





Machine Learning Study of CLIC RF Breakdowns

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Presentation Outline

Presentation of preliminary analysis results:

1. Introduction
2. Transformation
3. Exploration
4. Modeling
5. Conclusion
6. Outlook



Introduction



Transformation



Exploration



Modeling



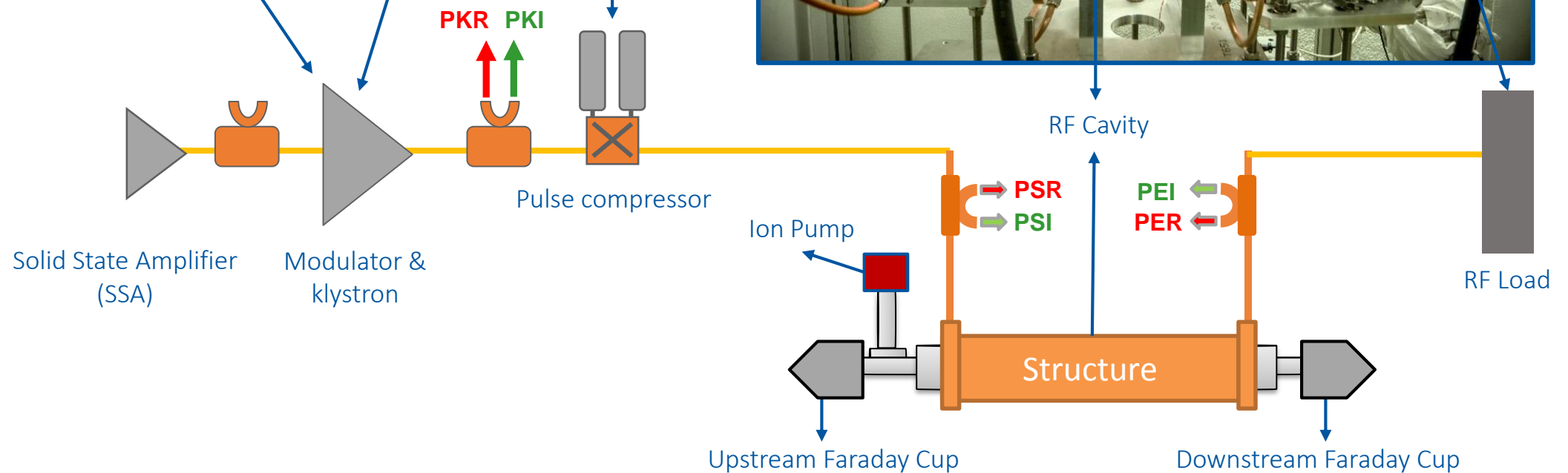
Conclusion



Outlook



1. XBOX 2 Test Stand



Content provided by Lee Millar



Introduction



Transformation



Exploration



Modeling



Conclusion



Outlook



1. Goals

