$$

data \nearrow \nwarrow theory

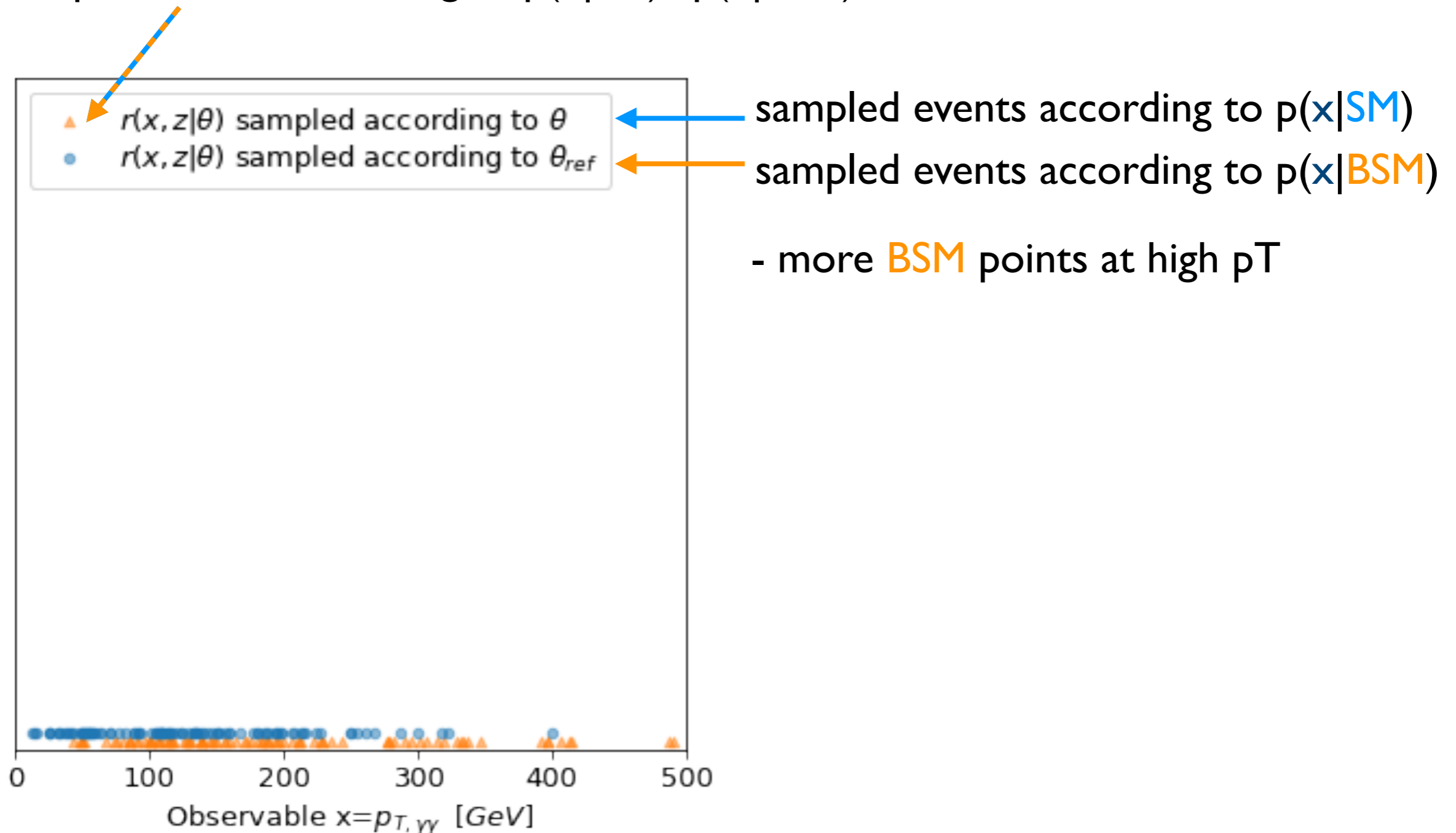
Generators give us: Joint Likelihood-ratio

$$r(x, z|\theta)$$

The MadMiner Approach

How is Likelihood Estimated?

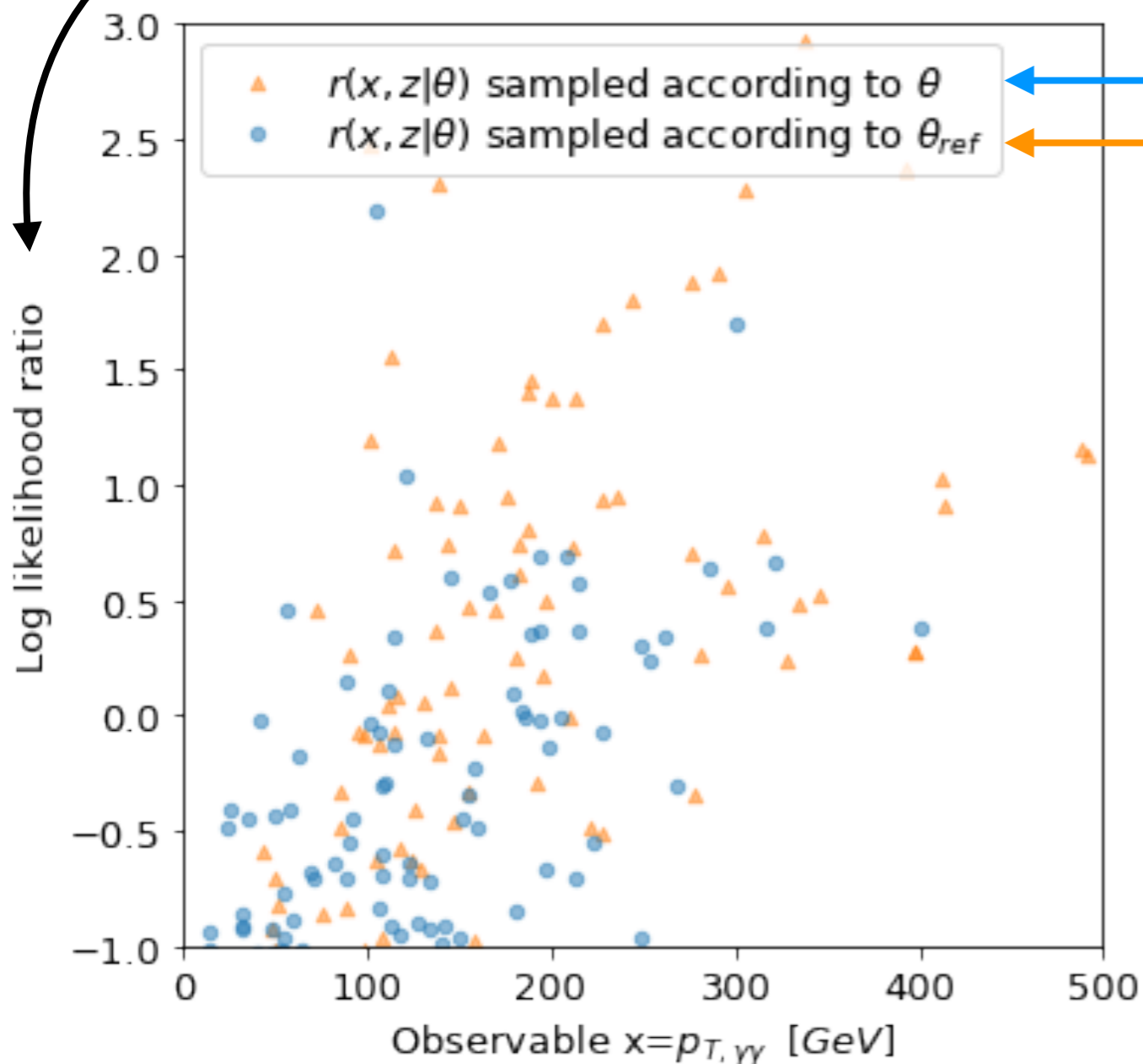
- consider two models **BSM** ($\theta=1$) vs **SM** ($\theta_{ref}=0$)
- * sampled events according to $p(x|SM)$, $p(x|BSM)$



The MadMiner Approach

How is Likelihood Estimated?

- consider two models **BSM** ($\theta=1$) vs **SM** ($\theta_{ref}=0$)
- * sampled events according to $p(x|SM)$, $p(x|BSM)$
- * y-axis: joint likelihood ratio $r(x,z|BSM,SM)$



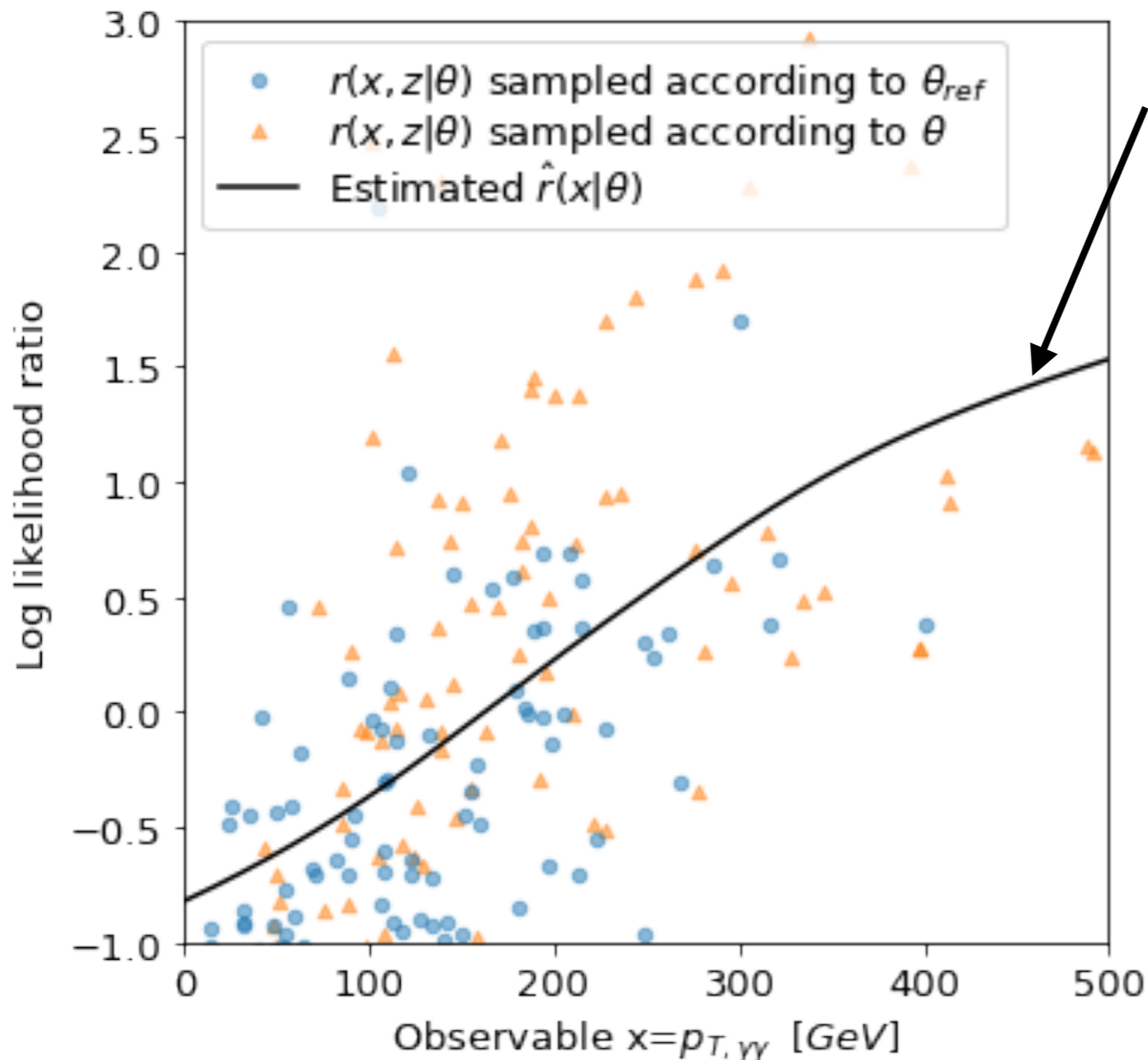
- ← sampled events according to $p(x|SM)$
- ← sampled events according to $p(x|BSM)$

- more **BSM** points at high p_T
- **BSM** more likely than **SM** at high p_T

The MadMiner Approach

How is Likelihood Estimated?

