

Iterative image reconstruction algorithm for computed tomography with very high energy electron beam

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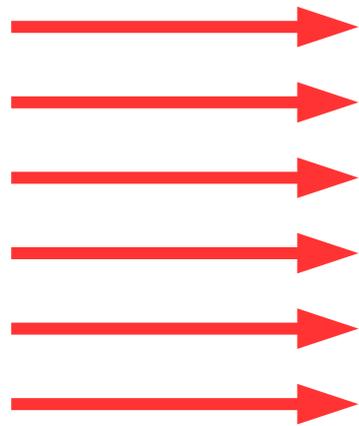
Outline

- Introduction of electron computed tomography
- Iterative image reconstruction algorithm
- Image analysis
- Future plans
- Conclusions

Imaging

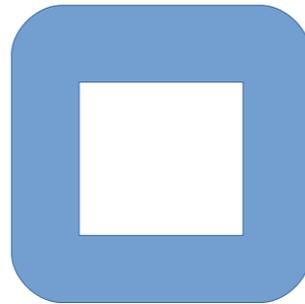
Source

- x-ray, neutron
- **charged particle**



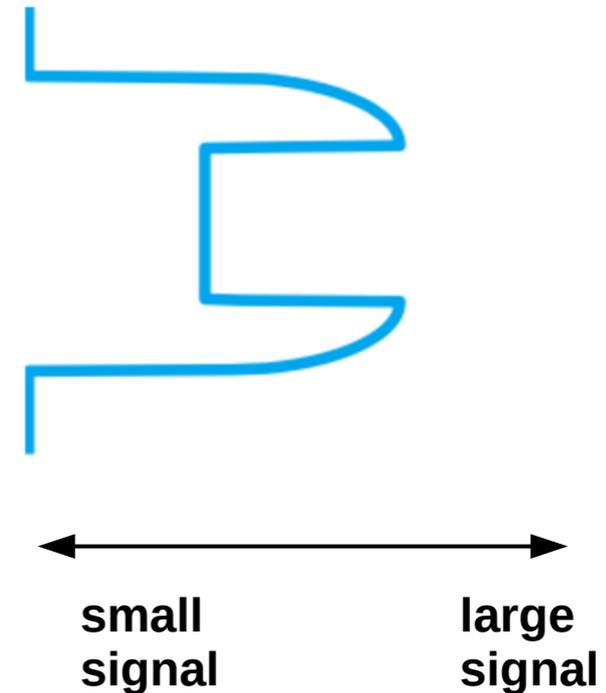
Interaction with the target

- absorption
- energy loss
- **scattering**



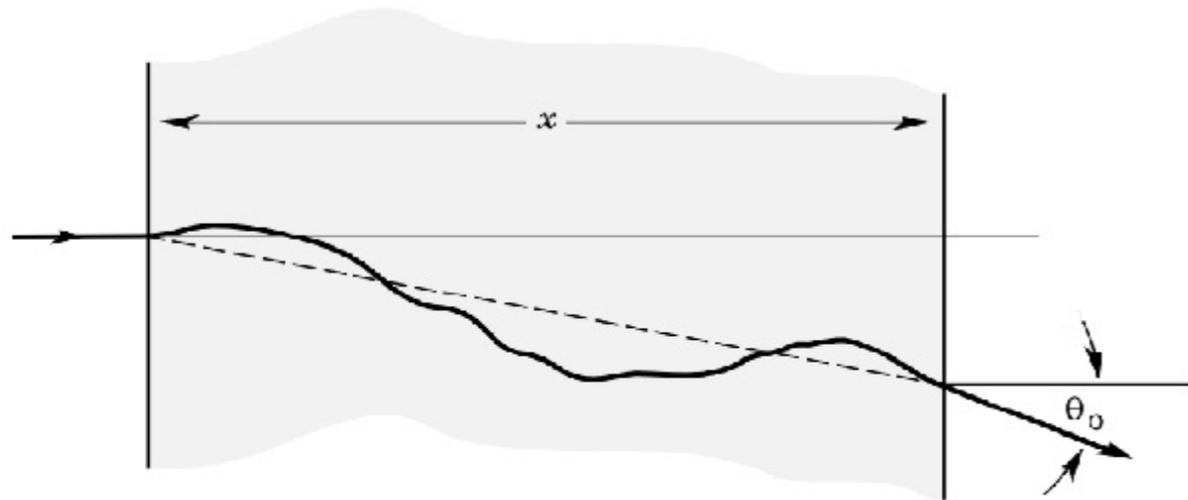
Measure physical quantity

- intensity
- remaining energy
- **variance of the deflection angle**



- Novel imaging modality using
 - High energy electron
 - Multiple Coulomb Scattering

Multiple Coulomb Scattering (MCS)



Highland's formula:

$$\Theta_0 = \left(\frac{13.6 \text{ MeV}}{\beta c p} z \right) \sqrt{\varepsilon} (1 + 0.038 \ln \varepsilon)$$

Material budget

$$\varepsilon = \int \frac{1}{X_0(x)} dx$$

z : electron charge number

βc : electron velocity

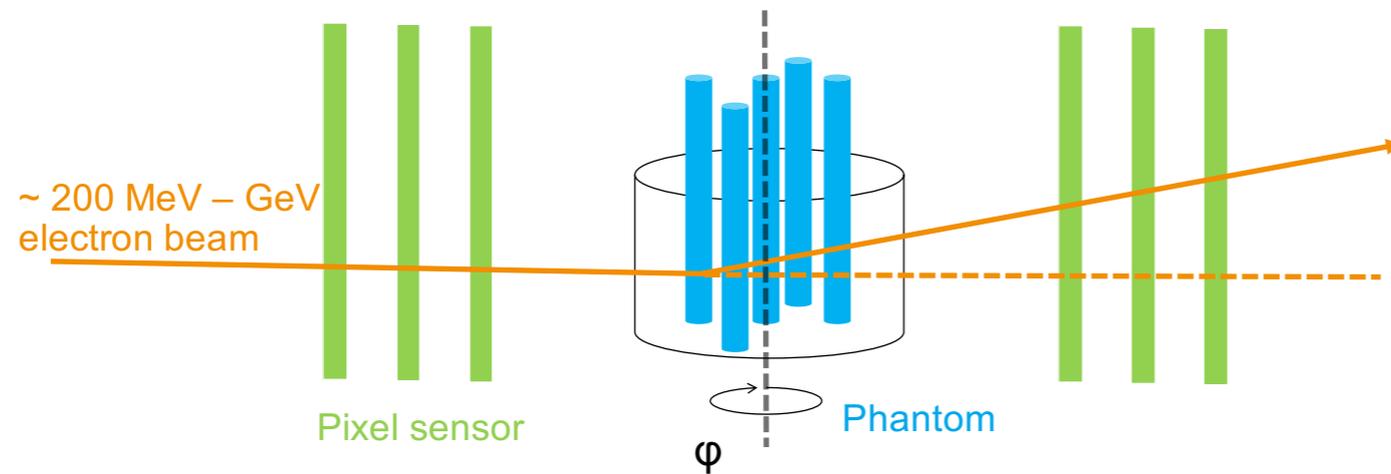
p : electron momentum

X_0 : material's radiation length

$$\Theta_0^2 \propto \varepsilon$$

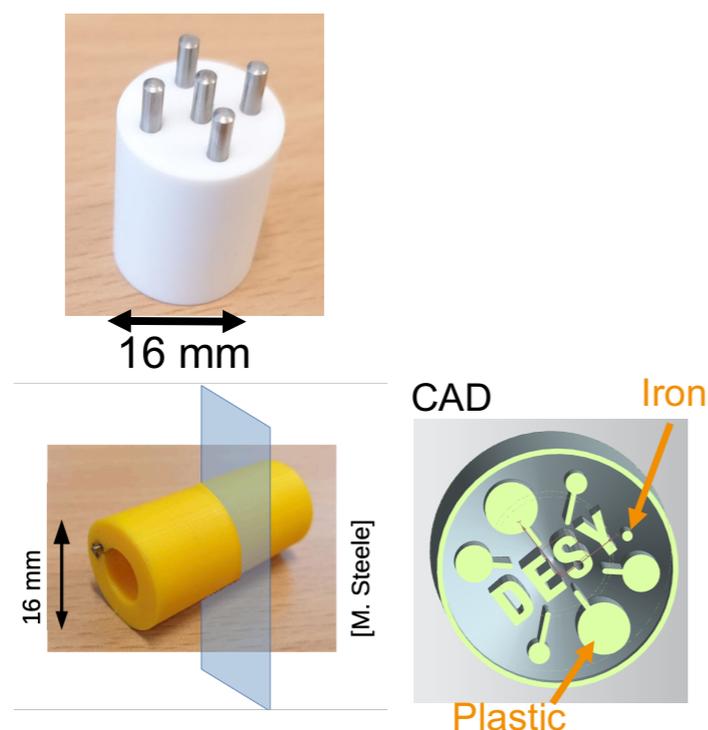
- ▶ Electrons undergo MCS when transversing material
- ▶ Gaussian width of the deflection angle distribution correlates with material budget
- ▶ Material budget imaging by measuring the scattering angle distribution

