



# **HL-LHC BPMs: Status of the Specifications Update July 2020**

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# Discussion between WP13 (BI) and WP2

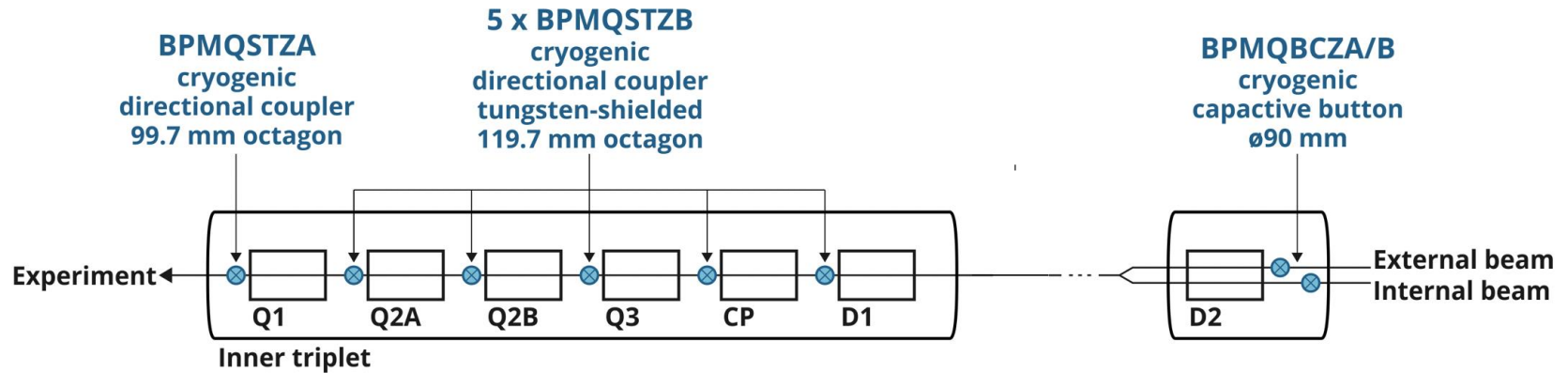
- **A new HL-LHC BPM document was drafted:**
  - **Conceptual BPM Specifications for the HL-LHC**
  - **Current version: 2020-06-02**
  - **Authors: R. De Maria, D. Gamba, R. Tomas**
- **Covering:**
  - **HL-LHC beam parameters**
  - **BPM families**
  - **Measurement modes**
  - **HL-LHC Specifications**

# Beam Parameters

Particle	Bunch charge		# of bunches		Min. bunch spacing [ns]	Bunch length FWHM [ns]	
	min	max	min	max		min	max
Protons	5e9	2.3e11	1	2760	25	0.7	1.2
Ions	5e9	1.6e10	1	1232	50	0.7	1.2
Pilot (p or ions)	5e9	1e10	1	3	(25)	0.7	1.2

- **Doubled bunch (5/20ns) operation was discussed**
  - No doubles bunches are foreseen in future!
  - The HL-BPM and the LHC BPM consolidation projects can assume the double bunches will not be operated in the HL-LHC!
- **Bunch length: FWHM = 4 x sigma?**
  - **To be clarified!**
- **Pilot bunches**
  - Machine setup and optics studies

# BPM Families



Type	Two beams	Operation range (OP) [mm]	Max. range for studies	Bunch spacing [ns]
Arc	no	$\pm 9$	$\pm 18$	25
Matching section	no	$\pm 12$	$\pm 24$	25
Triplet point 2/8	yes	$\pm 14$	$\pm 27$	6
Triplet point 1/5	yes	$\pm 29^\dagger$	$\pm 58^\ddagger$	3.8