- consider two models **BSM** ($\theta=1$) vs **SM** ($\theta_{ref}=0$)
- * sampled events according to $p(x|SM)$, $p(x|BSM)$
- * y-axis: joint likelihood ratio $r(x,z|BSM,SM)$



- likelihood ratio $r(x|SM,BSM)$ is solution to minimization problem
- define functional (loss function)

$$L[\hat{r}(x|\theta)] \sim \sum |r(x|\theta) - r(x,z|\theta)|^2$$

and minimize it

$$r(x|\theta) = \arg \min_{\hat{r}(x|\theta)} L_r[\hat{r}(x|\theta)]$$

neural network

loss function

stochastic gradient descent

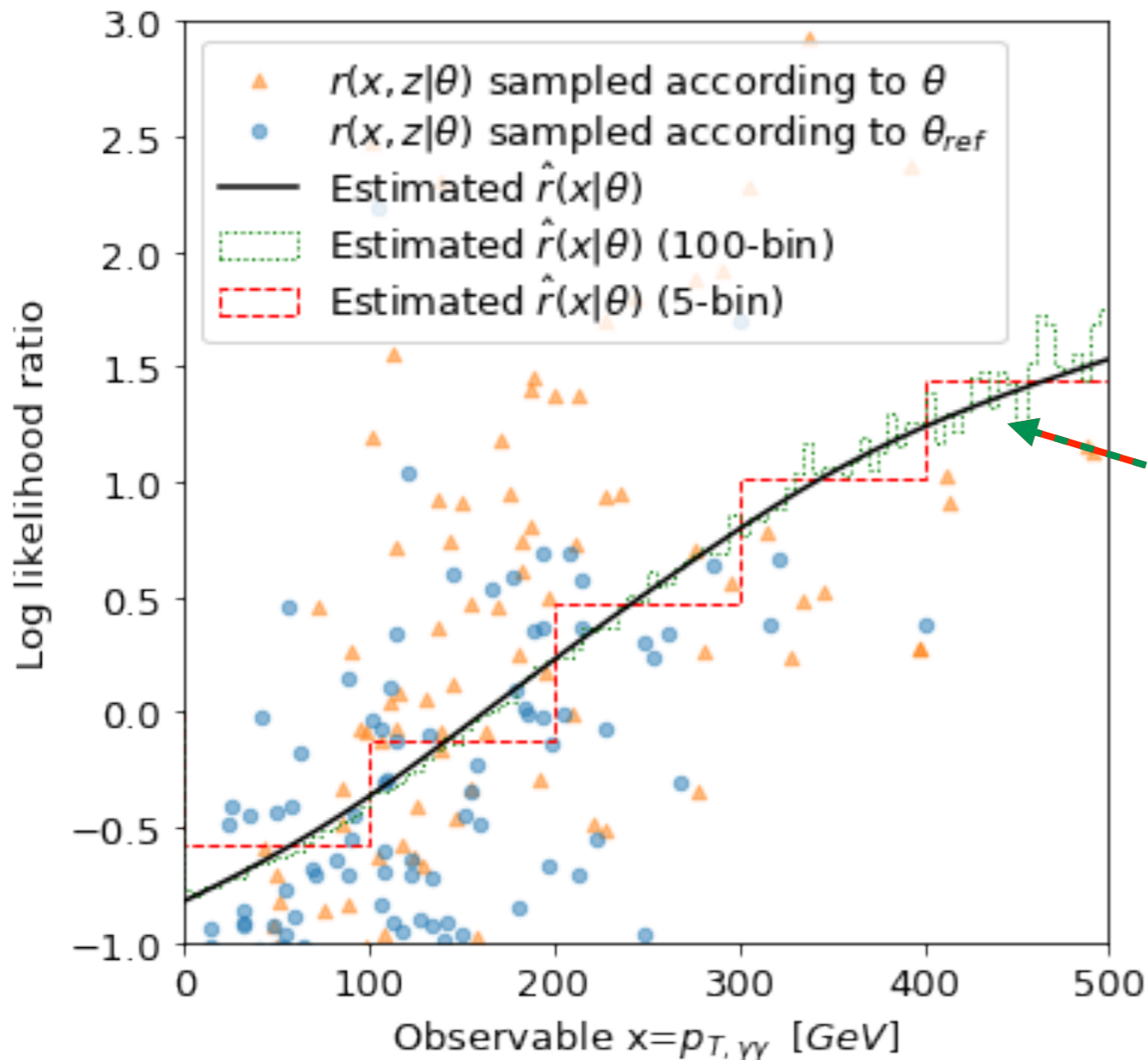
A sufficiently expressive network, efficiently trained in this way with enough data will learn the likelihood ratio function $r(x|\theta)$!

[Proof: J. Brehmer, K. Cranmer, G. Louppe, J. Pavez | 805.00020]

The MadMiner Approach

How is Likelihood Estimated?

- consider two models **BSM** ($\theta=1$) vs **SM** ($\theta_{ref}=0$)
- * sampled events according to $p(x|SM)$, $p(x|BSM)$
- * y-axis: joint likelihood ratio $r(x,z|BSM,SM)$



- estimated $r(x|SM,BSM)$
→ obtain “best fit”

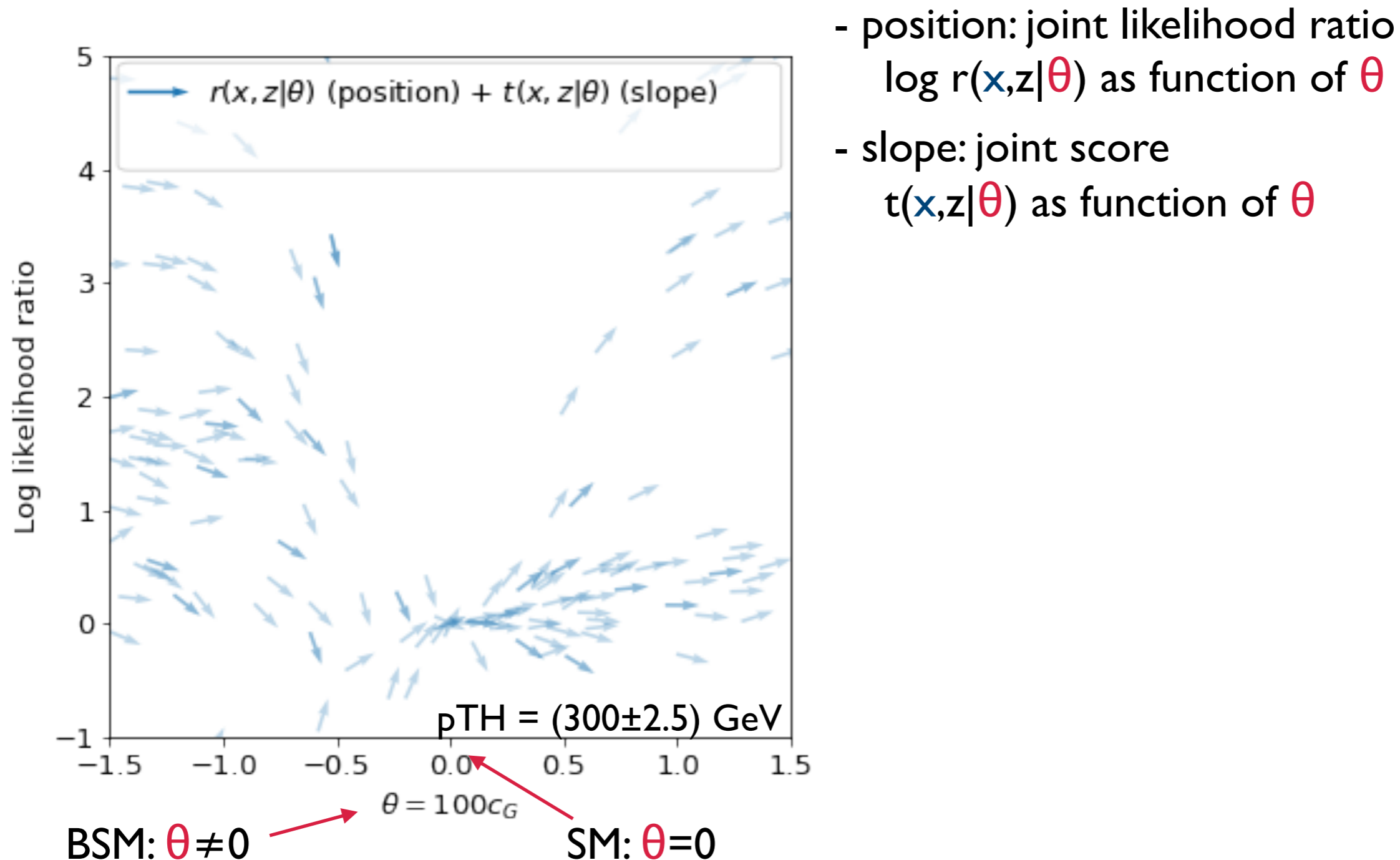
- LLR obtained using histogram
→ agrees well :)
→ “continuum limit of for large # of bins”

The MadMiner Approach

Useful: the Score!

- knowing the derivative often helps: “How does data x change, when theory θ is changed?”