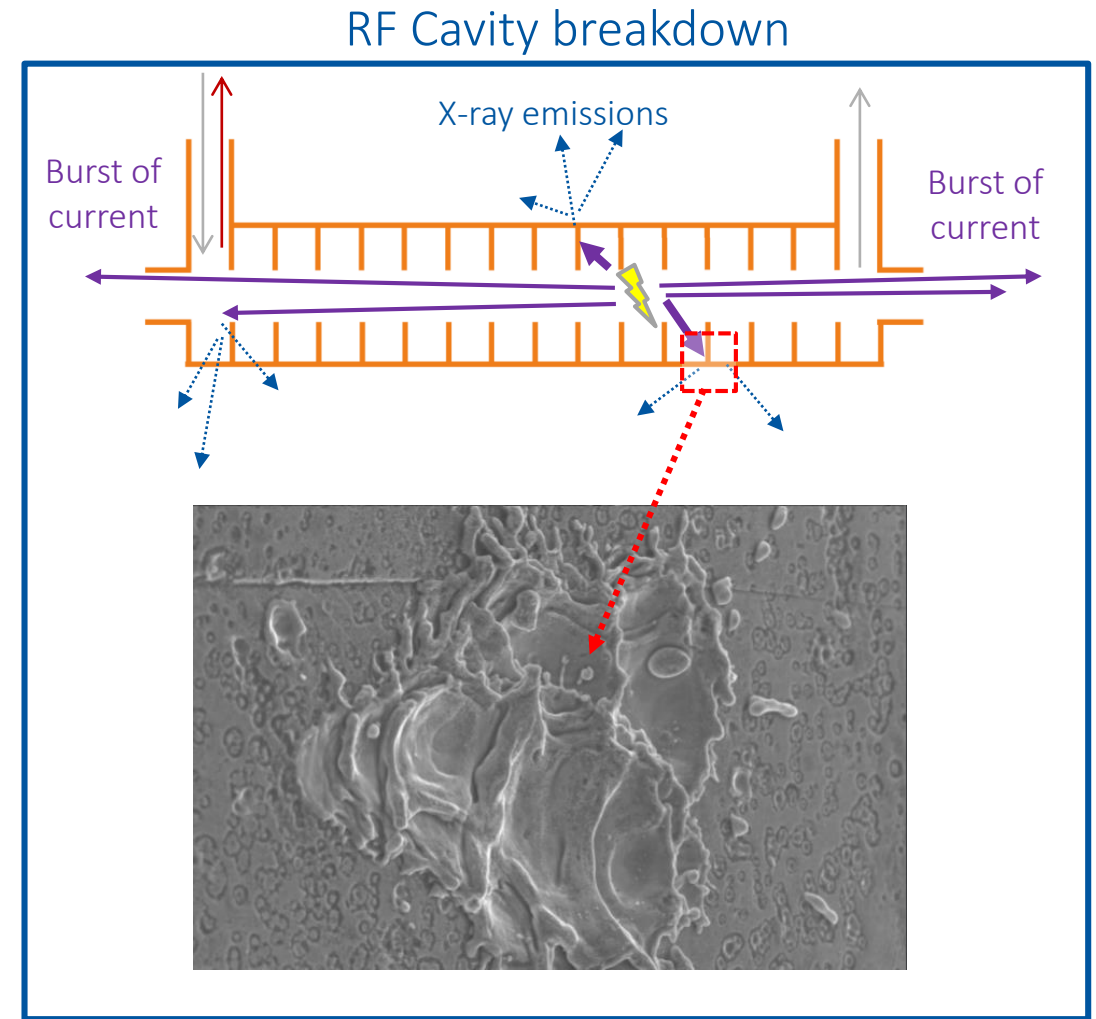
Breakdowns:

Small deformities cause field enhancement on surface which can lead to plasma formation (arc) and surface damage

- Labels “healthy” (=1) and “breakdown” (=0) are assigned by CLIC team with threshold on DC (Faraday Cup) and reflected signals

Goal (short-term): Investigate breakdown precursors in XBOX 2 test structure

Goal (ultimate): operational tool for BD reduction, in order to avoid their occurrence by suitable adjustment of the power in the cavity



Content provided by Lee Millar

1. Data Overview

Data available:

90 GB of Data from 2018 (6months of data)

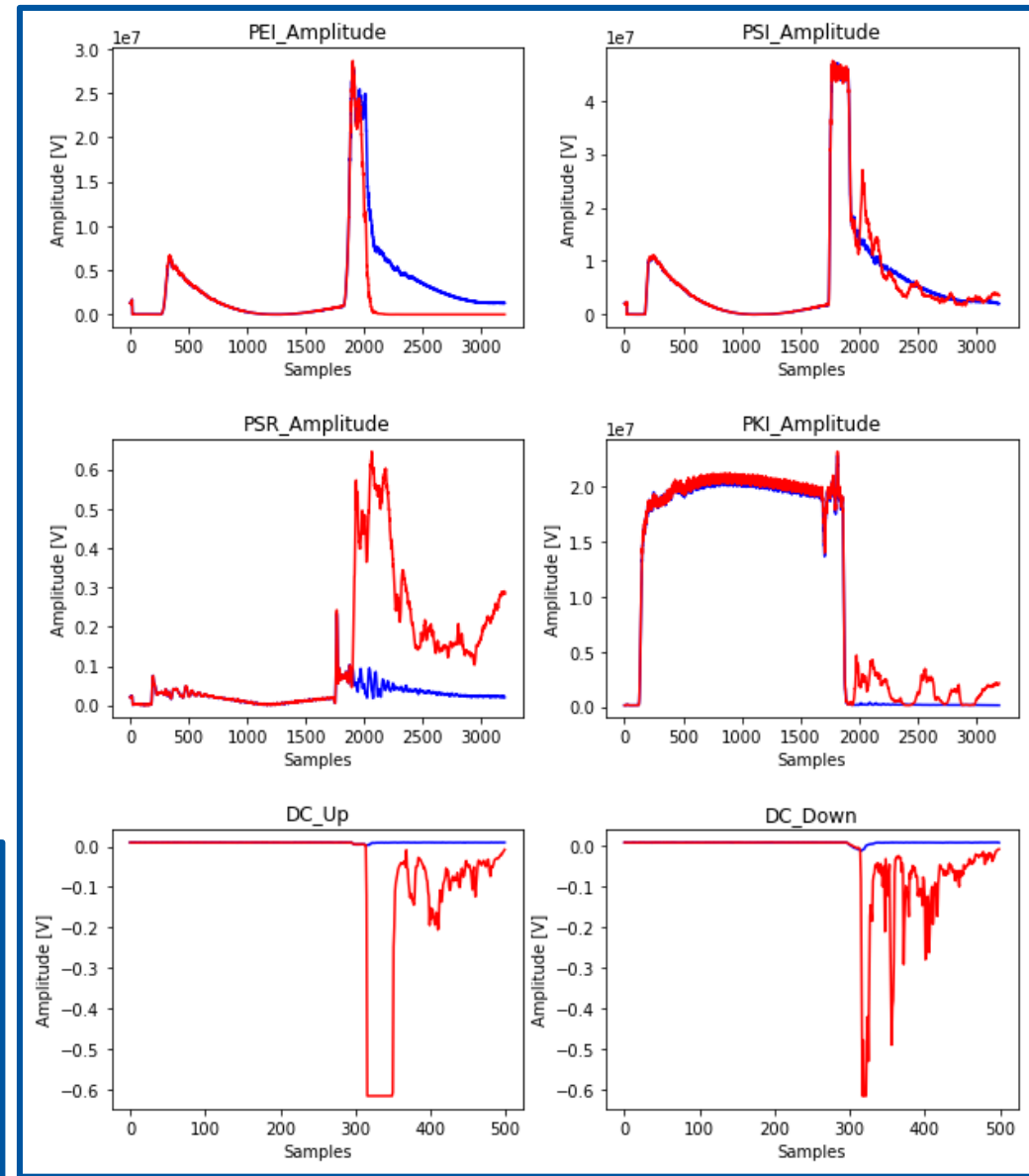
Event data:

- Data from test stand sensors: (**healthy**, **breakdown**)
16 Channels with up to 3200 sample points (12 GHz sample rate)