$^\dagger$  For BPMQSTZA:  $\pm 25$  mm

$^\ddagger$  For BPMQSTZA:  $\pm 50$  mm

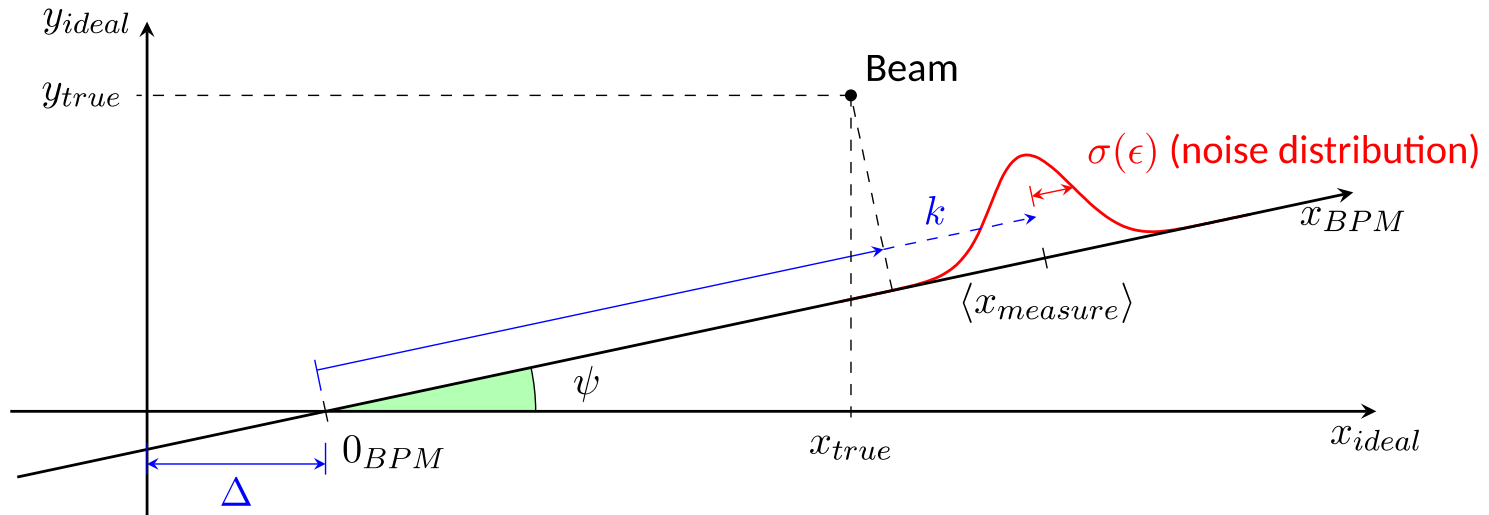
# Measurement Modes

- **Bunch-by-bunch, turn-by-turn for beam orbit Trajectories and oscillations (TR)**
- **High resolution averaged Closed Orbit (CO)**

Reproducibility timescale	Usage	Class
Bunch-by-bunch	Optics measurement and correction, steering at injection	TF
Stable Beam (~10 h)	Keep orbit during optic changes, IP position stabilization	CO
Fill to fill (~24 h)	Find collisions after a refill, ensure machine reproducibility	CO

Measurement	Frequency	Quantity
Orbit mode (CO)	25 Hz	Continuous
Trajectory mode (TR)	~0.1 Hz	1-3 pilots, 20 k turns, on demand

# Errors of a single BPM Measurement



$$|x_{measure} - x_{true}| \leq |\Delta| + |k|X + |\psi|Y + \max_{x \in [-X, X], y \in [-Y, Y]} \left( \sum_{k=2}^{\infty} \sum_{j \leq k} \alpha_{k,j} x_{true}^{k-j} y_{true}^j \right) + 2\sigma(\epsilon)$$

Uncertainties:

$\Delta$ : offset

$k$ : calibration error

$\psi$ : tilt

$\alpha_{k,j}$ : non-linearities

$\epsilon$ : noise

with  $X$  and  $Y$  being the applicable ranges of the measurement

# Long term BPM Measurement Stability

$$x_{\text{measure}}(t) = x_{\text{true}}(t) + x_{\text{error}}(t, I_b, T, \dots)$$

Timescale	Arc and MS BPMs	Triplet BPMs	
		Point 1/5	Point 2/8
Stable beam (~10 h)	$\pm 20 \mu\text{m}$	$\pm 2 \mu\text{m}$	$\pm 10 \mu\text{m}$
Fill to fill (~24 h)	$\pm 28 \mu\text{m}$	$\pm 28 \mu\text{m}$	$\pm 28 \mu\text{m}$