Testbeam Experiment at DESY

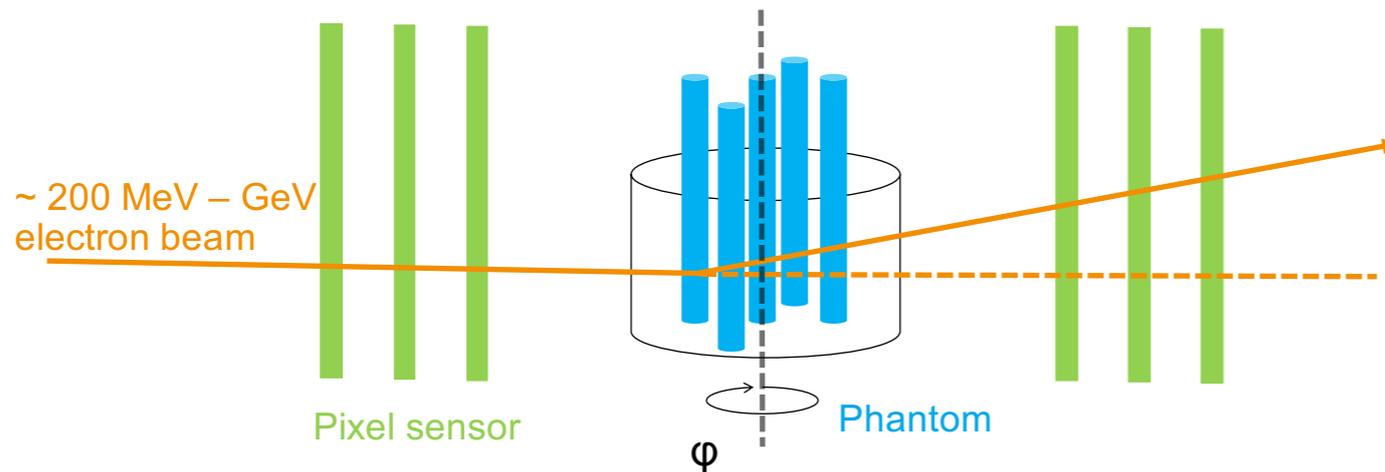


Beam

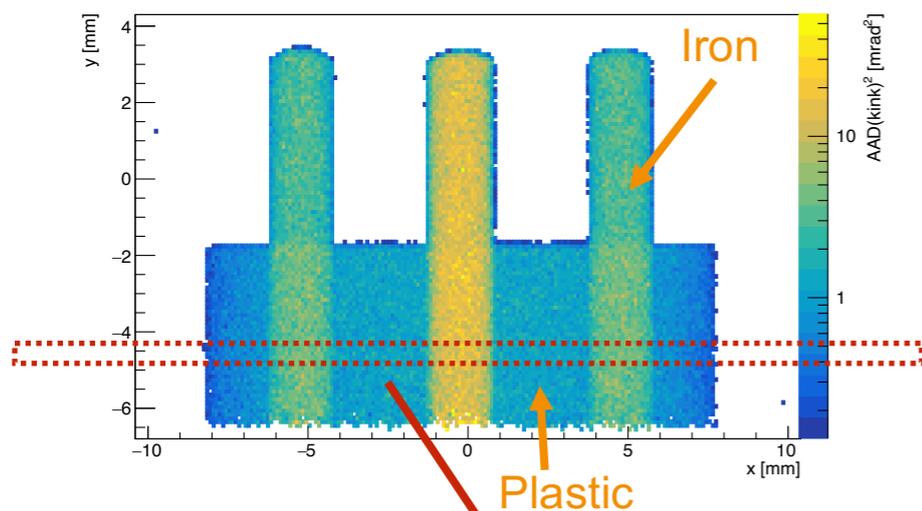
- ▶ Performed in June and August in 2020
- ▶ Electron energy: 2 GeV
- ▶ Test 2 phantoms
 - 5 iron rods + plastic
 - DESY logo



Electron Computed Tomography

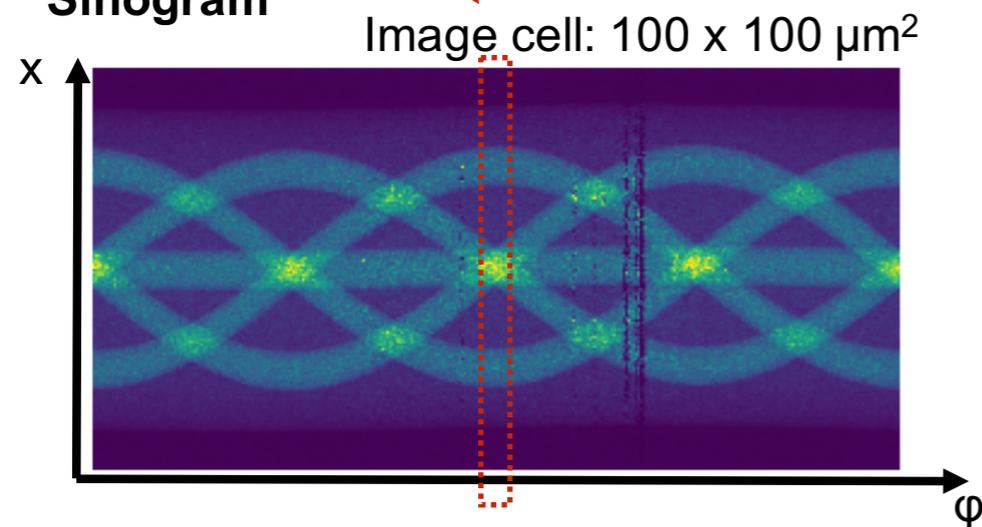


- Measure trajectory of electrons



- Group electrons into pixels at a virtual plane though the phantom
- Calculate squared width of angular distribution per pixel (AAD_{90}^2)

Sinogram



- Repeat for various projections ($400 \cdot 0.9^\circ = 360^\circ$)
- Create a sinogram

→ Tomographic image reconstruction

Tomographic Image Reconstruction Algorithm

1. Filtered Back Projection (FBP)

- **Analytical reconstruction** using inverse Radon transform
- Artefacts and noise due to statistical/systematic effects

2. Iterative reconstruction

- **Reconstruction based on a model with statistical noise** using iterative methods
- Artefacts and noise removal by adding a regularization method

Iterative Image Reconstruction

$$\begin{array}{ccc} \text{Data} & \vec{y} = A \vec{x} & \text{Image} \\ & \text{Model} & \text{(Truth)} \end{array}$$

Suppose that:

$$\vec{y} = A \vec{x} + \vec{n} \quad \text{n: noise}$$

Reconstruct image x when noise n is minimized

Objective function:

$$J(\vec{x}) = \|A\vec{x} - \vec{y}\|^2$$

$$A^T A \vec{x} = A^T \vec{y} \quad (\text{minimize } J(\vec{x}) \rightarrow \partial J(\vec{x}) / \partial \vec{x} = 0)$$

Landweber method:

$$\vec{x}^{(k+1)} = \vec{x}^{(k)} + \alpha A^T (\vec{y} - A \vec{x}^{(k)}) \quad \begin{array}{l} \text{k: number of iteration} \\ \alpha: \text{step size} \end{array}$$

Simultaneous iterative reconstruction technique (SIRT)

TVS Regularization

β : regularization strength
 $U(x)$: energy function

$$\vec{x}^{(k+1)} = \vec{x}^{(k)} + \alpha \left[A^T(\vec{y} - A\vec{x}^{(k)}) + \beta \frac{\partial U(\vec{x})}{\partial \vec{x}} \right]$$

Regularization

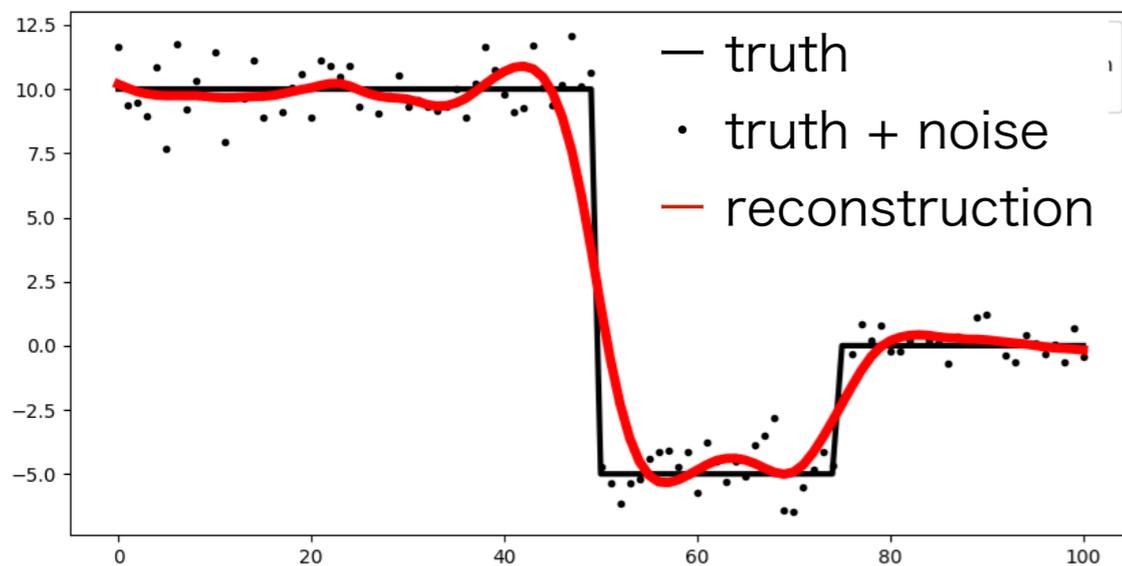
Total Variation Superiorization (TVS):

$$U(\vec{x}) = \sum_{i,j} \sqrt{(x_{i,j} - x_{i-1,j})^2 + (x_{i,j} - x_{i,j-1})^2}$$

