

Background/Motivation

- Early gyrokinetic PIC codes adopted explicit δf as the main scheme
- **Full f implicit scheme** enables studies of specific physics problems
 - Particle/heat/momentum source and sink; arbitrary distributions
 - Significant profile change during simulation (flux driven simulations)
 - (Semi) implicit scheme or/and full f scheme have attracted numerous efforts [GK5D, GENE; EUTERPE&ORB5, GEMPIC, ELMFIRE, XGC, ECSIM ...]
- Implicit scheme: good in conservation properties, large Δt but
 - For a system with N_G field grids and N_p particles, the computational cost is too high: $\text{DOF} = N_G + N_p$; matrix size is $(N_G + N_p)^2$.
 - Solution: “particle enslavement” [Chen&Chacon, J. Comput. Phys. 230 (2011) 7018]
 - Particles (x, v) represented as functions of field $F(x) \rightarrow \text{DOF reduced to } N_G$
 - Open issue: efficient convergence of the implicit particle-field system
 - XGC: preconditioned Picard iteration (numerical); δf [Sturdevant 2021POP]
 - Our work: analytical treatment of the iteration scheme (rigorous); full f
- The development of the implicit kinetic full f scheme for Alfvén wave/energetic particle physics has not been reported

Physics model & implementation

Shear Alfvén wave in 1D uniform plasma

- Ampere's law: $\nabla_{\perp}^2 \delta A_{\parallel} = C_A \delta J_{\parallel}$
- Quasi-neutrality (QN): $\nabla_{\perp} \cdot \left(\frac{B_0^2}{B^2} \nabla_{\perp} \delta \phi \right) = C_p \delta N$
 - $C_A = \beta / \rho_{te}^2$, $C_p = \frac{1}{\rho_{te}^2}$
 - **Ion polarization density** balances electron δN in QN Eq (dominant)
- Parallel electron motion:
 - $\frac{dl}{dt} = v_{\parallel}$; l : parallel coordinate
 - $\frac{dv_{\parallel}}{dt} = \partial_{\parallel} \delta \phi + \partial_t \delta A_{\parallel}$ $\beta = v_{te}^2 / v_A^2$
- Analytical dispersion relation: v_{te}, v_A : thermal, Alfvén velocities, $\bar{\omega} = \omega / \omega_{te}$, $\omega_{te} = v_{te} k_{\parallel}$

$$1 - \frac{2\beta[1 + \bar{\omega}Z(\bar{\omega})]}{M_e(k_{\perp} \rho_{te})^2} \left(\bar{\omega}^2 - \frac{M_e}{\beta} \right) = 0.$$

Crank-Nicolson (C-N) scheme (implicit)