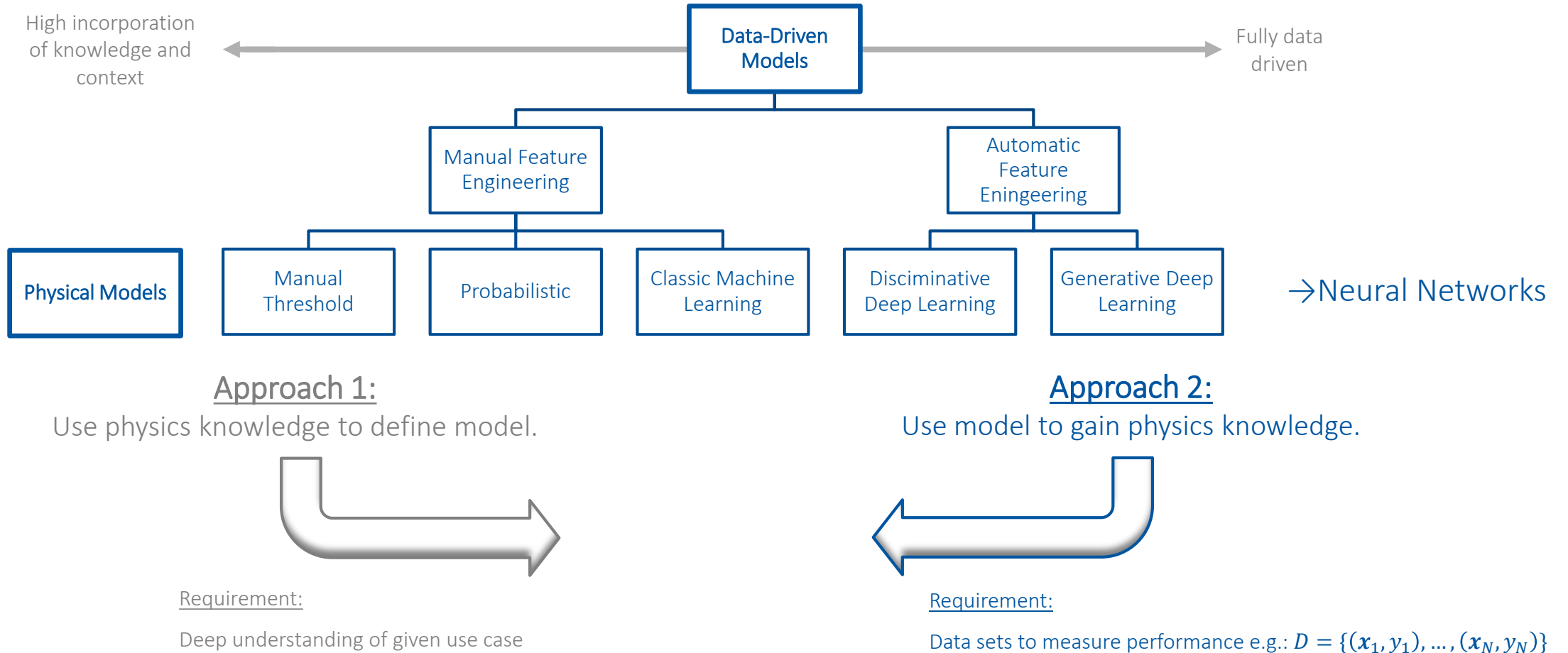
Trend data:

- Metadata about other machine parameters:
i.e. Temperature, pressure (~1Hz sample rate)

	Bunker_WG_Temp	Klystron_Flange_Temp	Load_Temp	PC_Left_Cavity_Temp	PC_Right_Cavity_Temp
0	24.134285	24.116962	27.955711	30.285633	30.187632
1	24.082500	24.145723	27.876066	30.277182	30.208776
2	23.241980	24.400513	27.502401	30.253901	30.191576
3	18.783634	19.573864	27.900787	30.100540	30.056396
4	18.741947	19.662273	4.099991	30.123297	30.077822

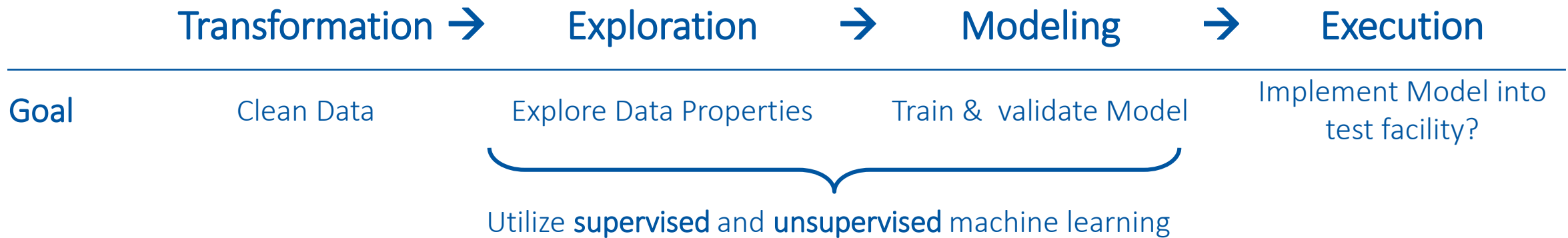


1. Overview of Data-Driven Models



Content from M. Maciejewski and H. Fawaz et al., „Deep learning for time series classification“, 2019

