## **CLASSICAL OBSERVABLES AND EFTs OF GRAVITY**





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THE SYSTEM AND THE INTERACTIONS  

$$S = \int d^{4}x \ J - \frac{q}{2} \left( -\frac{2}{K^{2}} \right) \left[ \begin{array}{c} R + \ R^{2} \ torum + \ \frac{\alpha}{\Lambda^{4}} \ R^{3} \ torum - \frac{\beta}{\Lambda^{6}} \ R^{4} \ torum + \dots \end{array} \right]$$

$$BH_{S} \longrightarrow + \frac{1}{2} \sum_{i=1}^{2} \left( q^{MN} \ \partial_{\mu} \ \phi_{i} \ \partial_{\mu} \ \partial_{\mu}$$

(s smatt)

We define the EIKONAL PHASE  $\chi(b,t) = \frac{4}{2(t-m_1^2-m_2^2)} \int \frac{\partial \frac{D-2}{q}}{(2m)^{D-2}} e^{i\vec{q}\cdot\vec{b}} T(-\vec{a}^2,t)$ As Jon as X <<1 and b is large, the tree level is a good approximation of the actual amplitude. BORN APPROXIMATION

In the case 
$$[\mathcal{X} = 1]$$
 it can be indiced that the amplitude EXPONENTIATE:  
 $i T_{eiKonual}(s,t) = \mathcal{L}(t-m_i^2-m_g^2) \int d^{D-2}b e^{-i\vec{q}\cdot\vec{b}'} \left[e^{-i\mathcal{X}(b,t)} - 1\right]$   
and the exponentiation comes from LOOP (CROSSED) LADDER DIAGRAMS,  
 $\frac{1}{2} + \frac{1}{2} + \frac{1$ 

Which is a good approximation for this integral ?  
• the expansion in powers of 
$$\chi$$
 is increasily bradly divergent. Not size  $I$ 

· SADDLEPOINT APPROXIMATION :

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- DEFLECTION ANGLE
- TIME DELAY

## THE KINEMATIC SETUP (IN UD)

$$m_{2} = 0$$

$$C_{ENTRE} \quad o \in M_{ASS} \quad (C_{OH}) \quad FRAME : \vec{p} \cdot \vec{q} = 0$$

$$p_{1}^{M} = -(E_{1}, \vec{p} - \frac{\vec{q}}{2}) \qquad p_{2}^{M} = (E_{1}, \vec{p} + \frac{\vec{q}}{2})$$

$$p_{1}^{M} = -(E_{3}, -\vec{p} - \frac{\vec{q}}{2}) \qquad p_{3}^{M} = (E_{3}, -\vec{p} - \frac{\vec{q}}{2})$$

$$E_{1} = \sqrt{m^{2} + \vec{p}^{2} + \frac{\vec{q}^{2}}{4}} \qquad (S_{2} + (E_{3}, -\vec{p} - \frac{\vec{q}}{2}))$$

$$(S_{3} = \sqrt{p^{2} + \frac{\vec{q}^{2}}{4}} = \omega$$

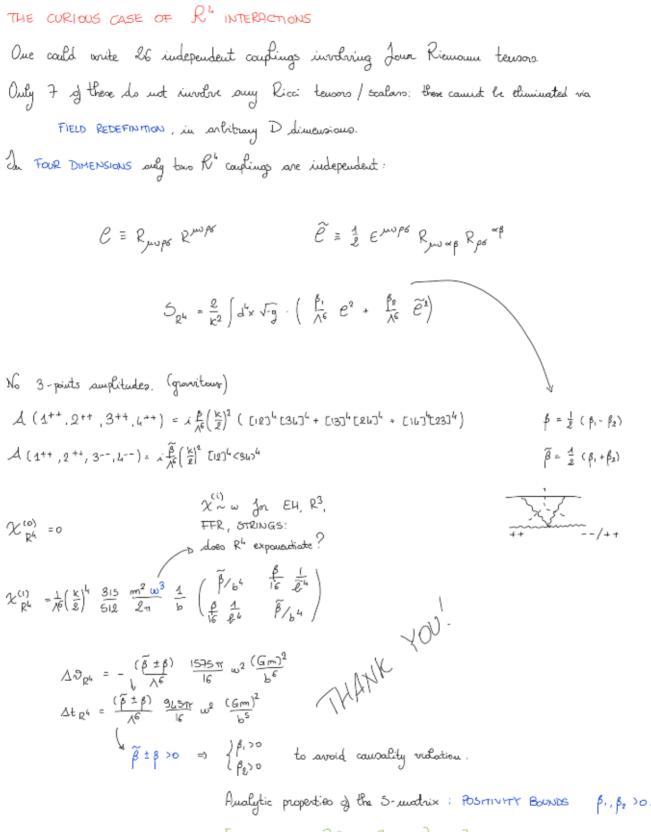
$$E_{1}KONAL \quad LIMIT : m_{2} > \omega > |\vec{q}|$$

Gravitous and protous as external states : we need a parametrisation of the manhen SPINOR HELICITY VARIABLES in the eikonal limit.

We choose 
$$\vec{p} = 1\vec{p} \cdot \hat{z} \implies \vec{q} = q_a \hat{x} + q_k \hat{y}$$
  
 $q = q_s + iq_2, \ \vec{q} = q_k - iq_k$   
 $p_3 \propto \dot{z} = \begin{pmatrix} \vec{q}^2 & - \frac{\vec{q}}{2} \\ \frac{\vec{q}}{2} & 2i\vec{p} \end{pmatrix}$ 

Helicity structures .

$$\begin{split} \lambda_{s} &= \sqrt{110} \left[ -\frac{\lambda_{s}}{2\mu_{s}} , \lambda \right] \qquad \tilde{\lambda}_{s} &= \sqrt{210} \left[ -\frac{\lambda_{s}}{2\mu_{s}} , \lambda \right] \qquad \text{[SUT]}^{2} &= q^{2} \qquad (++) \\ \lambda_{s} &= (\sqrt{210}) \left( \frac{\lambda_{s}}{4\mu_{s}} , \lambda \right) \qquad \tilde{\lambda}_{s} &= (\sqrt{210}) \left( \frac{\lambda_{s}}{4\mu_{s}} , \lambda \right) \qquad \text{Ne} \left( \frac{(3 + h^{2})}{2m^{2}} \right)^{2} &= -3 \qquad (-+) \\ \text{The Elecand Prime Prime Prime Elecand Interpretation for a face facing 12 and 11. \\ &= (\lambda_{s}^{-1} + \lambda_{s}^{-1} + \lambda_{s}^{-1} + \lambda_{s}^{-1} + 1) = \lambda(z_{s}, z) \neq 0 \qquad \text{Here elecand for a substrate f$$



[1503.00851 : Bellazzi, Cheung, Remmen]