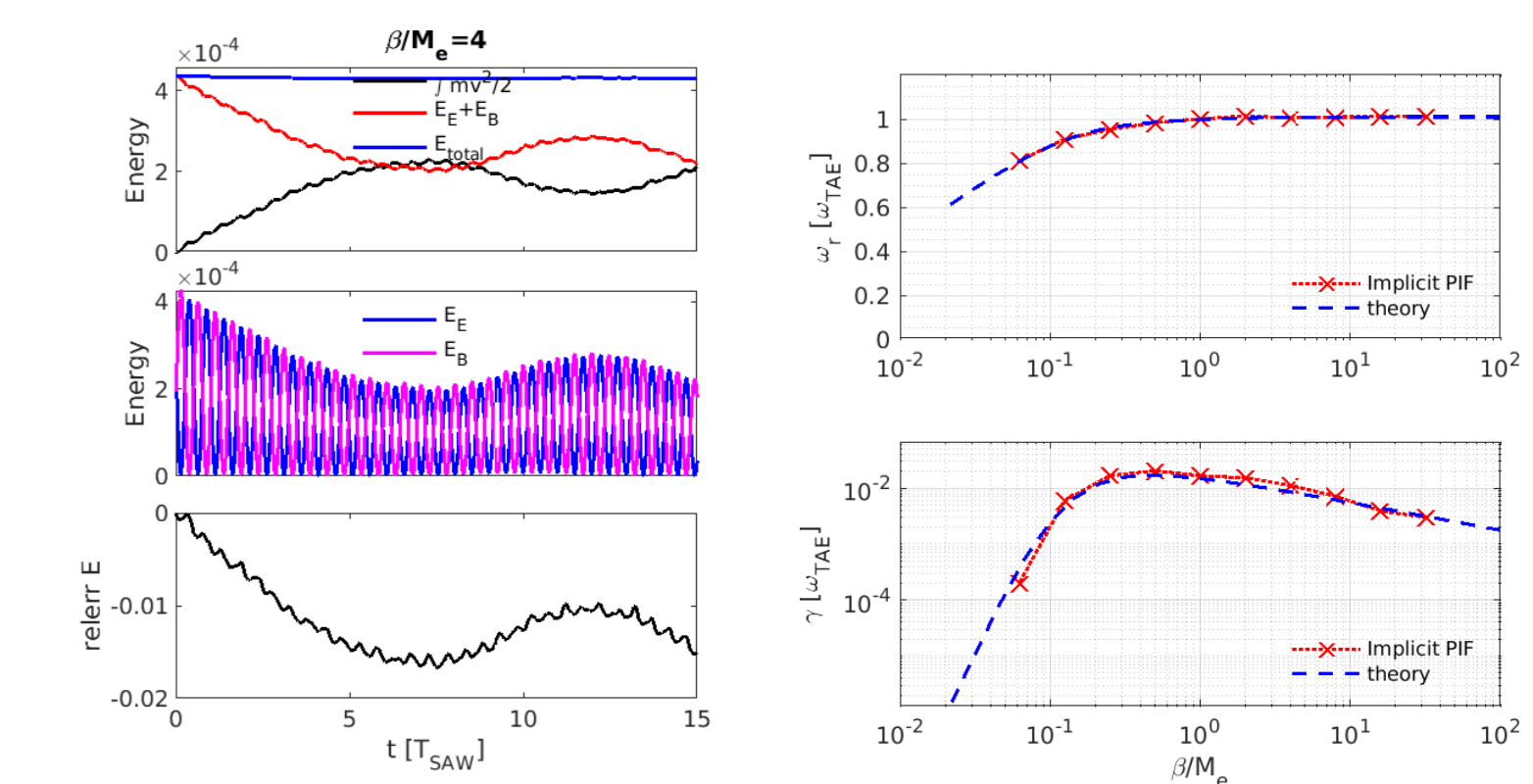
- $$\frac{l^{t+\Delta t} - l^t}{\Delta t} = \frac{v_{\parallel}^{t+\Delta t} + v_{\parallel}^t}{2}$$
- $$\frac{v_{\parallel}^{t+\Delta t} - v_{\parallel}^t}{\Delta t} = \partial_{\parallel} \frac{\delta \phi^{t+\Delta t} + \delta \phi^t}{2} + \frac{\delta A_{\parallel}^{t+\Delta t} - \delta A_{\parallel}^t}{\Delta t}$$
- $$\nabla_{\perp}^2 \delta A_{\parallel}^{t+\Delta t} = C_A \delta J_{\parallel}^{t+\Delta t}$$
- $$\nabla_{\perp} \cdot \left(\frac{B_0^2}{B^2} \nabla_{\perp} \delta \phi^{t+\Delta t} \right) = C_p \delta N^{t+\Delta t}$$
- Total Degree of Freedom: $(N_G + N_p)$
 - First simplification using “particle enslavement”: $(l, v_{\parallel})^{t+\Delta t}$ written as functions of $(\delta \phi, \delta A_{\parallel})^{t+\Delta t}$; then DOF reduced to N_G [Chen&Chacon JCP 2011]
 - Second simplification: “moment enslavement” developed in this work
 - DOF ($> 10^5$) in TRIMEG is large; aiming for low cost