→ Score: $t(x|\theta) = d \log p(x|\theta) / d\theta$

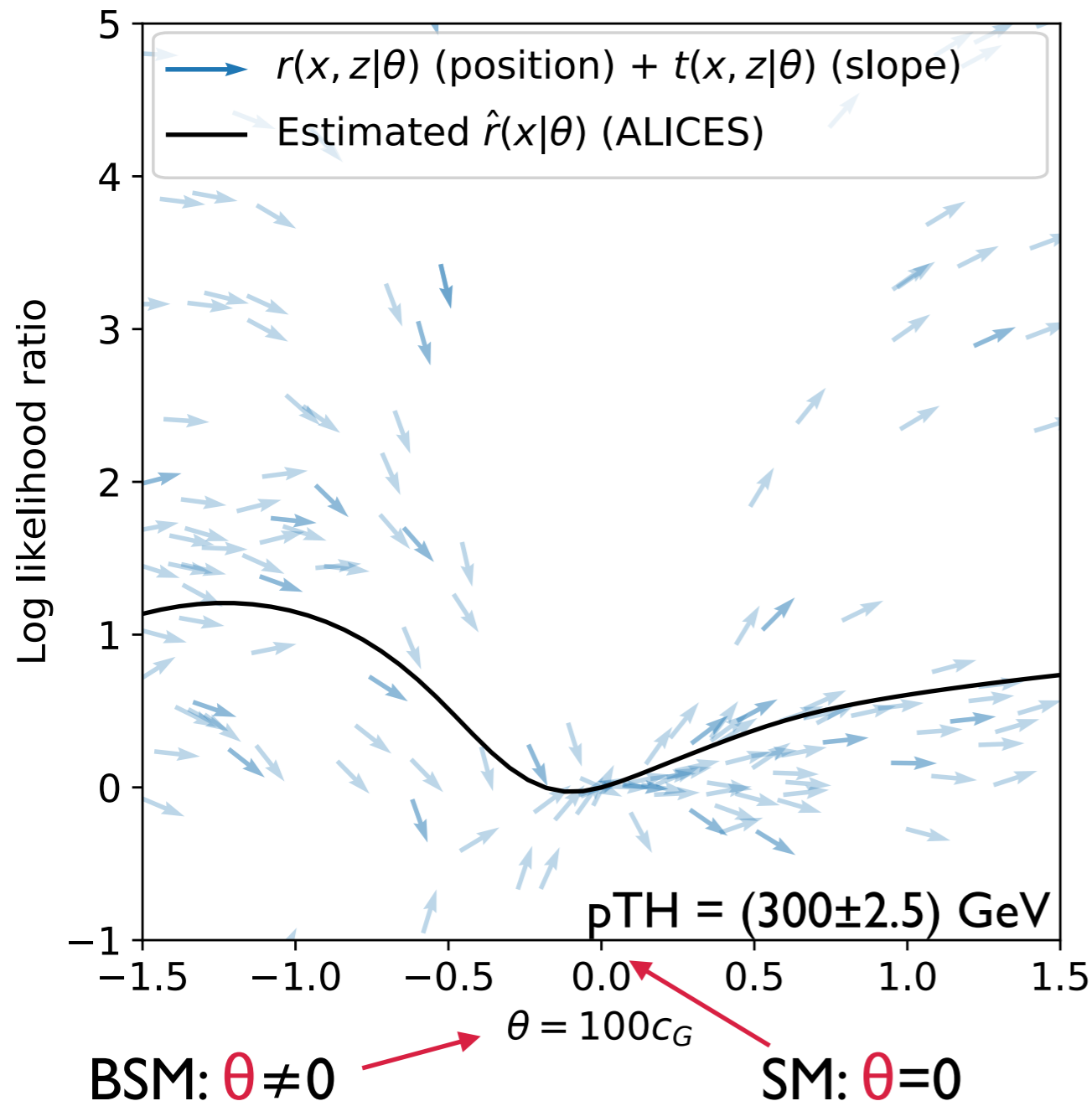


The MadMiner Approach

Useful: the Score!

- knowing the derivative often helps: “How does data x change, when theory θ is changed?”

→ Score: $t(x|\theta) = d \log p(x|\theta) / d\theta$



- position: joint likelihood ratio

$\log r(x, z|\theta)$ as function of θ

- slope: joint score

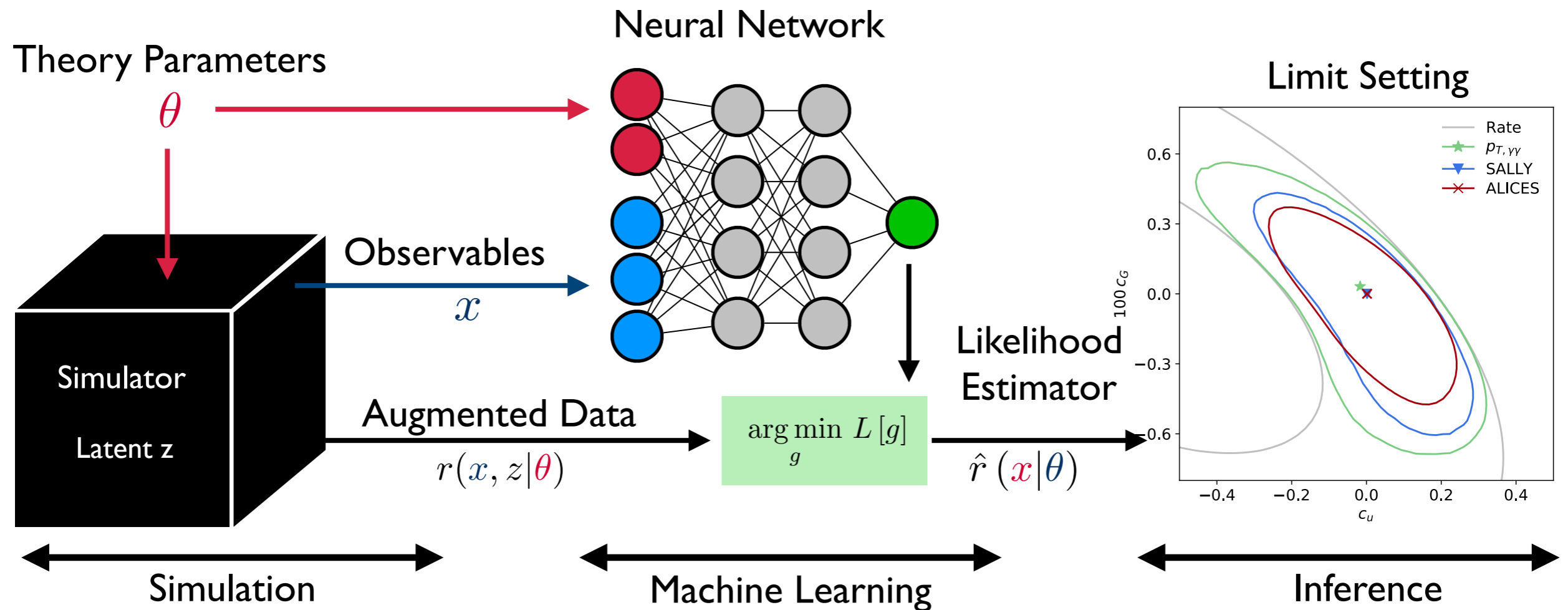
$t(x, z|\theta)$ as function of θ

↓ obtain “best fit”

- estimate $r(x, \theta)$ and $t(x, \theta)$

The MadMiner Approach

A short summary



Likelihood Ratio Estimator (ALICES)

- learn LLR as function of x and θ
- use $r(x, z | \theta)$ and $t(x, z | \theta)$ as input

$$\text{NN} : (x, \theta) \rightarrow \hat{r}(x | \theta) \approx p(x | \theta) / p(x | \theta_{\text{ref}})$$

Score Estimator (SALLY)

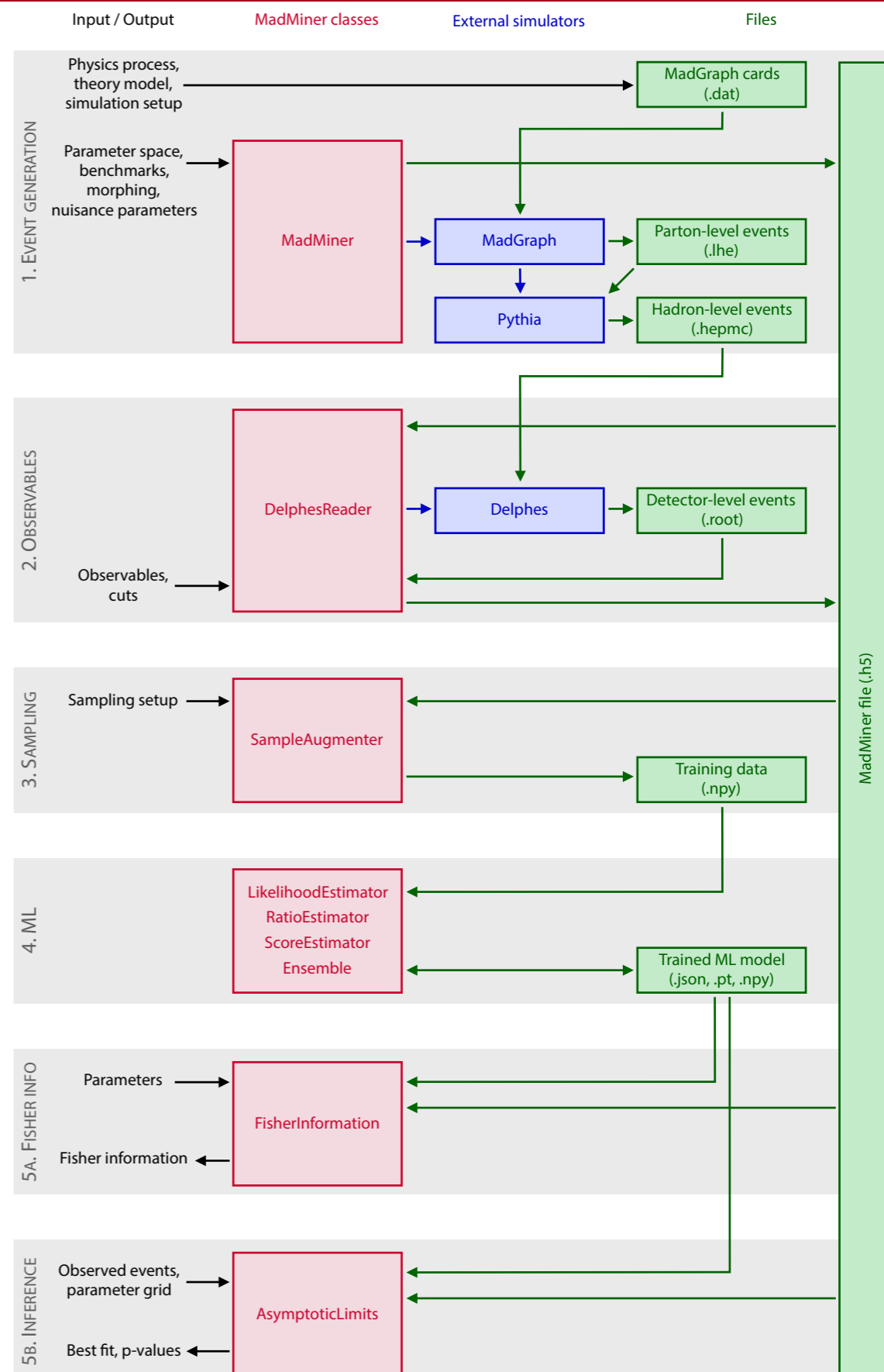
- learn score as function of x at θ_{ref}
- $t(x, z | \theta_{\text{ref}})$ as input

$$\text{NN} : x \rightarrow \hat{t}(x) \approx \nabla_{\theta} \log(x | \theta) \Big|_{\theta_{\text{ref}}}$$

MadMiner: The Tool

MadMiner [J. Brehmer, FK, I. Espejo, K. Cranmer | 907.10621]

- automizes these techniques
- straightforward to apply them to LHC problems
- out of the box: Pheno-level analysis
 - * MadGraph, Pythia, Delphes
 - * backgrounds
 - * PDF/scale uncertainties
 - * ML uncertainties
 - * morphing
 - * many inference techniques (SALLY, ALICES ...)
- scalable to state-of-the-art experimental tools
- python package
 - * modular interface
 - * extensive documentation
 - * on GitHub
 - github.com/diana-hep/madminer
 - * easy to install
 - `pip install madminer`



MadMiner: The Tool

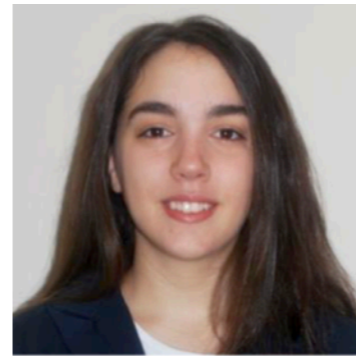
MadMiner Team



Johann Brehmer



Kyle Cranmer

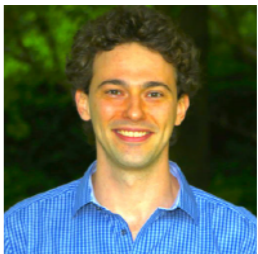
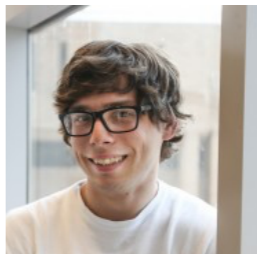
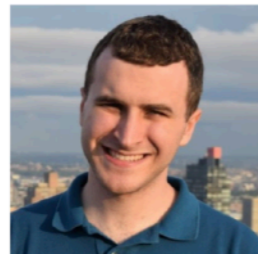


Irina Espejo



Felix Kling

Already used by many people



Thank you a lot for testing!