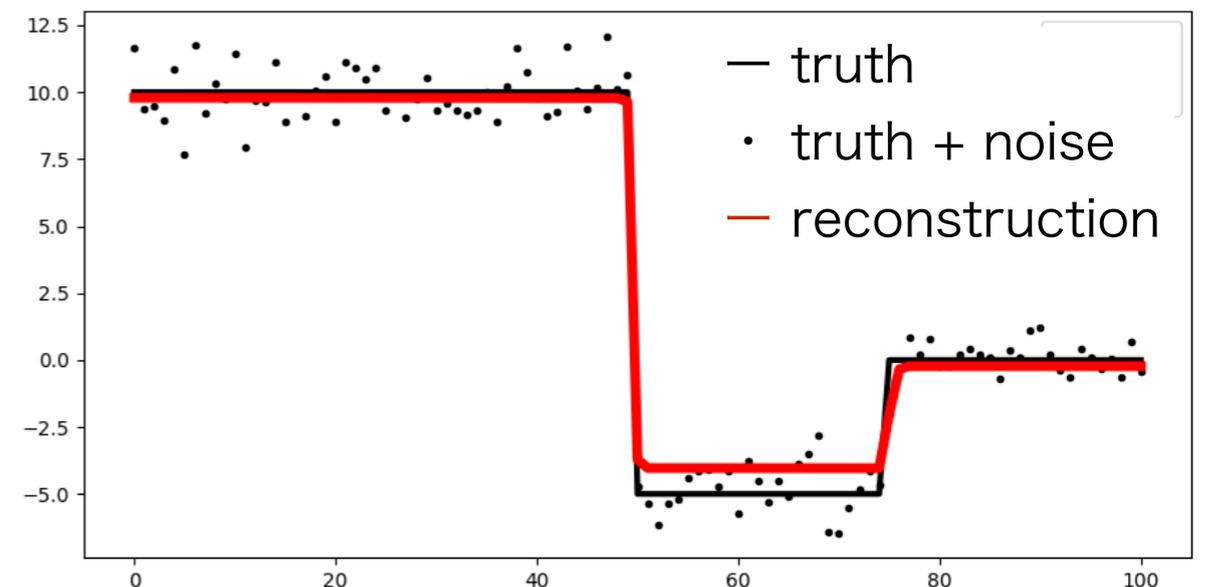
Magnitude of gradient

(Quote: https://pylops.readthedocs.io/en/latest/gallery/plot_tvreg.html)

Normal L2 regularization



TV regularization (L1 regularization)



▸ Smoothing while preserving “edge”

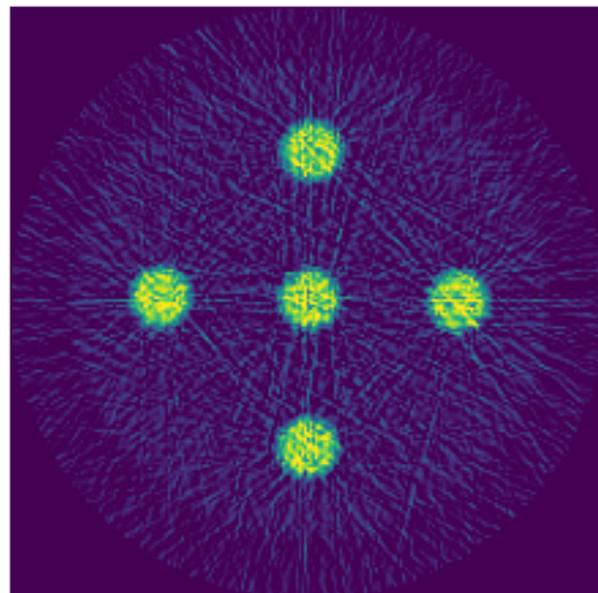
Image analysis



16 mm

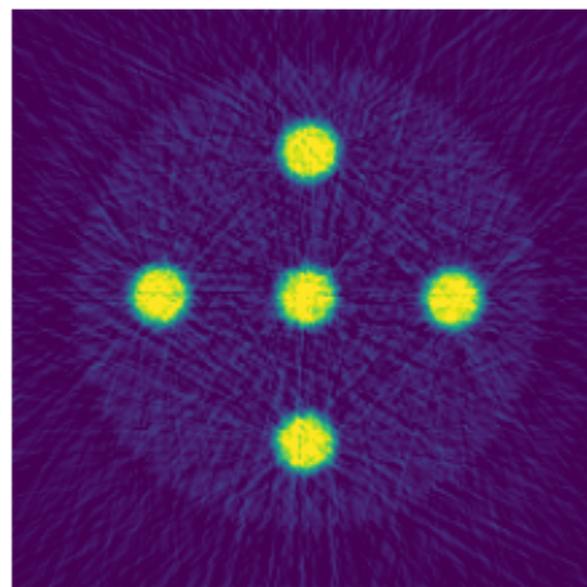
β : regularization strength

FBP

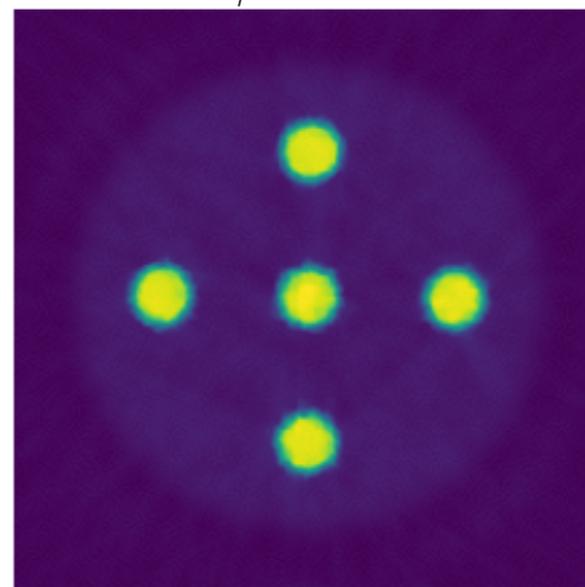


SIRT + TVS (30 iterations)

$\beta = 0$



$\beta = 3$



$\beta = 10$

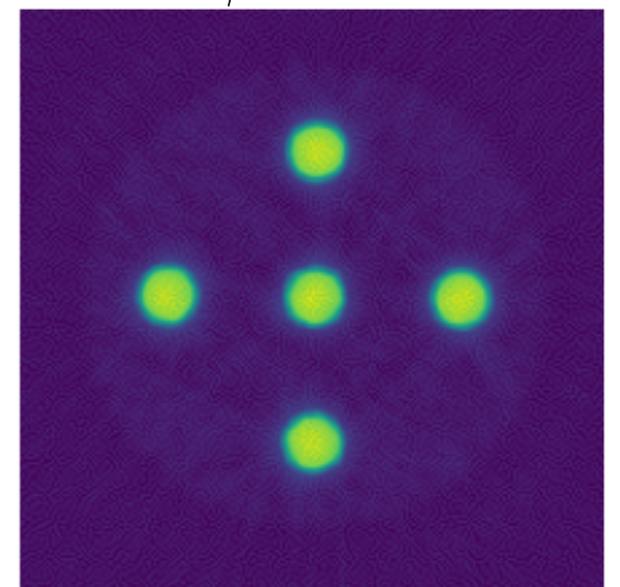
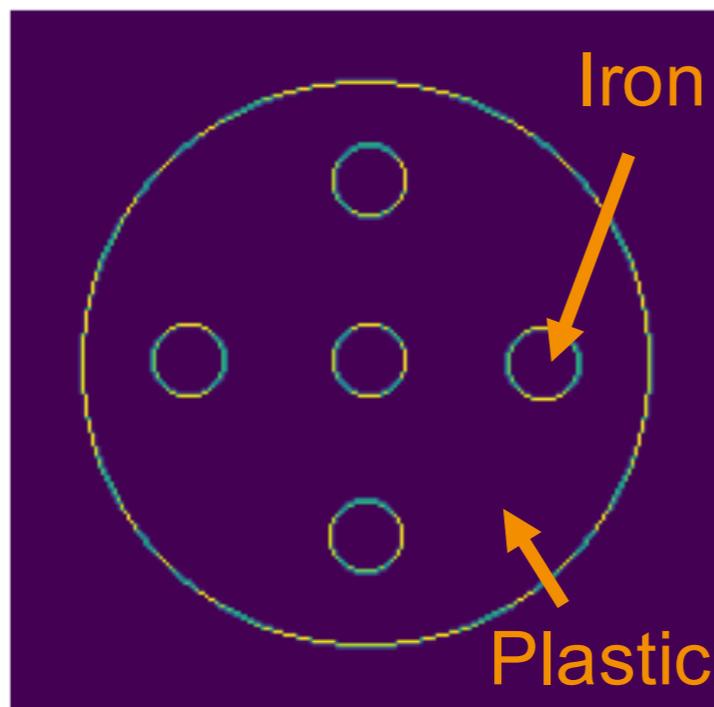