1D Shear Alfvén wave simulations

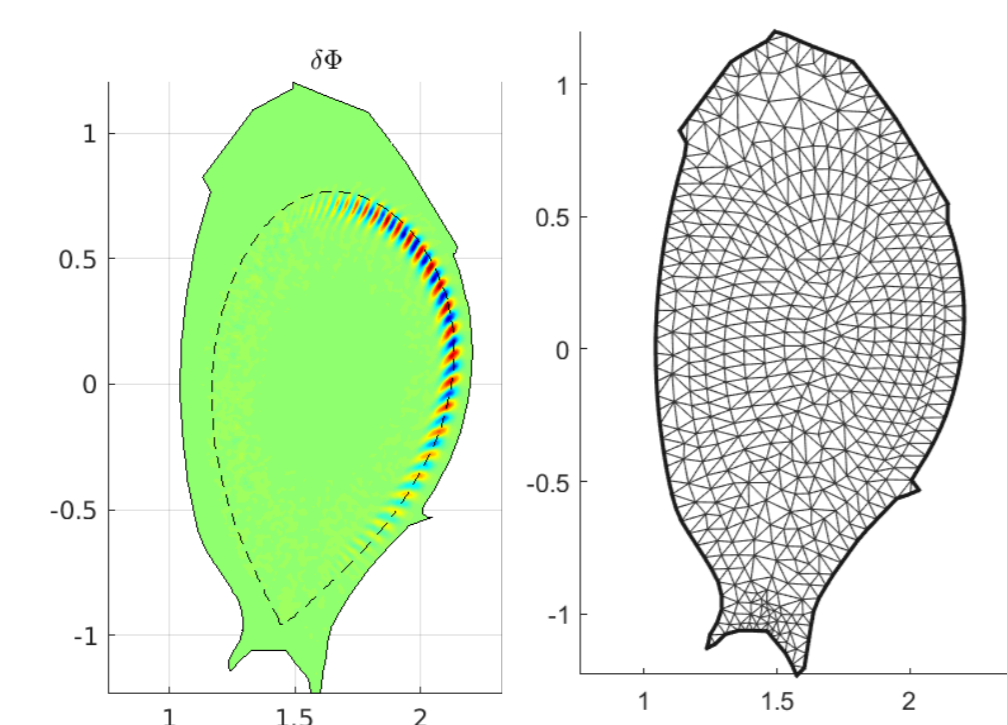
The implicit scheme is capable of simulating SAW in a broad range of $\frac{\beta}{m_e}$

- The relative error in total energy is bounded (< 0.02)
- Damping rate and real frequency properly simulated

- $k_{\perp} \rho_N = 0.2$, $\beta / M_e \in [1/16, 32]$, marker #: 10^5 , $dt = 0.01 T_{SAW}$
- Parameters relevant to tokamak plasmas, $\beta = 1\%$, $M_e = \frac{1}{1836}$
- Using implicit scheme, SAW is simulated
- For high β / M_e , more iterations needed for convergence
- The challenge in high β / M_e corresponds to “cancellation” problem in p_{\parallel} formula.

From ES δf to EM full f TRIMEG

TRIMEG: TRIangular MESH based Gyrokinetic code

ITG simulation near separatrix, ES δf [Lu19POP]

TRIMEG(before 2020)

- δf , electrostatic, explicit
- Unstructured mesh
- Adiabatic electrons

[Lu et al, POP2019]

TRIMEG(since 2020)

- Full f, electromagnetic, implicit
- Structured mesh
- EM unstructured will be reported elsewhere

[Lu et al, JCP2021]

Conclusions

- The implicit scheme has been implemented for the full f electromagnetic simulations of Alfvén waves and EP physics.
- Using the analytical derivation based implicit scheme “moment enslavement”, good convergence of the field-particle solver is achieved
- By applying to the 1D shear Alfvén wave problem, this implicit scheme shows good energy conservation and capabilities of calculating the frequency and damping rate properly in a broad range of β / M_e values, including the small electron mass condition
- The application of this method to the TAE problem shows its applicability for electromagnetic simulations with/without EPs. The TAE mode structure distortion due to the non-perturbative effects of the EPs is observed, consistent with previous simulations and theoretical studies