- **Long term stability in orbit mode**
  - For luminosity production runs
  - Assuming a factor 2 between RMS and peak values

# BPM Errors

Goal	Arc BPMs	Triplet BPMs	
		Point 1/5	Point 2/8
Offset	$\pm 100 \mu\text{m}$	$\pm 30 \mu\text{m}$	$\pm 30 \mu\text{m}$
$\langle x_{B1} \rangle - \langle x_{B2} \rangle$	n.a.	$\pm 40 \mu\text{m}$	$\pm 40 \mu\text{m}$
Calibration error ( $k$ )	3 %	6 %	4 %
Noise ( $\varepsilon$ )	$\pm 100 \mu\text{m}$	$\pm 30 \mu\text{m}$	$\pm 100 \mu\text{m}$

- **Offset**
  - Valid for all types of beams
- **B1-B2 accuracy**
  - Position difference for crossing and separation:  $\pm 1 \%$
- **Calibration error**
  - Single pilot bunch between two calibrations



# Specification Summary

Goal	Tolerance LHC	Tolerance HL-LHC
Calibration error	$\pm 4\%$	$\pm 3\%$ (TR, Arc) $\pm 1.6\%$ (TR, P 1/5) $\pm 4\%$ (TR, P 2/8)
Roll	$\pm 2$ mrad (Arc) $\pm 1$ mrad (Triplet)	$\pm 2$ mrad (CO, Arc) $\pm 1$ mrad (CO, P 1/2/5/8)
Offset	$\pm 100\ \mu\text{m}$ (Arc) $\pm 30\ \mu\text{m}$ (Triplet)	$\pm 100\ \mu\text{m}$ (CO, Arc) $\pm 30\ \mu\text{m}$ (CO, P 1/2/5/8)
Non-linearity	$\pm 200\ \mu\text{m}$ over $\pm 4$ mm (CO) $\pm 500\ \mu\text{m}$ over OP range (CO)	$\pm 200\ \mu\text{m}$ over $\pm 4$ mm (TR tbc) $\pm 500\ \mu\text{m}$ over OP range (TR tbc)
$2 \times \text{Std}(x_{error})$	$\pm 20\ \mu\text{m}$ (CO, Arc) $\pm 10\ \mu\text{m}$ (CO, Triplet)	$\pm 20\ \mu\text{m}$ (CO, 10 h, Arc) $\pm 10\ \mu\text{m}$ (CO, 10 h, P 2/8) $\pm 2\ \mu\text{m}$ (CO, 10 h, P 1/5) $\pm 28\ \mu\text{m}$ (CO, 24 h, Arc) $\pm 28\ \mu\text{m}$ (CO, 24 h, P 1/2/5/8)
$\langle B1 \rangle - \langle B2 \rangle$	$\pm 30\ \mu\text{m}$ (CO, Triplet)	$\pm 40\ \mu\text{m}$ (CO, P 1/2/5/8)
Noise	n.a.	$\pm 100\ \mu\text{m}$ (TR, Arc) $\pm 100\ \mu\text{m}$ (TR, P 2/8) $\pm 30\ \mu\text{m}$ (TR, P 1/5)
Resolution	$\pm 50\ \mu\text{m}$ (TR)  $\pm 5\ \mu\text{m}$ (CO)	$\pm 50\ \mu\text{m}$ (TR, Arc) $\pm 15\ \mu\text{m}$ (TR, P 1/5) $\pm 5\ \mu\text{m}$ (CO, Arc) $\pm 1\ \mu\text{m}$ (CO, P 1/2/5/8)

# Discussion

- **Thanks to WP2 (APB and CO) for providing detailed BPM specifications!**
- **Some difficult to be achieve specifications may need follow up discussion, e.g.**
  - **Long term accuracy P 1/5**
  - **Bunch-by-bunch resolution pilot bunch**
  - **Maximum operation range P 1/2/5/8 BPMs**
  - **Bunch length**
- **Some discussion has already started, e.g.**
  - **Difference noise vs. resolution**
  - **BPM offsets**