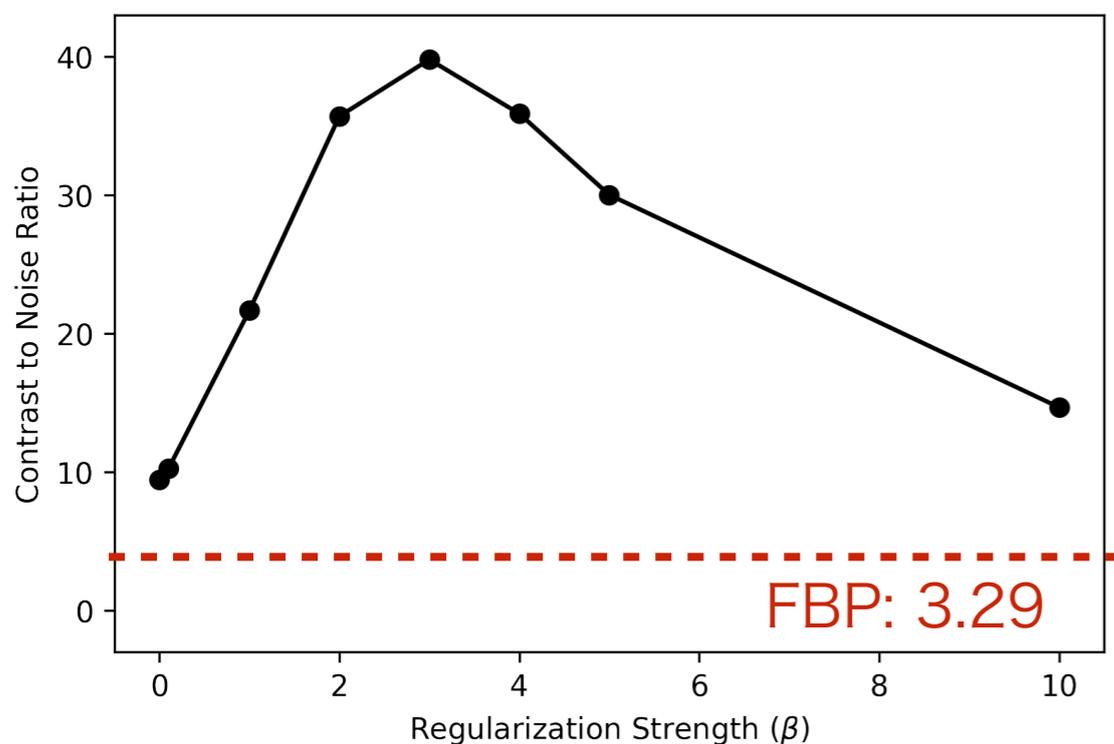
Image cell: 100 x 100 μm^2

- Quantitative image analysis
 - Contrast to noise ratio
 - Spatial resolution

Contrast to Noise Ratio (CNR)



- Circle detection to define the region of iron and plastic
(https://scikit-image.org/docs/dev/auto_examples/edges/plot_circular_elliptical_hough_transform.html)



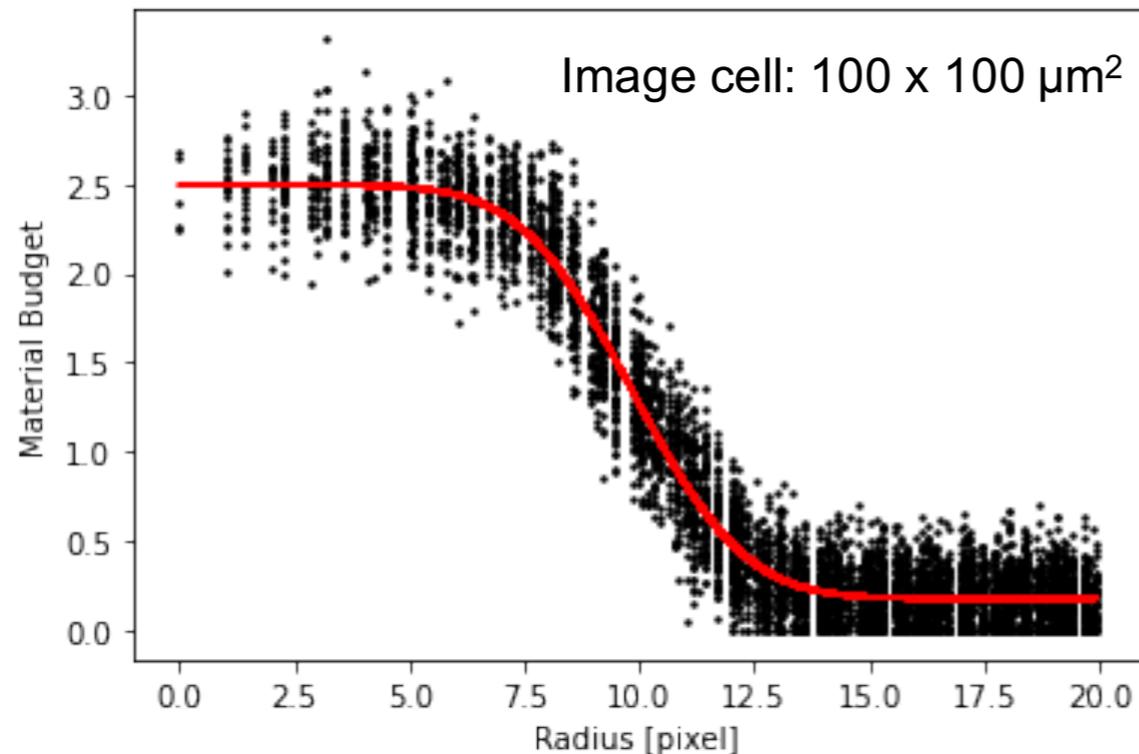
- Calculate the mean and the standard deviation within the area of iron and plastic
- Calculate CNR

$$\text{CNR} = \frac{\mu_{\text{iron}} - \mu_{\text{plastic}}}{\sqrt{\sigma_{\text{iron}}^2 + \sigma_{\text{plastic}}^2}}$$

μ : Mean
 σ : Standard deviation

SIRT+TVS ($\beta=3$) shows the best CNR

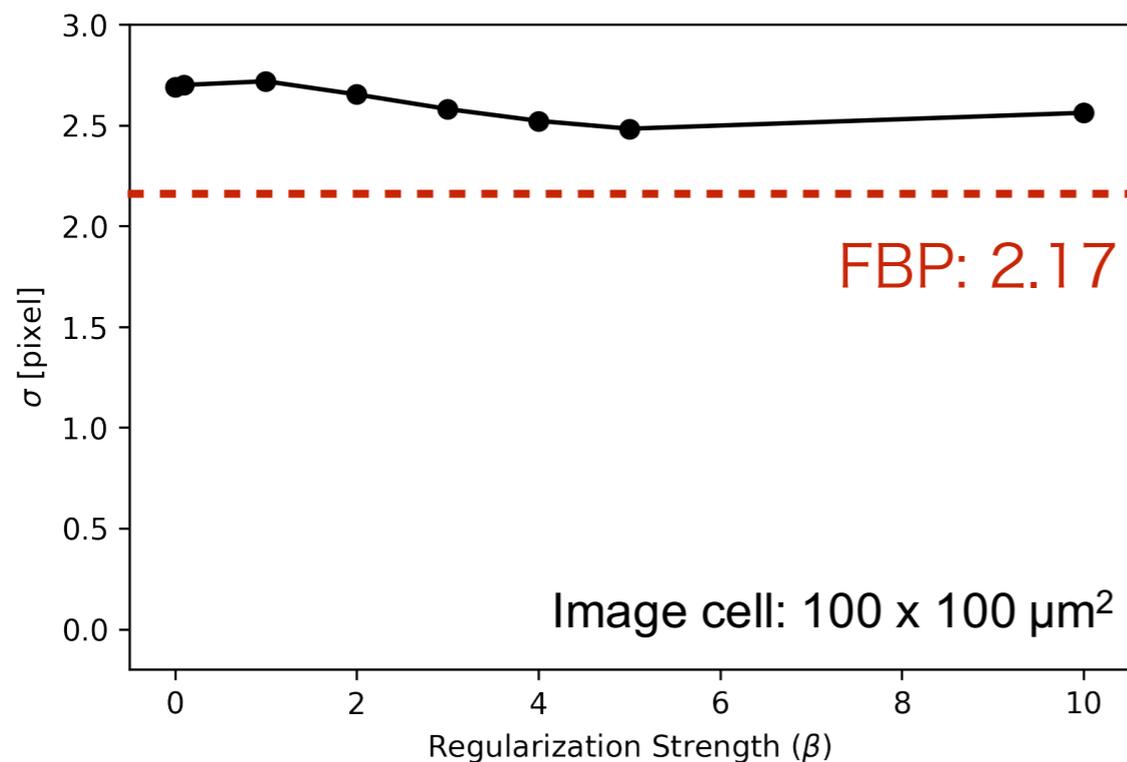
Spatial Resolution



Edge-spread-function:

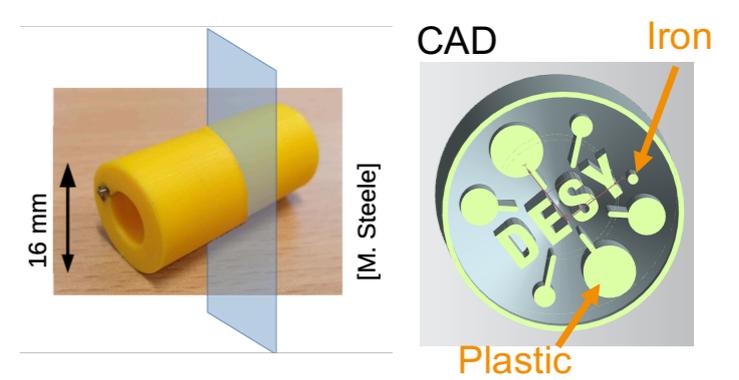
$$\text{ESF}(x) \propto A + \text{Erf} \left(\frac{x - \mu}{\sigma} \right)$$
$$\text{Erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x \exp(-t^2) dt$$

- Circle detection for 5 iron rods
- Plotting material budget as a function of radius from the center of the irons
- Fitting with ESF
- σ of the ESF corresponds to spatial resolution



TVS regularization only slightly worsen the spatial resolution

Image Analysis (DESY logo)