[1] [Z.X. Lu, Ph. Lauber, T. Hayward-Schneider, A. Bottino, M. Hoelzl, Phys. Plasmas, 26, 122503 (2019)]

[2] Lu, Meng, Hoelzl, Lauber, Journal Comput. Phys. 440 (2021) 110384

Particle & moment enslavement

Workflow of the implicit particle-field solver

- Iterations start with an explicit solution at $i=1$, aiming for solution to C-N scheme.

$$\left\{ \begin{array}{l} \delta \phi^{start, i} \\ \delta A_{\parallel}^{start, i} \end{array} \right\} \rightarrow \left\{ \begin{array}{l} \delta N^{start, i} \\ v_{\parallel}^{start, i} \end{array} \right\} \rightarrow \left\{ \begin{array}{l} \delta \phi^{end, i} \\ \delta A_{\parallel}^{end, i} \end{array} \right\} \rightarrow \left\{ \begin{array}{l} \delta \phi^{start, i+1} \\ \delta A_{\parallel}^{start, i+1} \end{array} \right\}; \text{ all variables are at } t + \Delta t \quad i: \text{ iteration \#}$$

1. Each iteration starts with the given field $\{F^{start}(t + \Delta t)\}^i$, where $F \equiv \{\delta \phi, \delta A_{\parallel}\}$
2. Push particles implicitly from t to $t + \Delta t$
3. In the end of each iteration, fields $\{F^{end}(t + \Delta t)\}^i$ are solved
4. Set $\{F^{start}(t + \Delta t)\}^{i+1}$ so that $|\{F^{start}(t + \Delta t)\}^{i+1} - \{F^{end}(t + \Delta t)\}^{i+1}| \rightarrow 0$ in the next iteration

Step 4: good estimate of the field for next iteration $\{F^{start}(t + \Delta t)\}^{i+1}$: key of good convergence

Analytic treatment in iteration: “moment enslavement”:

- Particle enslavement: $l = l(\delta \phi, \delta A_{\parallel})$, $v_{\parallel} = v_{\parallel}(\delta \phi, \delta A_{\parallel})$, at $t + \Delta t$
 - $(N_G + N_p)^2$ matrix inversion: unacceptable \rightarrow “particle enslavement” [Chen&Chacon 2011]
- Moment enslavement: $\delta N^{end} = \delta N^{end}(l, v_{\parallel}) = \delta N^{end}(\delta \phi, \delta A_{\parallel})$, at $t + \Delta t$

Step 4: analytic form for $\{F^{start}\}^{i+1}$: $\{\delta \phi^{start}, \delta A_{\parallel}^{start}\}^{i+1} = \{\delta \phi^{end}, \delta A_{\parallel}^{end}\}^i + \{\Delta \delta \phi, \Delta \delta A_{\parallel}\}$, with

$$\left[\begin{array}{cc} \frac{1}{C_p} \nabla_{\perp}^2 & 0 \\ 0 & \frac{1}{C_A} \nabla_{\perp} \cdot \left(\frac{B_0^2}{B^2} \nabla_{\perp} \right) - \bar{M}_c \end{array} \right] \cdot \left[\begin{array}{c} \Delta \delta \phi \\ \Delta \delta A_{\parallel} \end{array} \right] = \left[\begin{array}{c} \delta N^{end} - \delta N^{start} \\ \delta J^{end} - \delta J^{start} \end{array} \right]^i, \quad \bar{M}_c = \left[\begin{array}{cc} \frac{\partial \delta N^{end}}{\partial \delta \phi} & \frac{\partial \delta N^{end}}{\partial \delta A_{\parallel}} \\ \frac{\partial \delta J^{end}}{\partial \delta \phi} & \frac{\partial \delta J^{end}}{\partial \delta A_{\parallel}} \end{array} \right] \approx \left[\begin{array}{cc} \frac{k_{\parallel}^2 \Delta t^2}{4M_e} & -\frac{k_{\parallel} \Delta t}{2M_e} \\ \frac{k_{\parallel} \Delta t}{2M_e} & \frac{1}{M_e} \end{array} \right]$$