Example I: Probing SMEFT in ttH

ttH production in SMEFT

[J. Brehmer, FK, I. Espejo, K. Cranmer 1907.10621]

- signal: fully leptonic tth

$$pp \rightarrow t\bar{t}h \rightarrow (b\ell^+) (\bar{b}\ell^-) (\gamma\gamma) E_T^{\text{miss}}$$

- 3 operators considered

$$\mathcal{O}_u = -\frac{1}{v^2} (H^\dagger H) (H^\dagger \bar{Q}_L) u_R$$

$$\mathcal{O}_G = \frac{g_s^2}{m_W^2} (H^\dagger H) G_{\mu\nu}^a G_a^{\mu\nu}$$

$$\mathcal{O}_{uG} = -\frac{4g_s}{m_W^2} y_u (H^\dagger \bar{Q}_L) \gamma^{\mu\nu} T_a u_R G_{\mu\nu}^a$$

- rescales top Yukawa: $y_t \rightarrow y_t (1 + 3/2 c_u)$

- Higgs-gluon coupling: $g_{ggh} \rightarrow g_{ggh} (1 + 192\pi^2/g^2 c_G)$

- chromo-dipole moment: gtt, ggtt, gtth, ggth

- background: ttγγ continuum

- simulation: MadGraph5 + Pythia8 + Delphes3

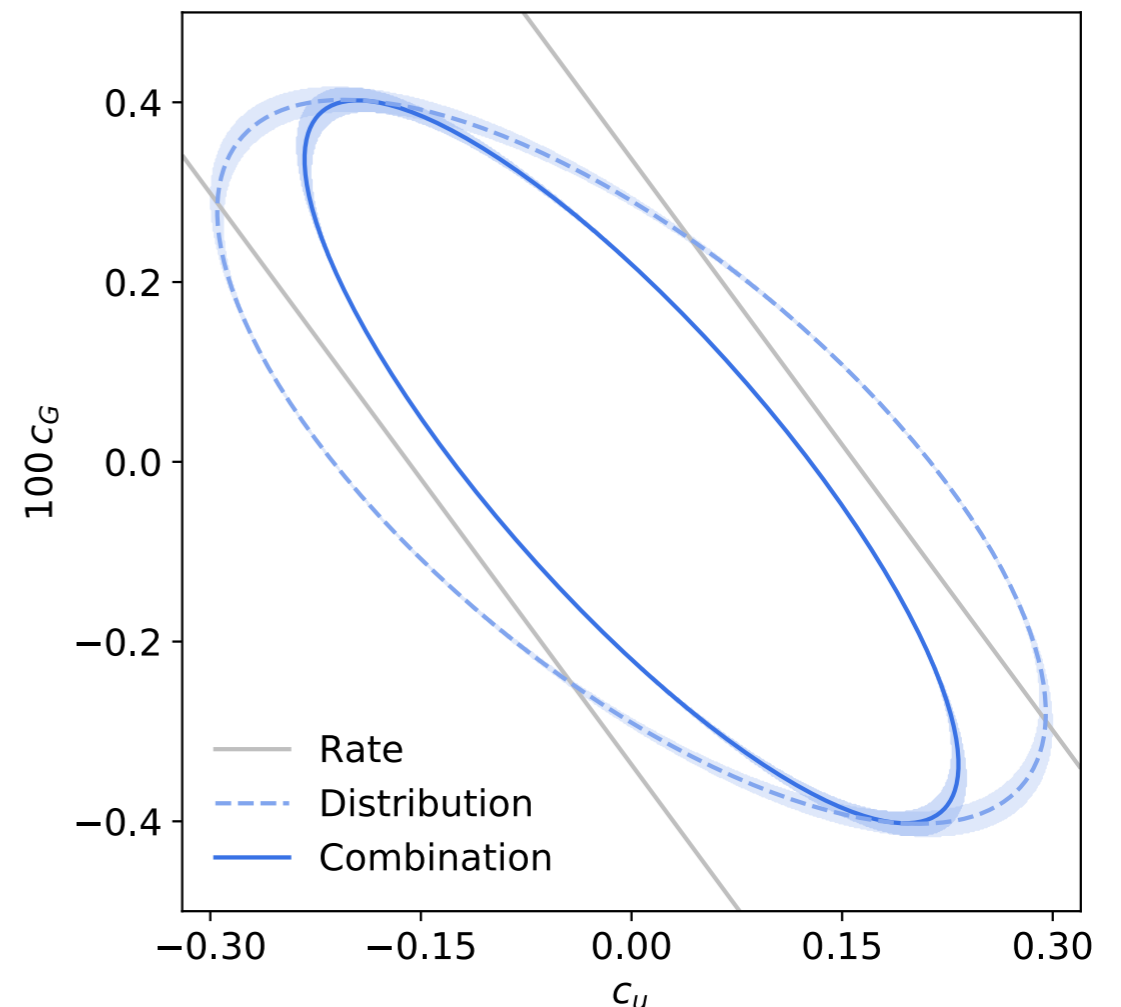
* PDF4LHC: scale + PDF uncertainties

- 48 observable:

* $\mathbf{x} = \{p_x, p_y, p_z, E, p_T, \eta, \Delta\Phi, \text{MET}, m_{ij}, \dots\}$

- Fisher Information:

$$I_{ij} = \begin{pmatrix} c_u & 100c_G & 100c_{uG} \\ 140.5 & 68.1 & 170.6 \\ 68.1 & 47.1 & 105.7 \\ 170.6 & 105.7 & 283.3 \end{pmatrix} \begin{matrix} c_u \\ 100c_G \\ 100c_{uG} \end{matrix}$$



Example I: Probing SMEFT in $t\bar{t}H$

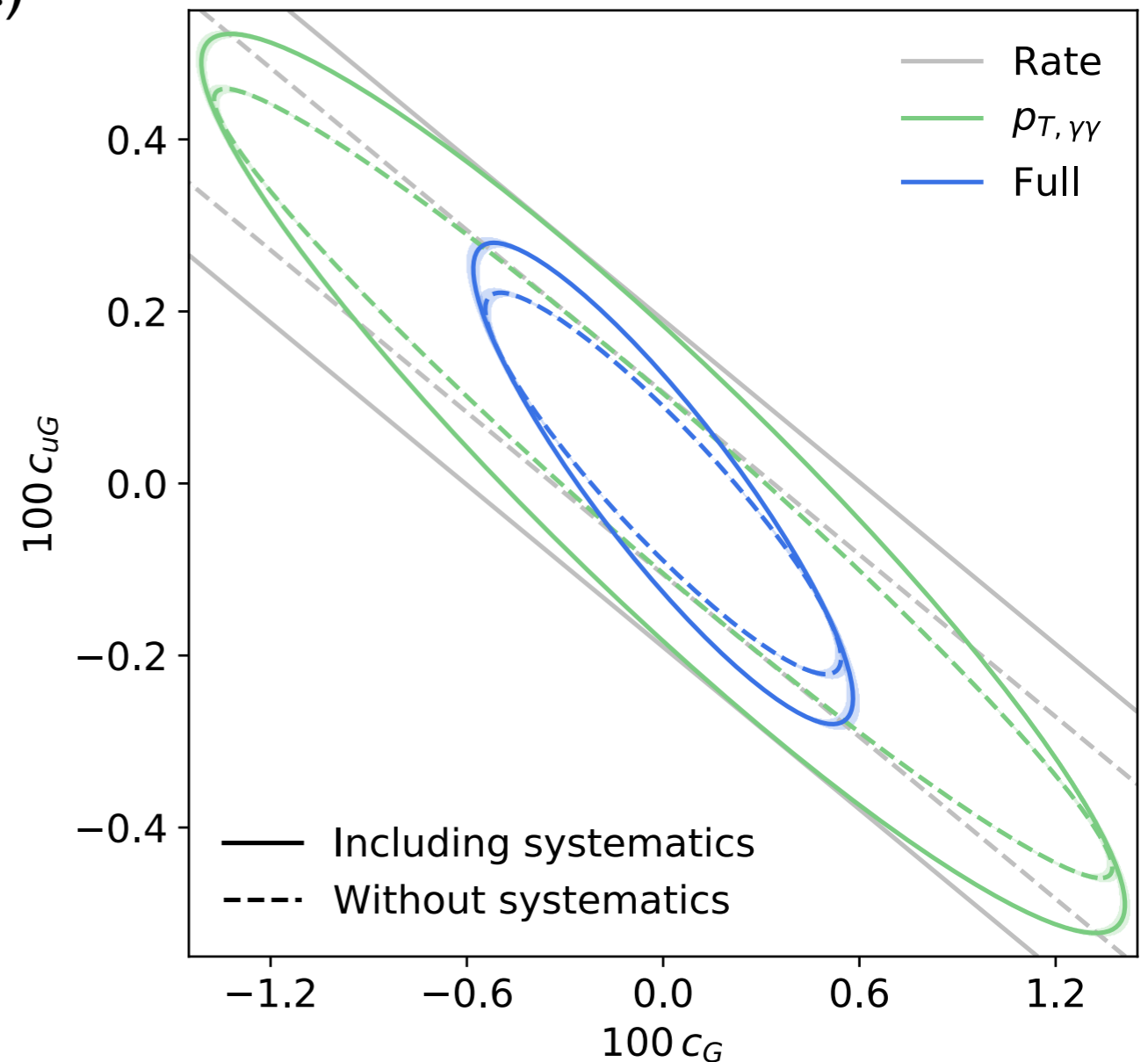
How about Systematics?