FBP

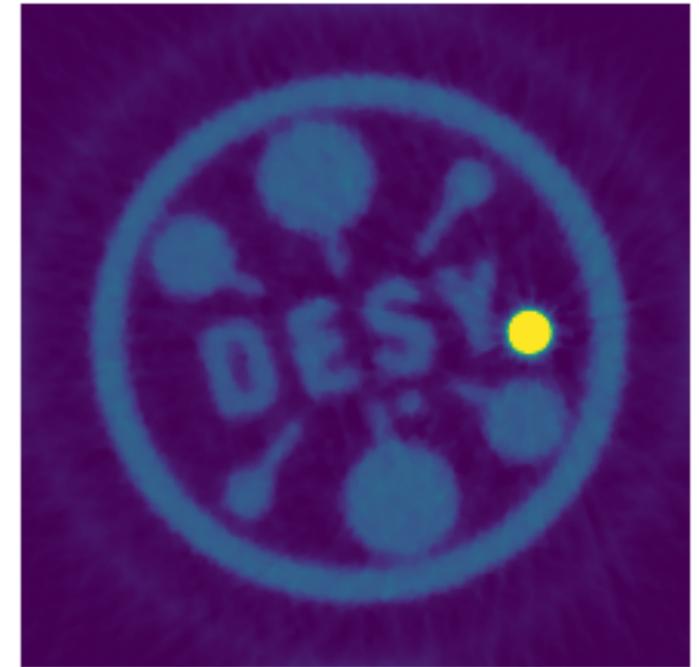
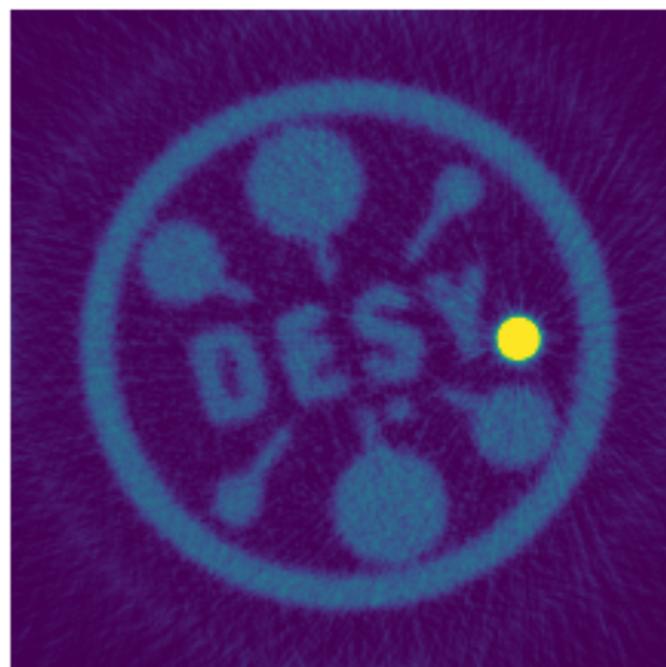
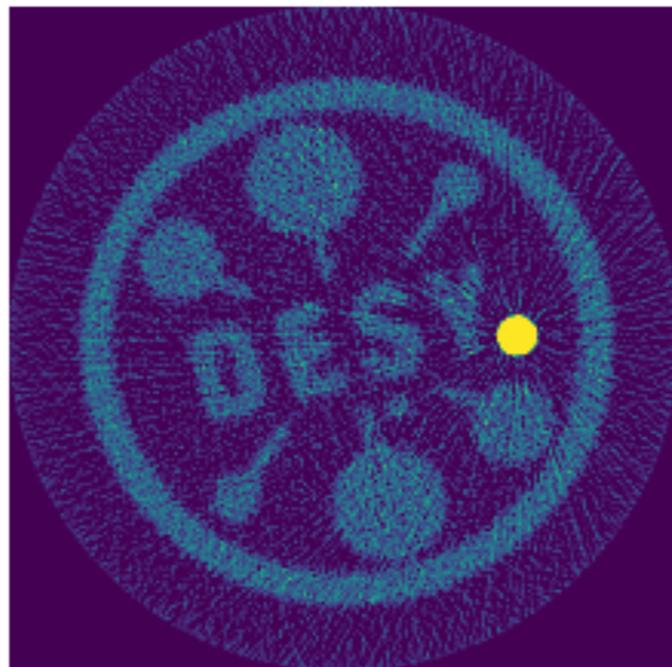
SIRT + TVS (30 iterations)

Number of
projections

$$\beta = 0$$

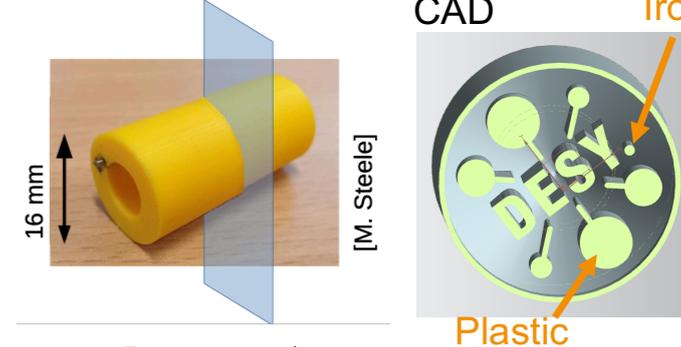
$$\beta = 0.4$$

400



Iterative reconstruction yields noise reduction while maintaining contrast and spatial resolution

Image Analysis (DESY logo)



FBP

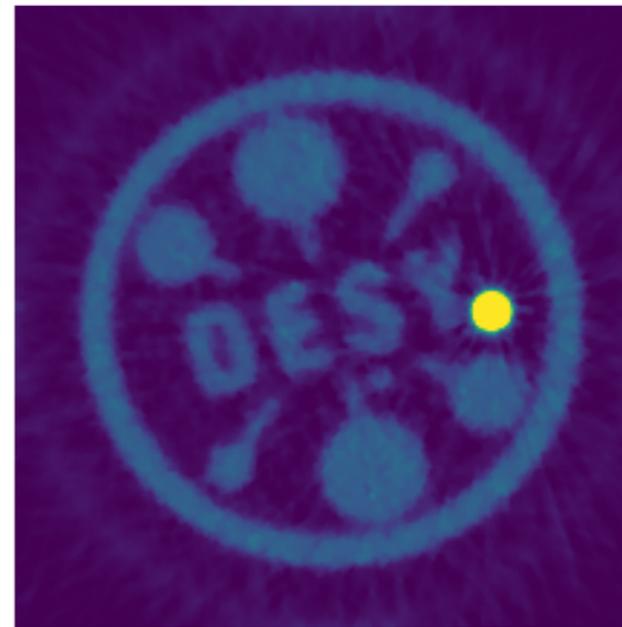
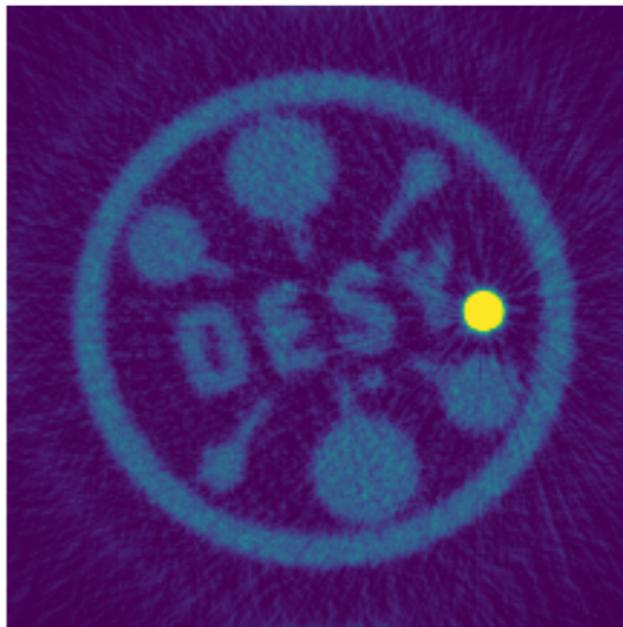
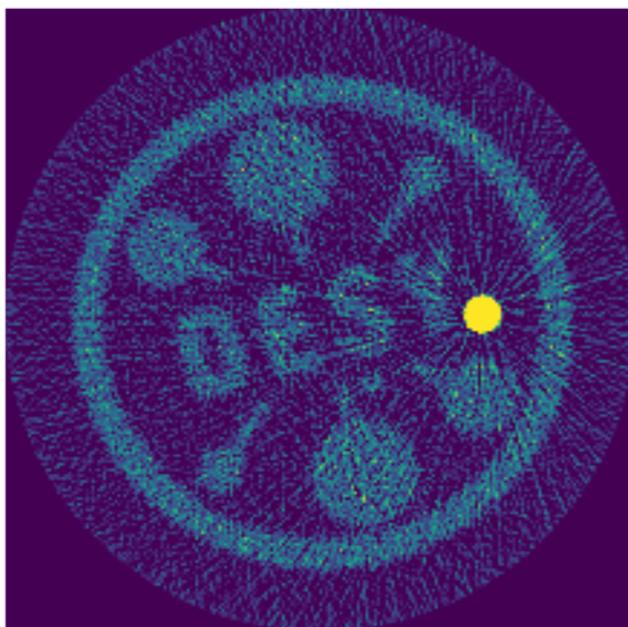
SIRT + TVS (30 iterations)