- \bar{M}_c obtained analytically; rigorous form can be readily obtained
- Numerical calculation of \bar{M}_c , cost: $(\alpha N_G \times N_p / \text{cell})$: not cheap; complicated in implementation
- Analytic acceleration here, cost: N_G , i.e., “moment enslavement”

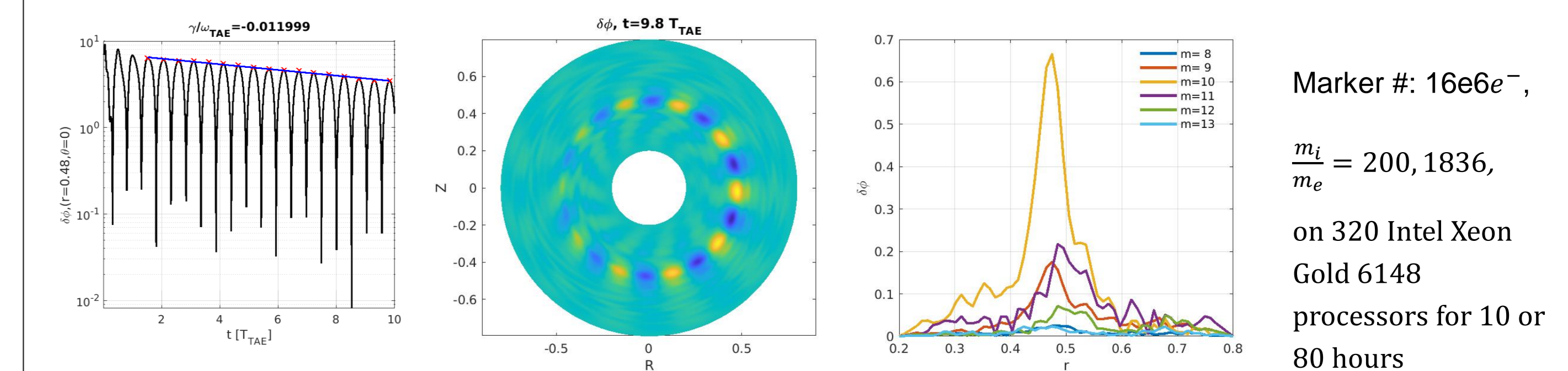
Another way: push particles and calculate \bar{M}_c ; more expensive by a factor of $\alpha N_p / \text{cell}$, $\alpha > 1$.

Simulation of TAE damping and excitation in torus

Simulation of TAE/EP using ITPA parameters [Könies et al Nucl. Fusion 58 (2018) 126027]

- $R_0 = 10m$, $a = 1m$, $q = 1.71 + 0.16r^2$, $B_0 = 3T$; $T_{i,e} = 1keV$, $n_e = n_i = 2 \cdot 10^{19} / m^3$
- EP density: $n(r) = n_{f0} c_3 \exp\{-c_2 / c_1 \tanh[(r - r_0) / c_2]\}$ $\rho_{Ti} = 0.00152m$, $a / \rho_{Ti} = 657.9$; $\beta = 0.0009$; $\beta / M_e k_{\perp}^2 \rho_{Ti}^2 \gg 1$
- Wave-particle interaction properly simulated by calculating the electron Landau damping
- The Gaussian shape density perturbation is set to be close to the TAE eigenmode

γ / ω_r	$\frac{m_i}{m_e} = 200$	$\frac{m_i}{m_e} = 1836$
LIGKA	-1.293%	-0.5000%
TRIMEG	-1.248%	-0.5008%



- Clear mode destabilization observed, with reasonable γ / ω_r produced
- Mode radial width (FWHM) $\Delta r \approx 0.12$, larger than that in TAE damping case ($\Delta r \approx 0.06$). It's due to the EP's non-perturbative effects on mode width