- strategy

- * introduce nuisance parameter \mathbf{v} for scale (2) and PDF (30) uncertainties
- * replace $r(\mathbf{x}|\boldsymbol{\theta}) \rightarrow r(\mathbf{x}|\boldsymbol{\theta}, \mathbf{v})$
- * learn score, obtain Fisher Info (3+32 dim.)
- * profile over \mathbf{v}

- results:

- * mainly scale uncertainties
- * systematic reduce reach in rate-sensitive direction
- * multivariate analysis less affected



Example I: Probing SMEFT in $t\bar{t}H$

Full Results

- inference methods

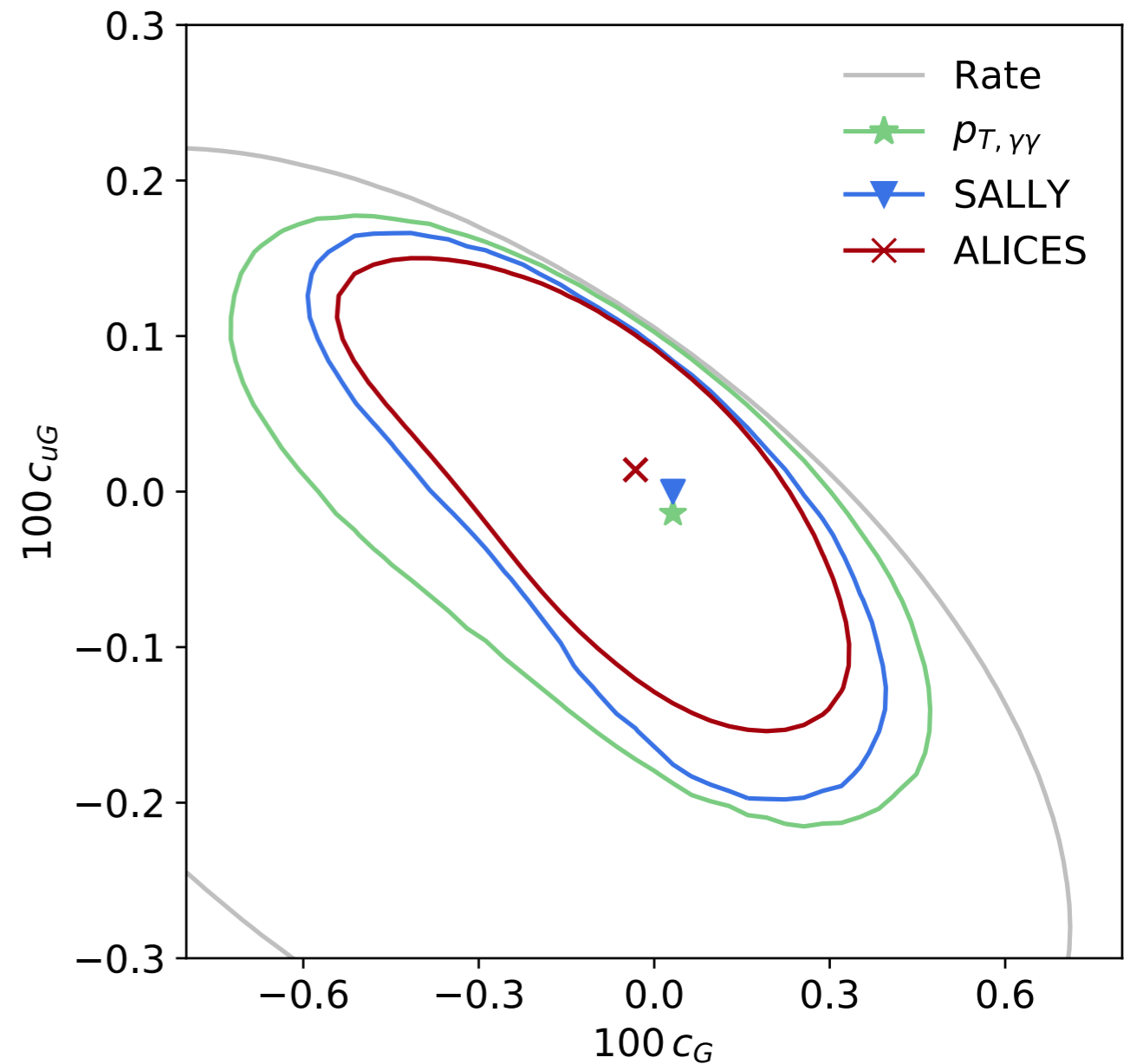
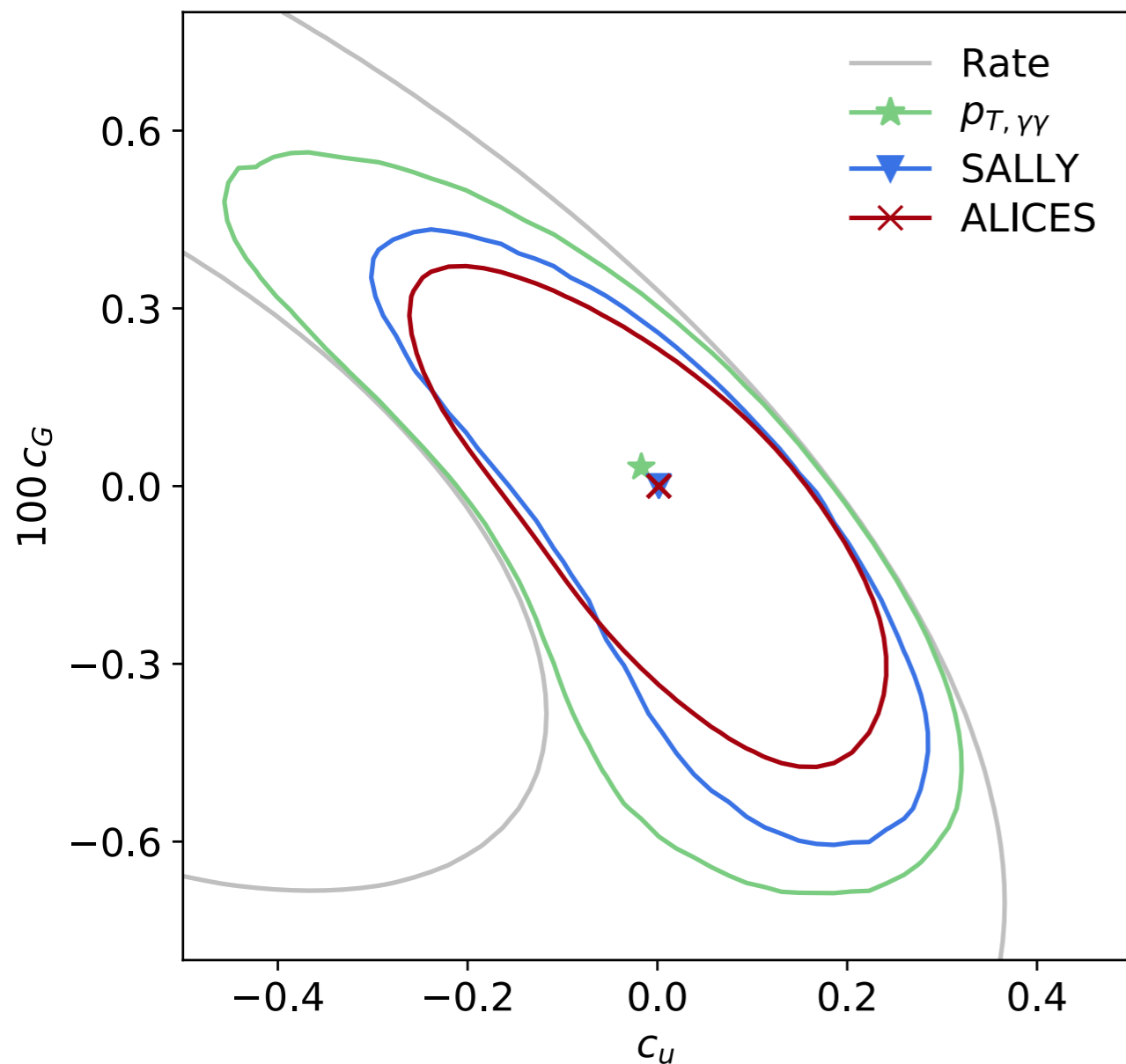
total rate

SALLY: score $t(\mathbf{x})|_{\text{SM}}$ as locally optimal observables

pTH histogram

ALICES: use full $r(\mathbf{x}|\theta)$

- multivariate methods significantly improve reach



Example 2: Probing SMEFT in WH

[Brehmer, Dawson, Homiller, FK, Plehn | 908.06980]

WH production in SMEFT

- process $WH \rightarrow l\nu b\bar{b}$

- 3 operators contribute

$$\tilde{\mathcal{O}}_{HD} = (\phi^\dagger \phi) \square (\phi^\dagger \phi) - \frac{1}{4} (\phi^\dagger D^\mu \phi)^* (\phi^\dagger D_\mu \phi)$$

$$\mathcal{O}_{HW} = \phi^\dagger \phi W_{\mu\nu}^a W^{\mu\nu a}$$

$$\mathcal{O}_{Hq}^{(3)} = (\phi^\dagger \overleftrightarrow{D}_\mu^a \phi) (\bar{Q}_L \sigma^a \gamma^\mu Q_L)$$

- 2 main observables: $p_{T,H}$ and $m_{T,tot}$

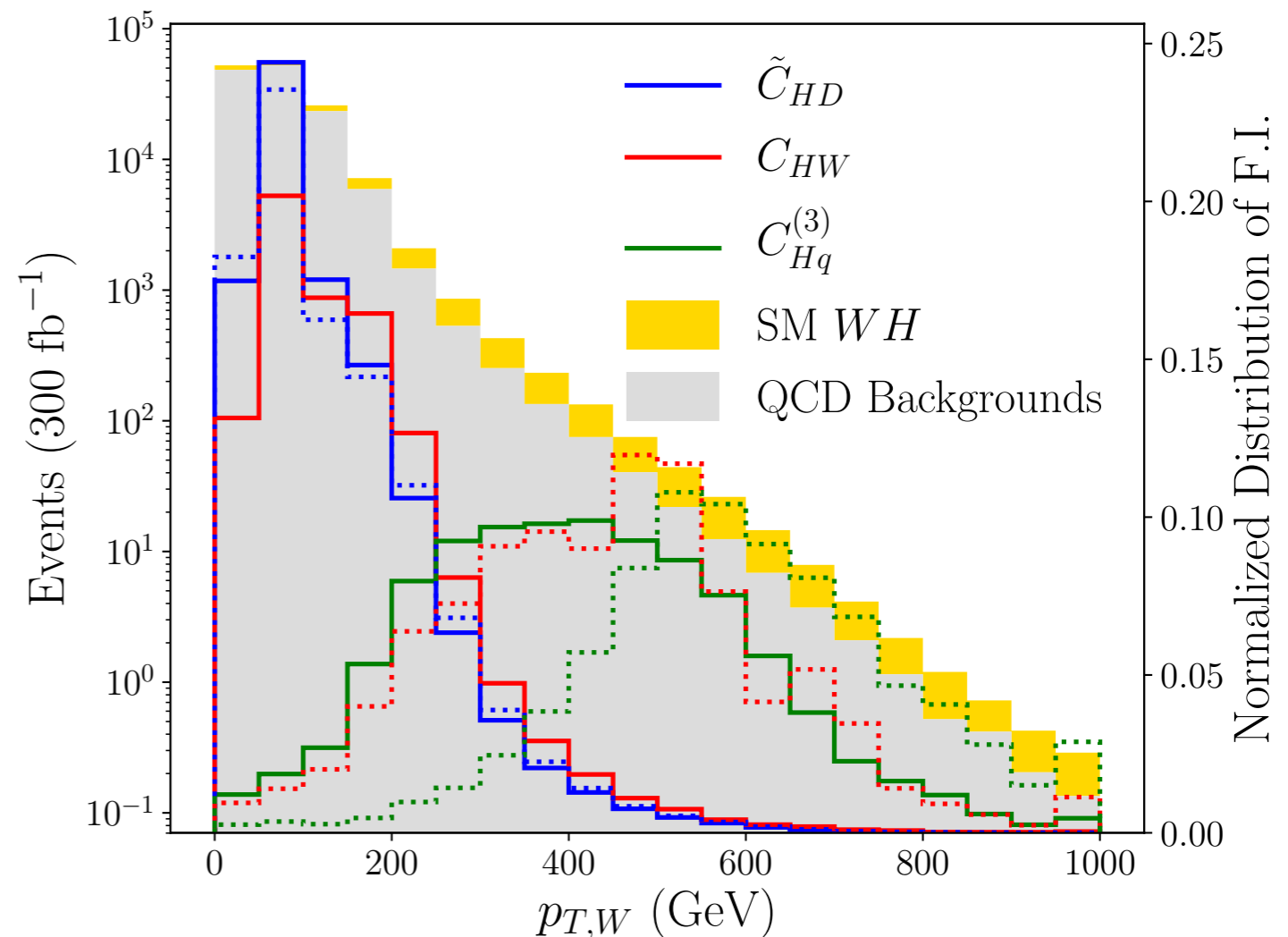
- where is the information

* identify sensitive phase space regions

Distribution of Information:

— interference term

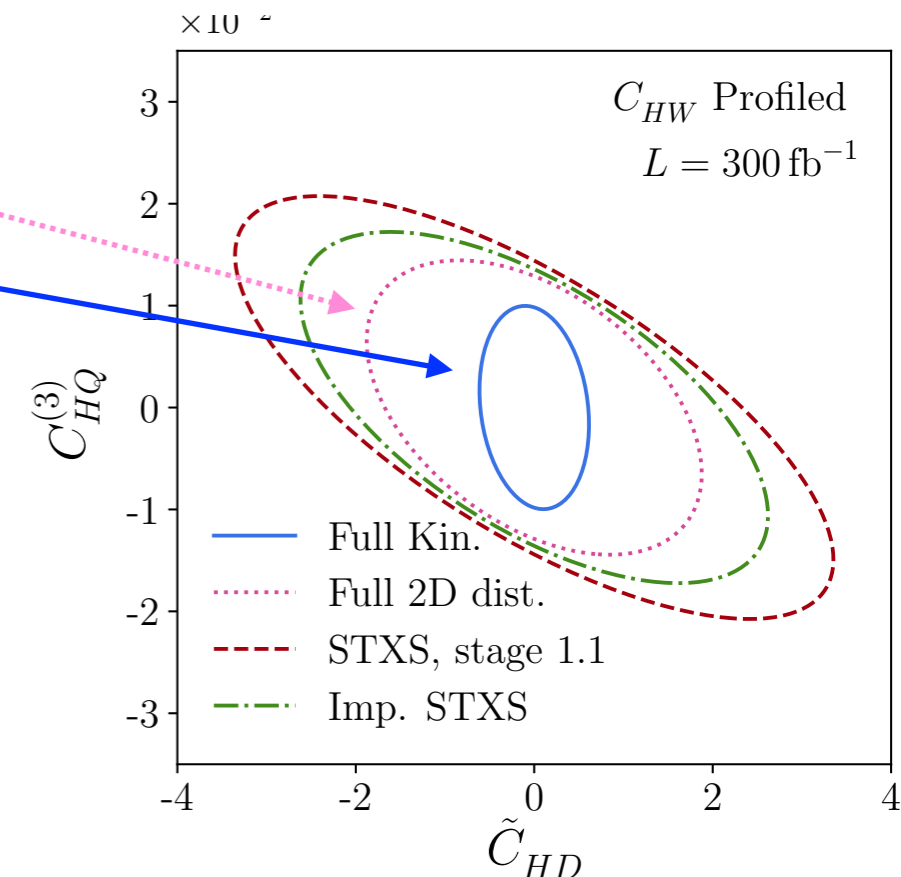
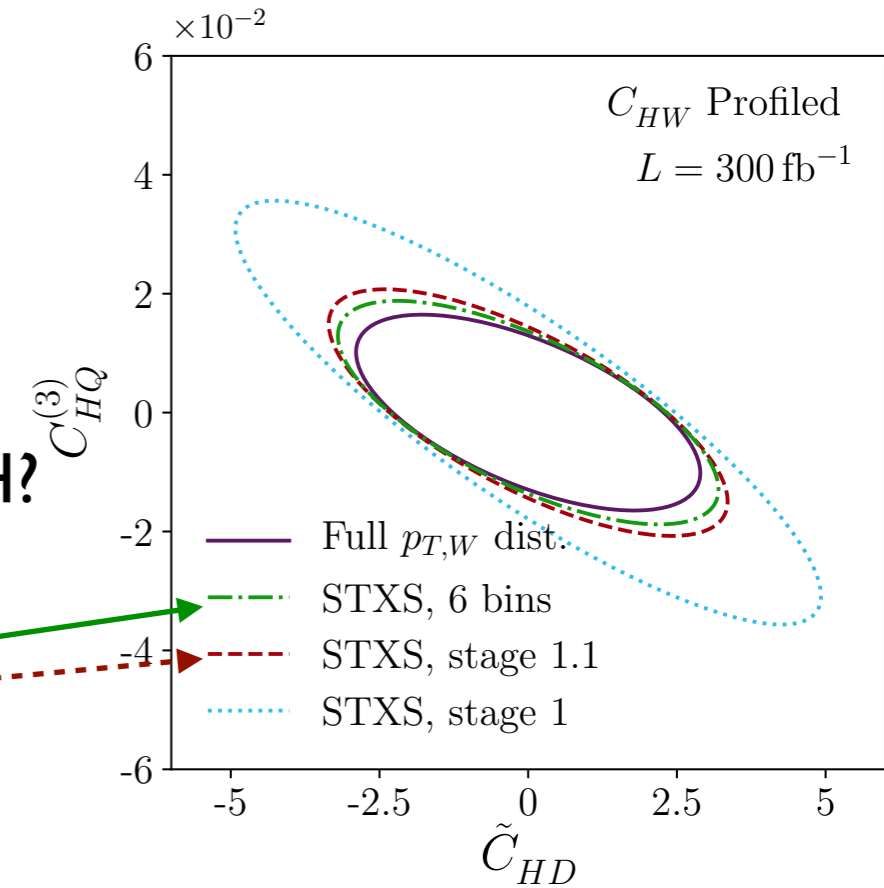
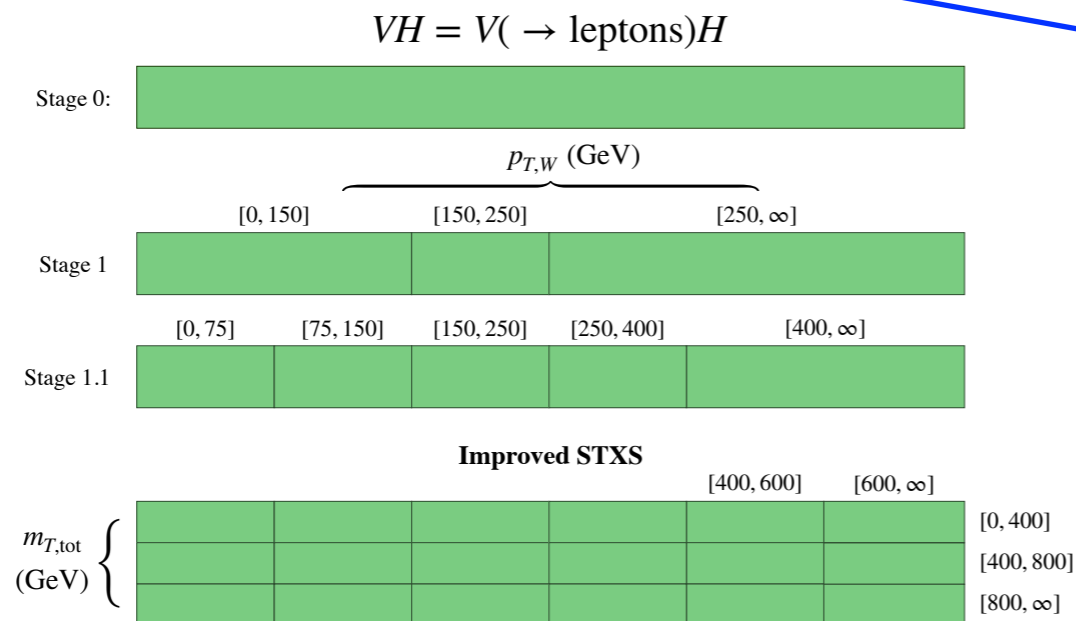
---- quadratic term



Example 2: Probing SMEFT in WH

Another example: WH production in SMEFT

- process $WH \rightarrow l\nu b\bar{b}$
- 3 operators contribute
- 2 main observables: $p_{T,H}$ and $m_{T,tot}$
- how good can simplified template cross sections probe WH?
 - * quantify performance using information geometry
 - * compare to full information
 - * additional high p_T bin essential
 - * include 2nd observable
 - * multivariate analysis potentially much more powerful



Outline

Some Statistic Concepts

Likelihoods, Optimal Observables and Fisher Information

Information Geometry in Theory

Parton Level and Matrix Elements

Information Geometry in Reality

Detector Effects and Machine Learning

Summary and Conclusion

Summary and Conclusion

Theory in an Era of Data

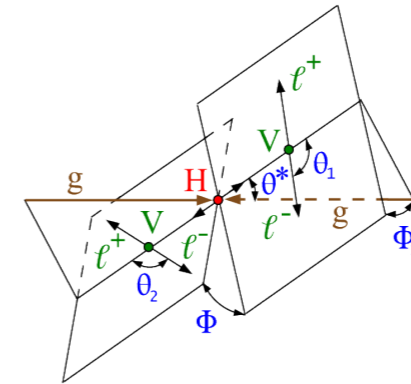
- lots of data, kinematic features
- goal: constrain high-dimension theory space

Information Geometry

- fisher information encodes the maximum sensitivity of observables to model parameters
- calculate maximum sensitivity
- identify important phase space regions
- identify most powerful observables
- quantitatively compare analyses
- include systematics
- powerful and transparent analysis tool
- particularly easy to apply to EFT

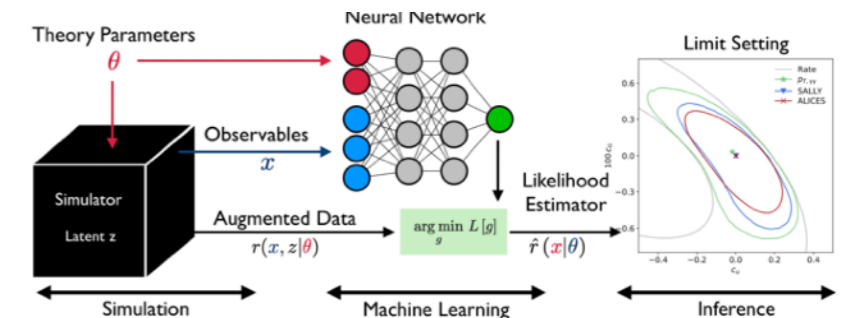
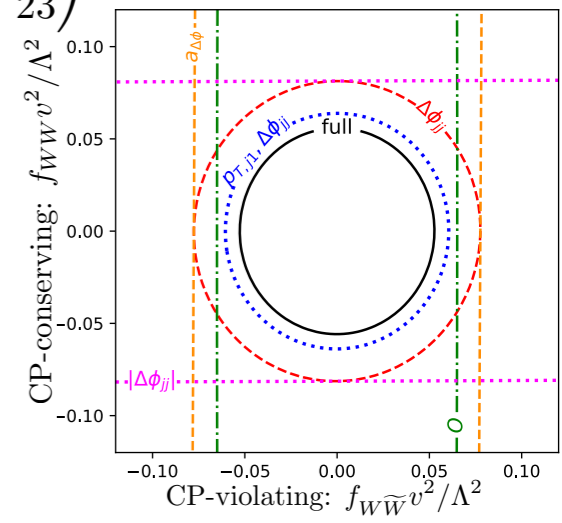
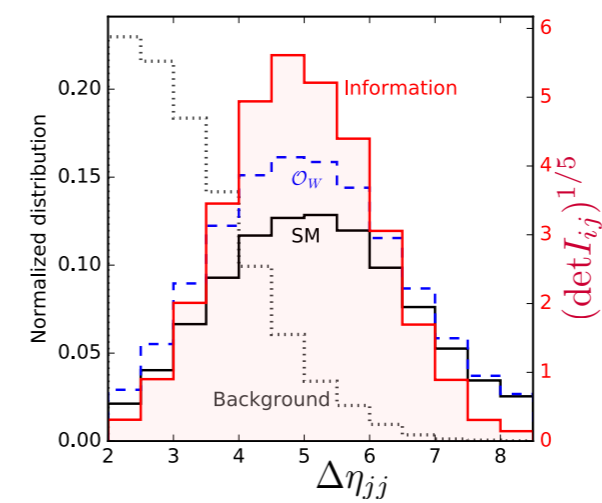
MadMiner