$\beta = 0$

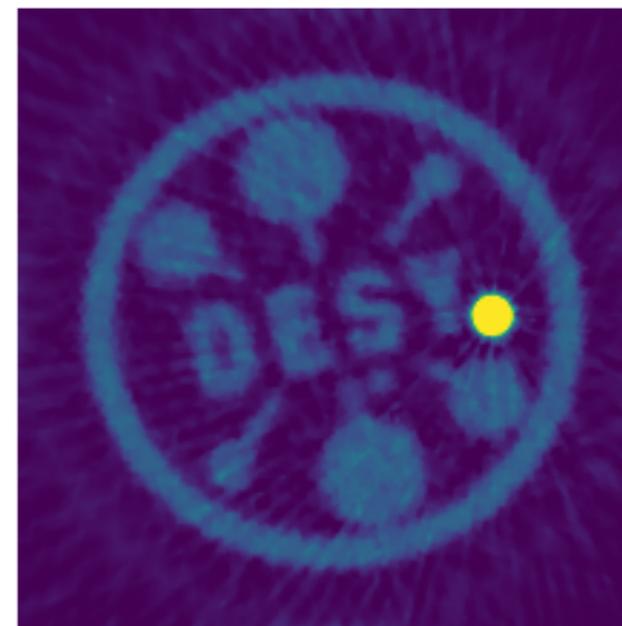
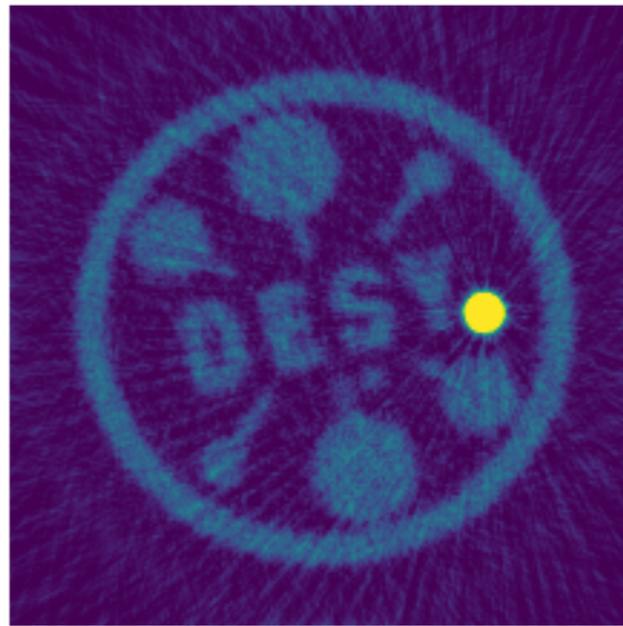
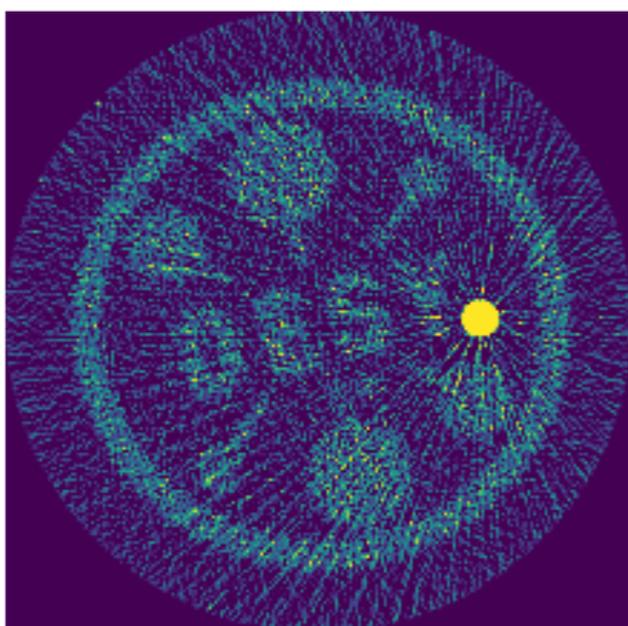
$\beta = 0.4$

Number of
projections

200



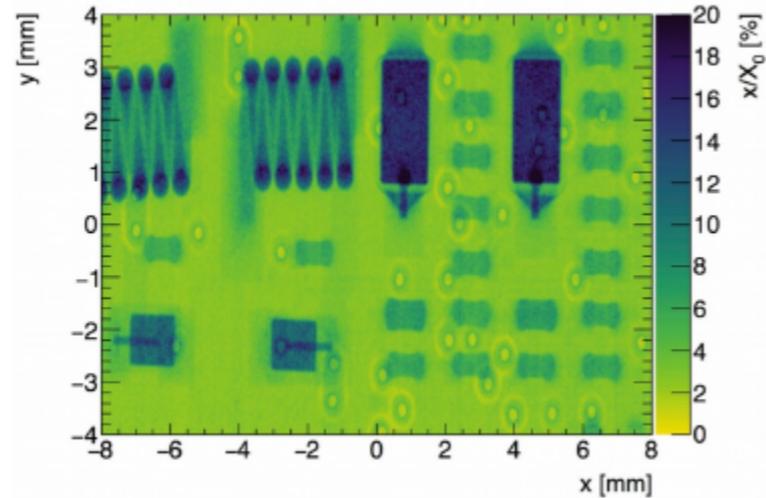
100



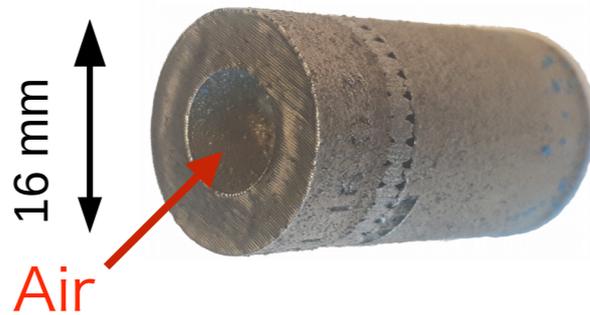
Noise increases as the number of projections decreased in FBP

The degradation is suppressed in iterative reconstruction

Applications

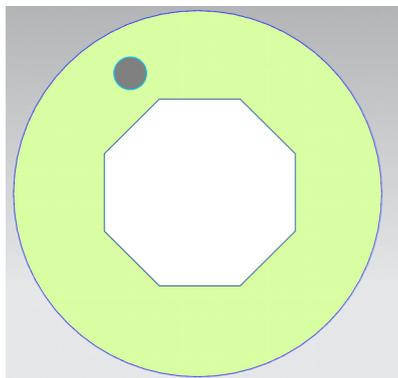


- ▶ Material Budget imaging for HEP detector upgrade

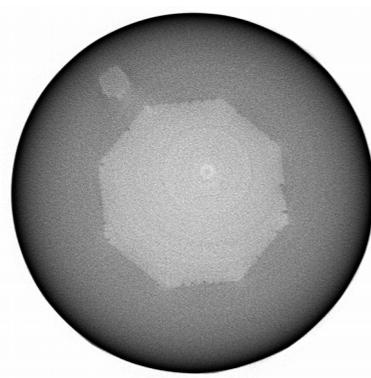


- ▶ Non-destructive imaging for high-Z materials

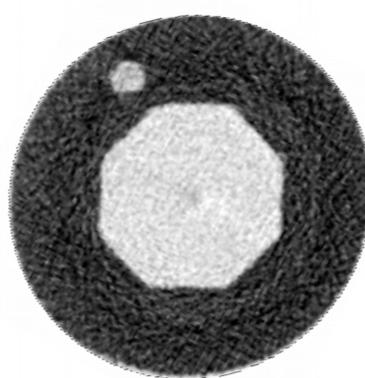
CAD



X-ray CT
@ 170 kVp



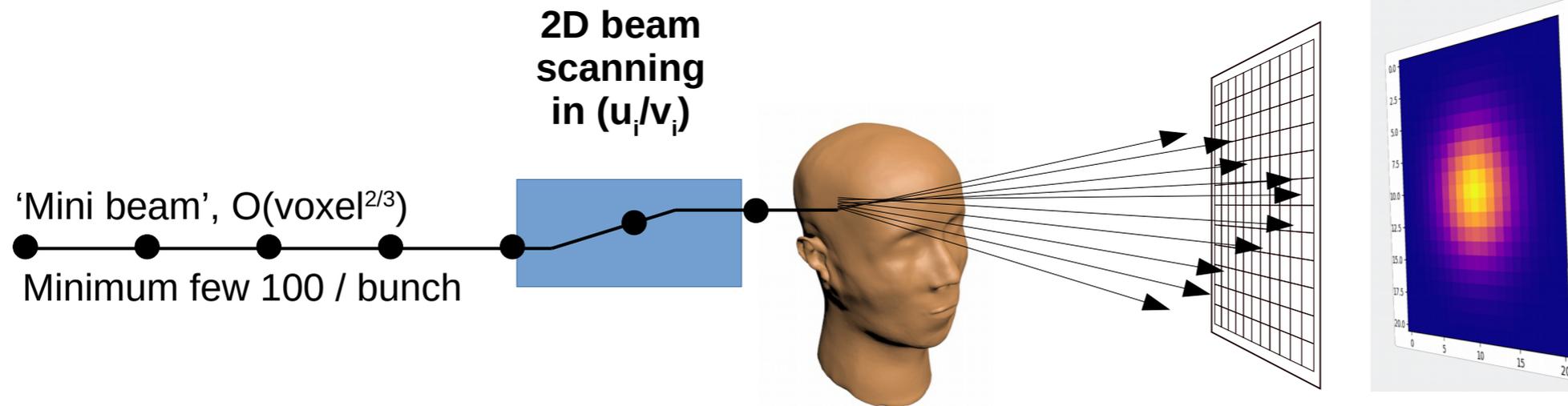
e-CT (with FBP)



Future Plans

- ▶ Imaging for use in combination with Very High Energy Electron Radiotherapy (VHEE-RT)
 - Energy: 50-250 MeV
 - Better dose conformity than conventional photon radiotherapy
 - Reasonable cost and size compared to hadron therapy
 - Possibility of treatment with ultra-high dose rate (FLASH-RT)
- ▶ Portal Imaging with 200 MeV
 - Example: Detecting metal markers implanted in the body to determine the location of the target

Pulse Beam Imaging



This is not the final image!

Merely the response per bunch.

- ▶ Place a sensor only downstream of target
- ▶ 2D beam scanning with pulsed beam
- ▶ Read data from each bunch and calculate material budget from the beam spread without track reconstruction
- ▶ First tests planned at PITZ/DESY-Zeuthen

Conclusions

- ▶ Iterative image reconstruction algorithm was developed for novel electron computed tomography
- ▶ The proposed algorithm yields noise reduction and better contrast
- ▶ Small negative effect for spatial resolution
- ▶ The improvement of the algorithm is significant with lower statistics
- ▶ Under development for medical imaging with 200 MeV

Backups

Iterative Reconstruction for e-CT

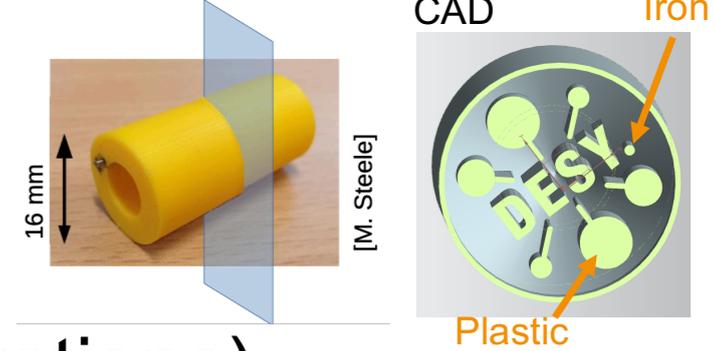
- ▶ Statistical noise
 - Unknown statistical noise of the width (AAD₉₀) of the scattering angle distribution
- ▶ Regularization
 - A large variety of regularization terms can be implemented in the iterative algorithm

U(x): energy function

$$\vec{x}^{(k+1)} = \vec{x}^{(k)} + \alpha \left[A^T(\vec{y} - A\vec{x}^{(k)}) + \beta \frac{\partial U(\vec{x})}{\partial \vec{x}} \right]$$

Function: quadratic, gaussian, total variation, ...

Image Analysis (DESY logo)



FBP

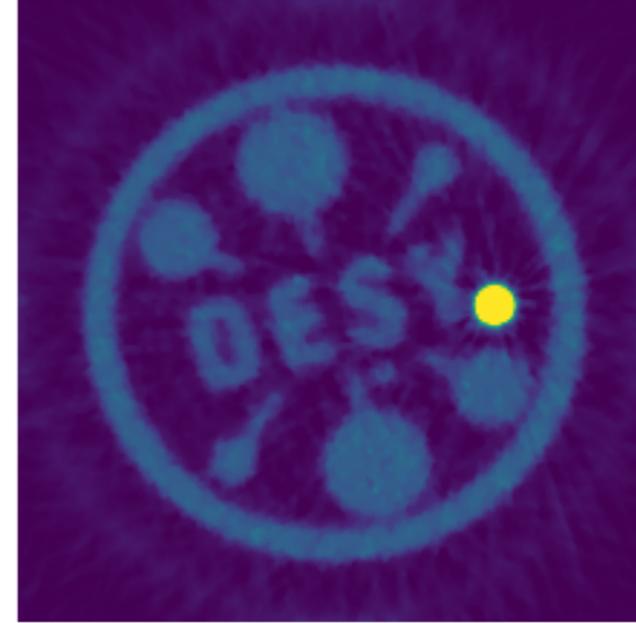
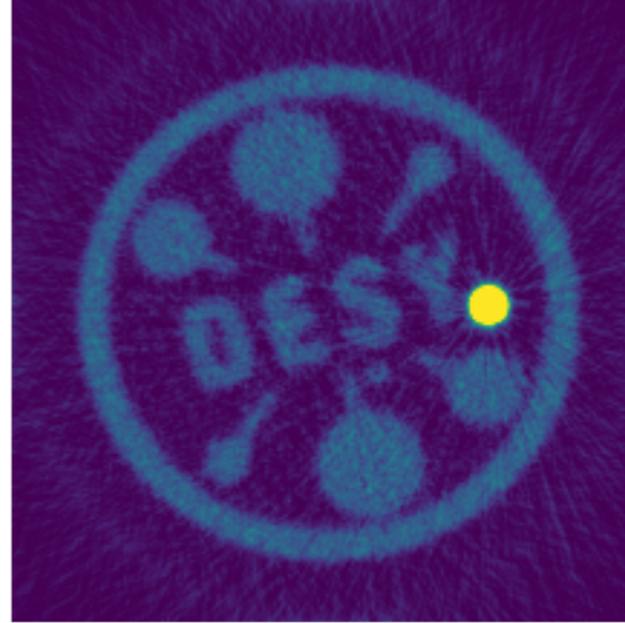
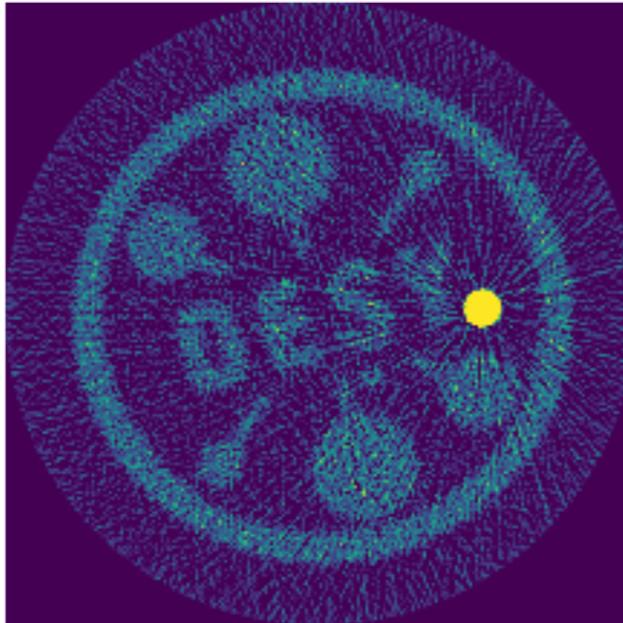
SART + TVS (30 iterations)

$\beta = 0$

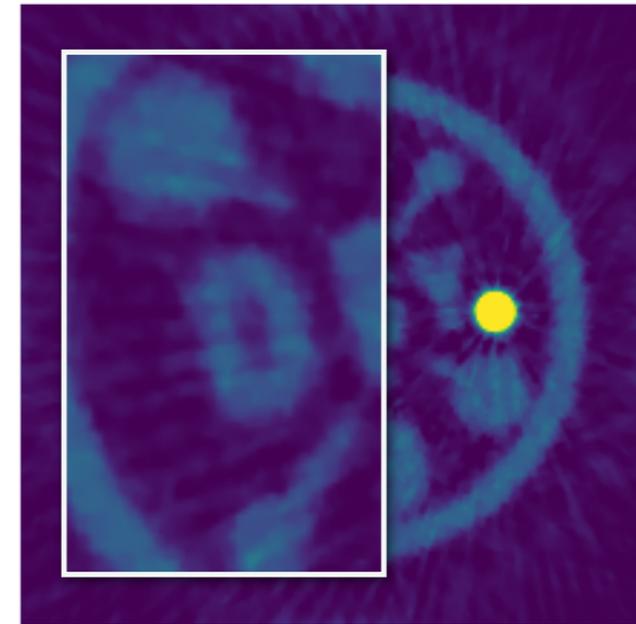
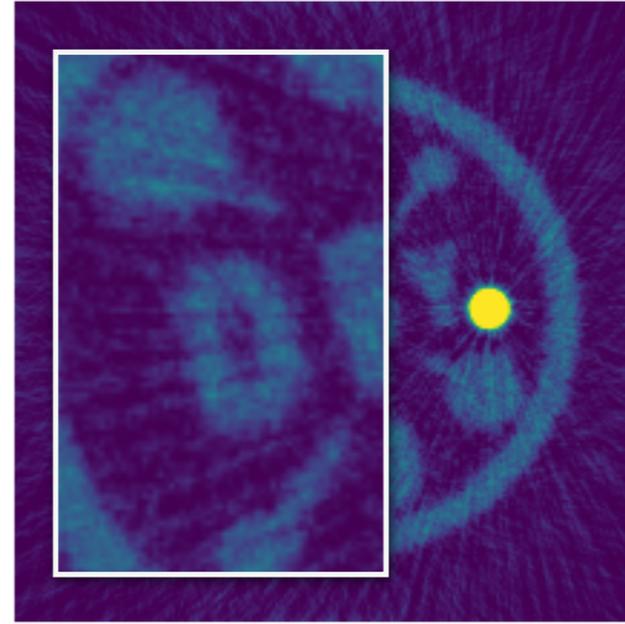
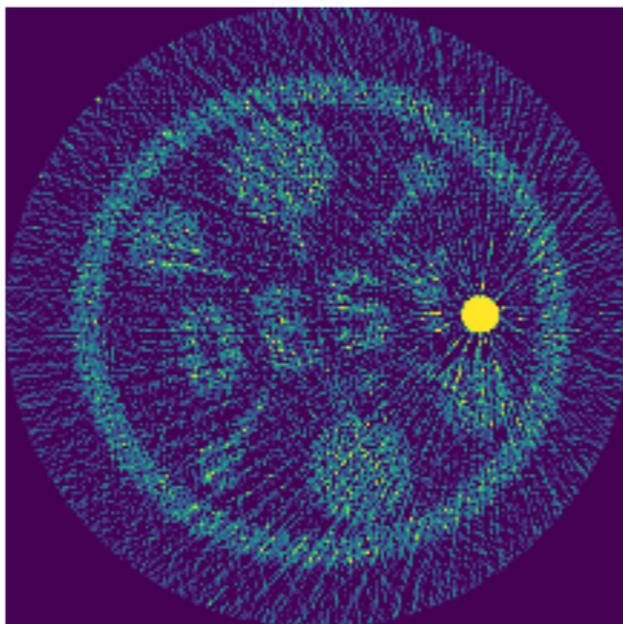
$\beta = 0.4$