- new inference techniques using ME and ML
- allows to apply information geometry at detector level
- MadGraph add-on / python package
- great for Pheno studies



$$\Delta\mathcal{L}_{SILH} = \frac{\bar{c}_H}{2v^2} \partial^\mu (H^\dagger H) \partial_\mu (H^\dagger H) + \frac{\bar{c}_T}{2v^2} (H^\dagger \overleftrightarrow{D}^\mu H) (H^\dagger \overleftrightarrow{D}_\mu H) - \frac{\bar{c}_\Lambda}{v^2} (H^\dagger H)^3 + \left(\frac{\bar{c}_u}{v^2} y_u H^\dagger H \bar{q}_L H^c u_R + \frac{\bar{c}_d}{v^2} y_d H^\dagger H \bar{q}_L H d_R + \frac{\bar{c}_l}{v^2} y_l H^\dagger H \bar{L}_L H l_R \right) + \text{h.c.} + \frac{i\bar{c}_{Wg}}{2m_W^2} (H^\dagger \sigma^i \overleftrightarrow{D}^\mu H) (D^\nu W_{\mu\nu})^i + \frac{i\bar{c}_{B\gamma}}{2m_W^2} (H^\dagger \overleftrightarrow{D}^\mu H) (\partial^\nu B_{\mu\nu}) + \frac{i\bar{c}_{HWg}}{m_W^2} (D^\mu H)^\dagger \sigma^i (D^\nu H) W_{\mu\nu}^i + \frac{i\bar{c}_{HB\gamma}}{m_W^2} (D^\mu H)^\dagger (D^\nu H) B_{\mu\nu} + \frac{\bar{c}_g}{m_W^2} H^\dagger H B_{\mu\nu} B^{\mu\nu} + \frac{\bar{c}_a}{m_W^2} H^\dagger H G_{\mu\nu}^a G^{\mu\nu}$$

$$I_{ij}(0) = \begin{pmatrix} 715 & -191 & 1 & 0 \\ -191 & 321 & -1 & 0 \\ 1 & -1 & 359 & -81 \\ 0 & 1 & -81 & 23 \end{pmatrix}$$



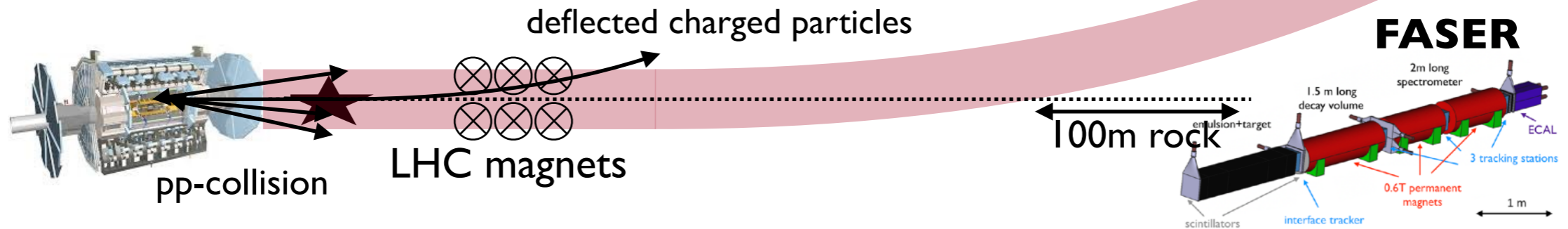
Outline

Backup

Cool stuff that didn't make it into the main part

Completely Independent: FASERv

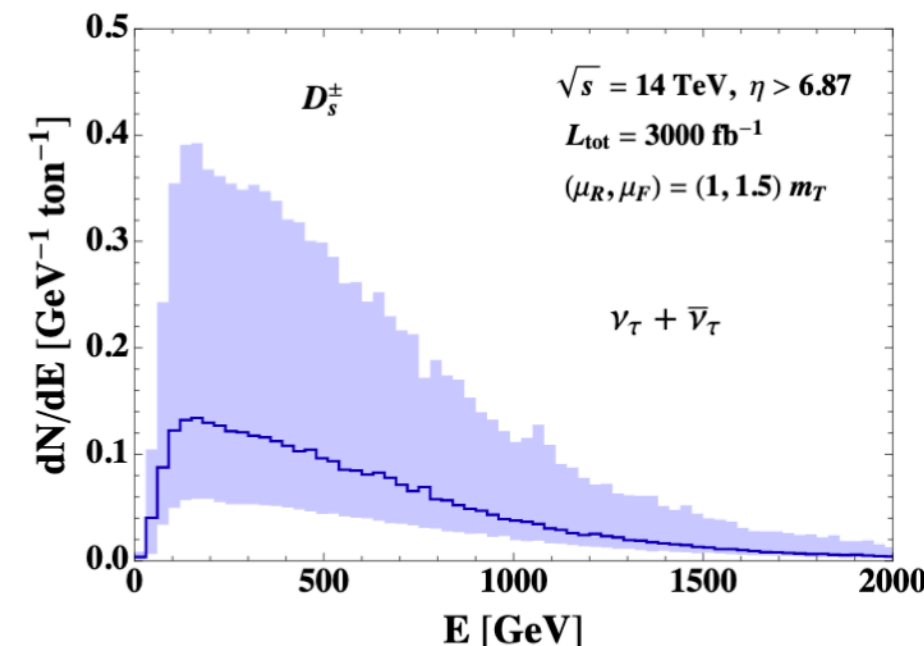
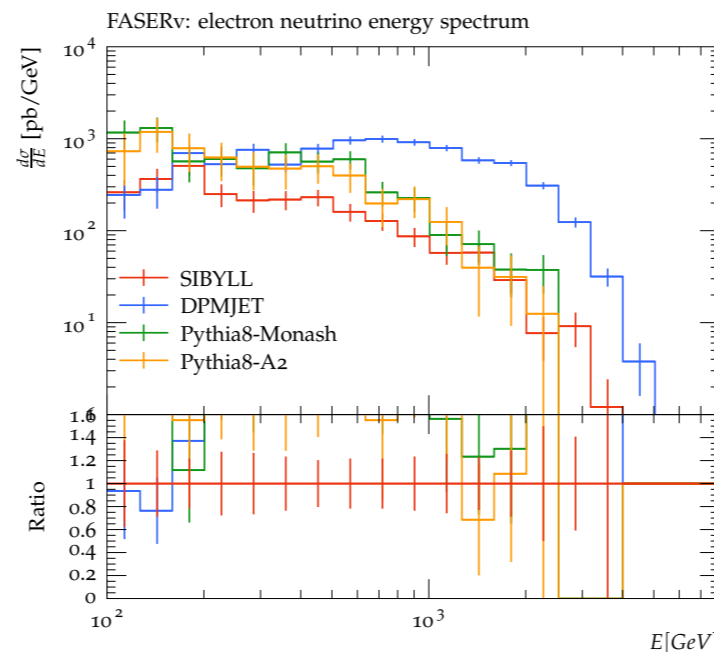
- the recently approved FASERv detector will detect for forward LHC neutrinos
 - * neutrinos from pions, kaon and D-meson decay
 - * proposal: [1908.02310](#) and [2001.03073](#), operation during LHC Run3
 - * covers pseudo rapidity > 9 , energy \sim TeV



- main physics goal: neutrino cross section at TeV energies
- currently large uncertainties on forward charm production
 - * generators not yet tuned, differ by up to factor 10 \rightarrow forward physics tune in progress
 - * NLO QCD calculation has $O(1)$ uncertainties as well: [2002.03012](#)

- physics sensitivity ?
 - * PDFs at low x, Q^2 ?
 - * intrinsic charm ?

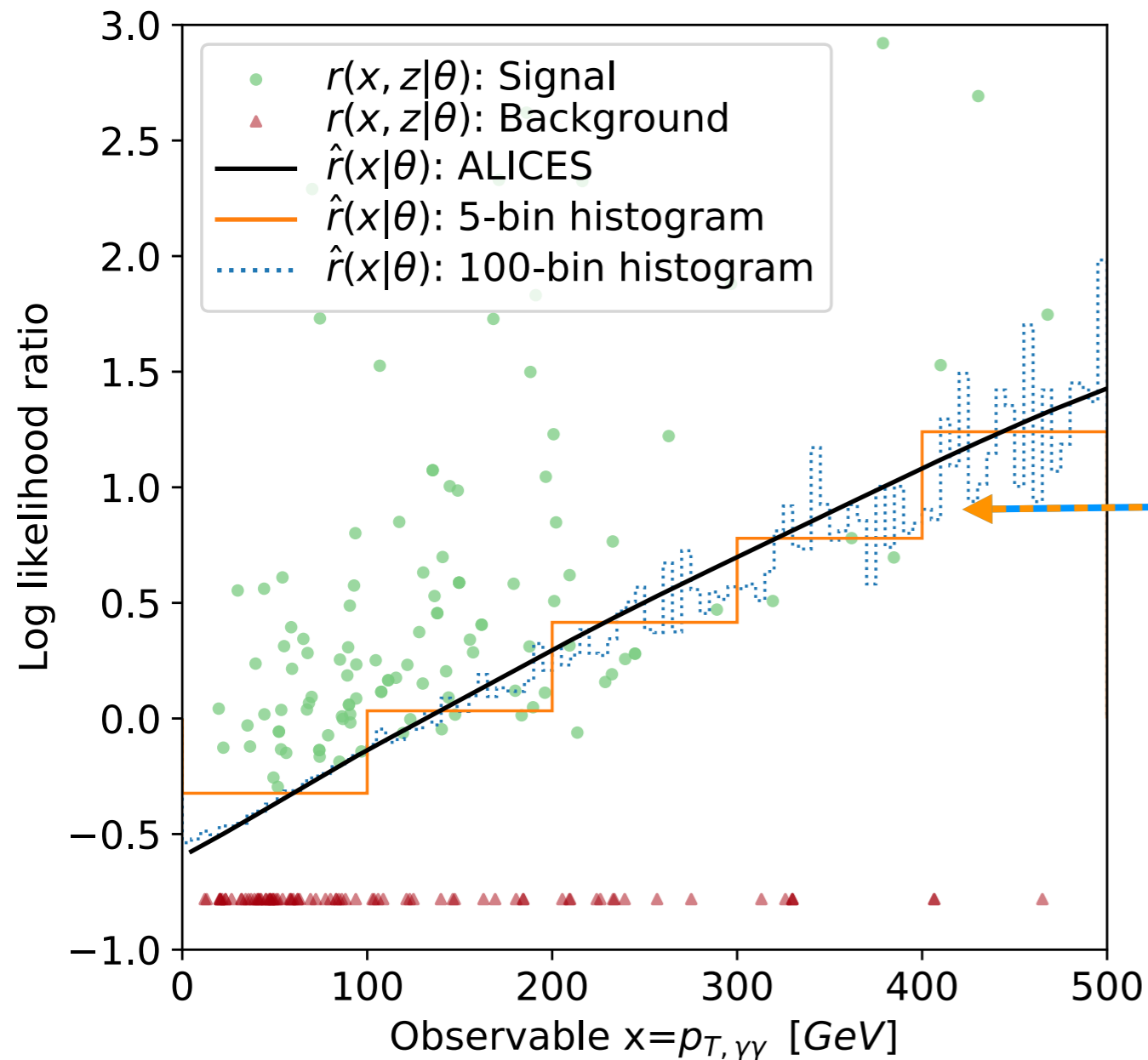
Suggestions, feedback, help and ideas are welcome!