Number of
projection

200



100



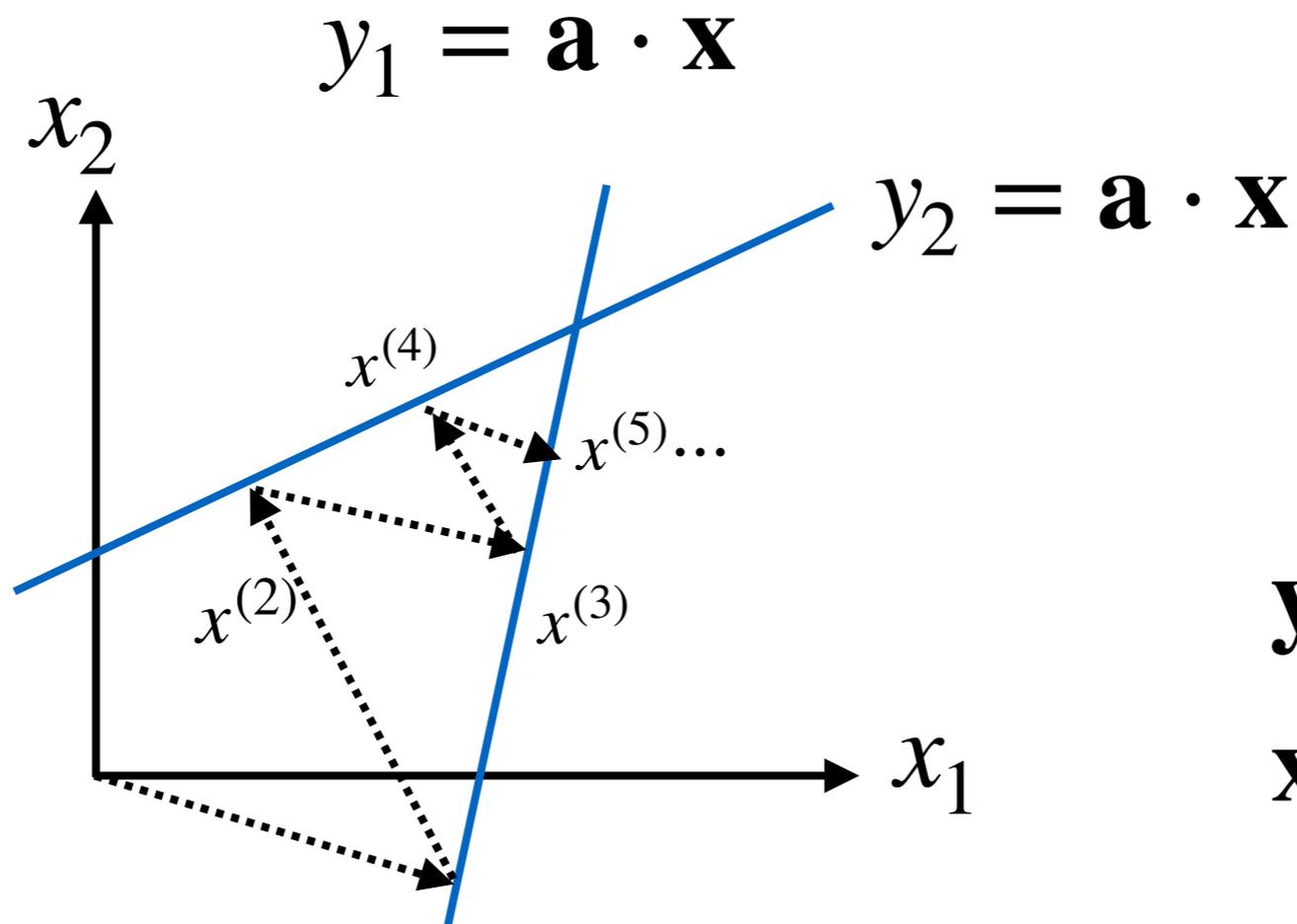
Not significant improvement like 5 iron rods?

→ TVS works (large uniform + clear edge) structure

Projection method

$$\vec{x}^{(k+1)} = \vec{x}^{(k)} + \sum_{i=1}^I \alpha_i \frac{y_i - \vec{a}_i \cdot \vec{x}^{(k)}}{\|\vec{a}_i\|^2} \vec{a}_i$$

$\alpha_i = 1 \rightarrow$ Algebraic reconstruction technique

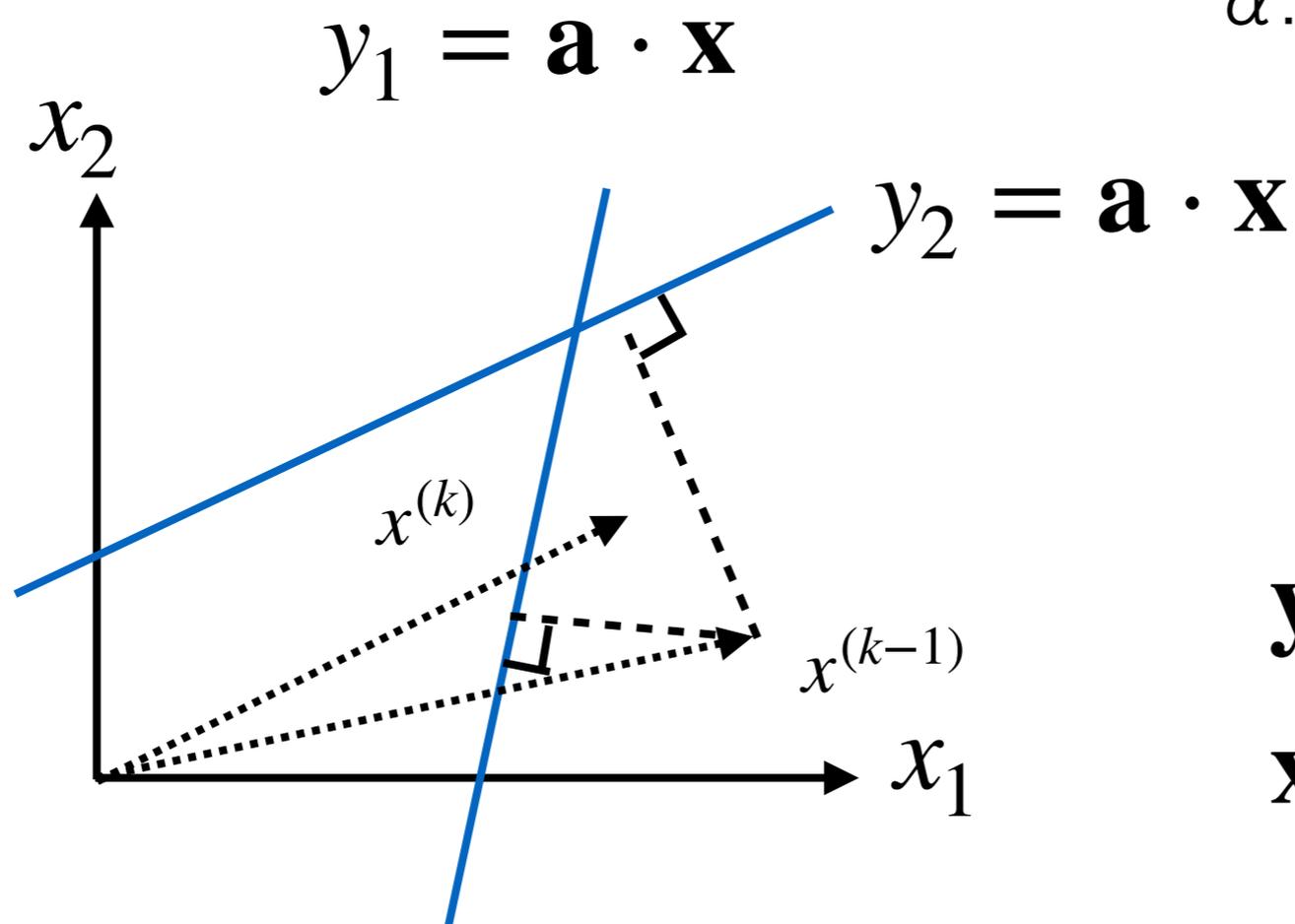


SIRT Projection

$$\vec{x}^{(k+1)} = \vec{x}^{(k)} + \sum_{i=1}^I \alpha \frac{\|\vec{a}_i\|^2 (y_i - \vec{a}_i \cdot \vec{x}^{(k)})}{\|\vec{a}_i\|^2} \vec{a}_i$$

Simultaneous projection with weighting $\sum_{i=1}^I \alpha \|\vec{a}_i\|^2$

α : step size (free parameter)



$$\mathbf{y} = (y_1, y_2)^T$$

$$\mathbf{x} = (x_1, x_2)^T$$