MadMiner with Backgrounds

How about Backgrounds?

- consider two models: BSM ($\theta=1$) vs SM ($\theta_{\text{ref}}=0$)
- include ttH signal and $tt\gamma\gamma$ background



- additional latent variable z : process label

- points: joint likelihood ratio

estimate $r(x, \theta)$: “best fit”

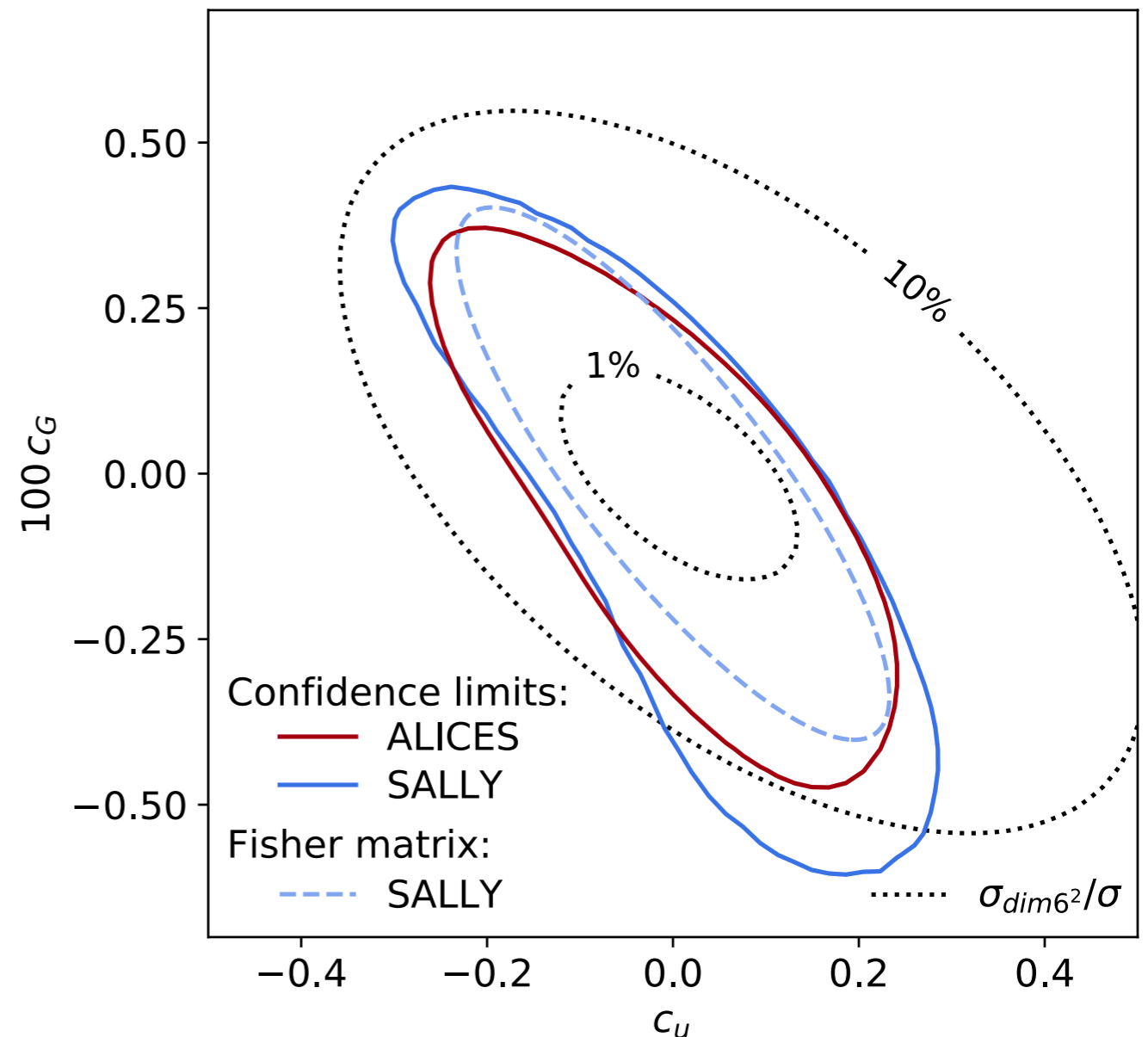
Comparison with Histogram

- LLR obtained using histogram
 - agrees well :)
 - ML “continuum limit of for large # of bins”
-
- realistic problem: x and θ high dimensional

Probing SMEFT in $t\bar{t}$

How good is local approximation?

- Fisher Information matrix
 - * estimate
 - * only sensitive to interference effects by construction
 - * symmetric limits (ellipses)
- SALLY
 - * estimates score $t(x)|_{SM}$
 - * use score as optimal observable (filled in histograms)
 - * optimal only close to SM
- ALICES:
 - * estimate $r(x|\theta)$
 - * optimal limits in whole parameter space
- this example analysis:
 - * few data, weak constraints
 - * dim6 squared terms important in probed parameter space
 - * local / full limits differ



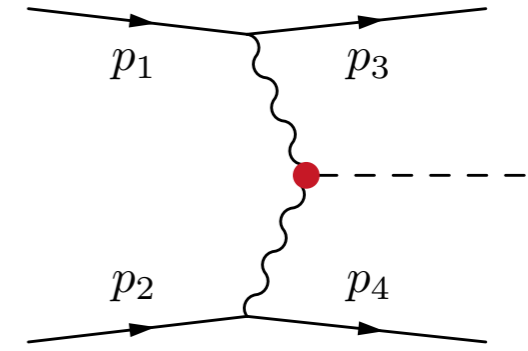
CP in WBF

Why is WBF Higgs production sensitive to CP?

- naive time reversal $\hat{T} : |\vec{p}, \vec{s}\rangle \rightarrow |-\vec{p}, -\vec{s}\rangle$
- \hat{T} -symmetric initial state at pp-collider
- \hat{T} -invariant squared matrix element in absence of CP-violation and re-scattering

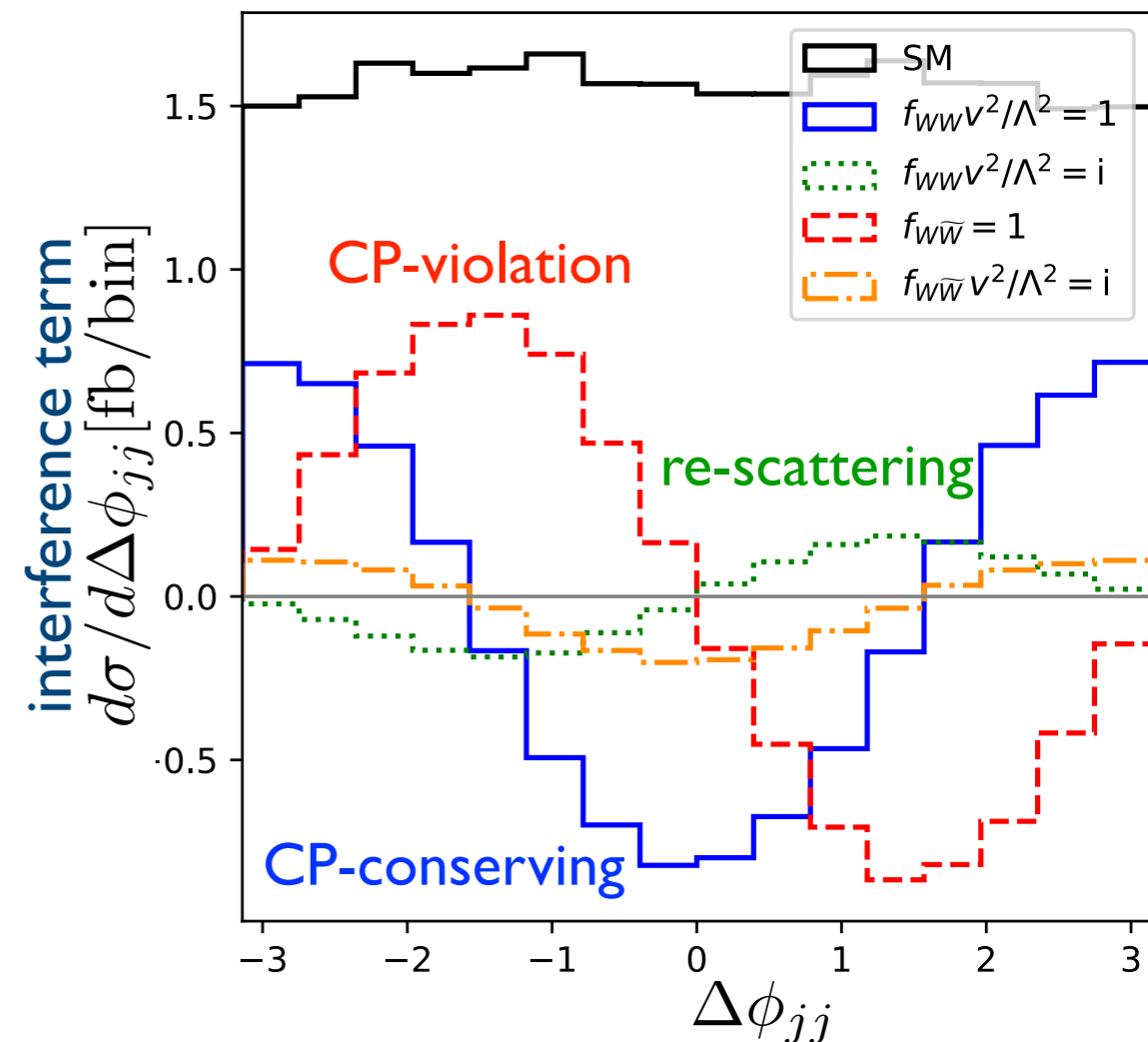
$$\langle f | \mathcal{T} | i \rangle \stackrel{\text{CPT-theorem}}{=} \langle i_T | \mathcal{T} | f_T \rangle \stackrel{\text{no re-scattering}}{=} \langle f_T | \mathcal{T} | i_T \rangle^* \Rightarrow |\langle f | \mathcal{T} | i \rangle|^2 = |\langle f_T | \mathcal{T} | i_T \rangle|^2$$

- genuine \hat{T} -odd observable $\epsilon_{\alpha\beta\gamma\delta} p_1^\alpha p_2^\beta p_3^\gamma p_4^\delta$
- signed angle $\Delta\phi_{jj}^s$



$\Delta\phi_{jj}^s$ is sensitive to CP-violation

if re-scattering effects are known to be small



Summary: Inference Techniques

Traditional

- use summary statistics
 - * hand-picked observables x'
 - * estimate $p(x'|\theta)$
- information loss
- problem dependent

Examples:

- rate only (cut and count)
- histograms
- Approximate Bayesian Computation
- STXS

Machine Learning

- multivariate analysis
- works great for S vs BG
- struggles with S' vs S
 - * large number of S'
 - * very similar S', S

Examples:

- Neural Density Estimator
- ML Classifier

Matrix Element Based

- multivariate analysis
- uses $p(x|\theta) \sim |M(x|\theta)|^2$
- works great at parton level
 - * S' vs S is easy
- requires approximations in reality
 - * S vs BG can be hard

Examples:

- Matrix Element Method
- Optimal Observables

power of
machine learning

physics insight of
matrix element information

MadMiner

[J. Brehmer, K. Cranmer, G. Louppe, J. Pavez 1805.00013, 1805.00020, 1805.12244]

[J. Brehmer, FK, I. Espejo, K. Cranmer 1907.10621]

Deployment: <https://github.com/epjordan/madminer>