1. Analysis Workflow



Content from M. Maciejewski



Introduction
○○○○○

Transformation
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Exploration
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Modeling
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Conclusion
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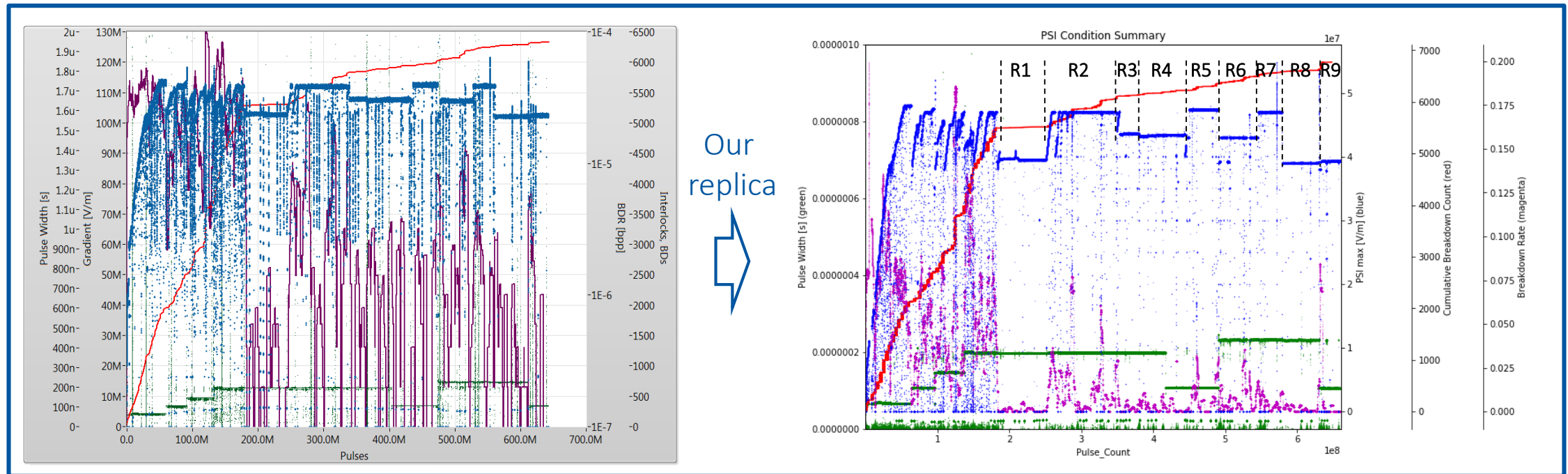
Outlook
●

2. Transformation

Goal: Clean data, fast queries, memory efficient storage, diverse usability

- Adding of extra features (e.g. run 1-9)
- Transformation of data into compressed pickle (24 GB, 1min to query data)

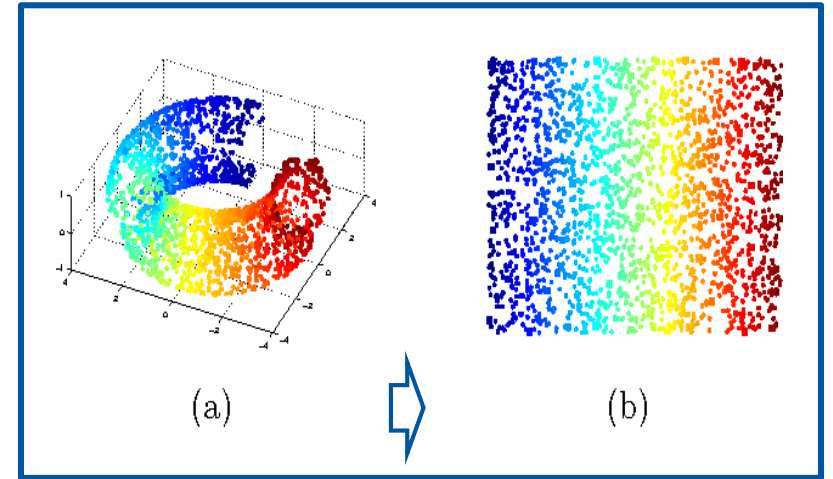
2018 Trend Data



3. Exploration

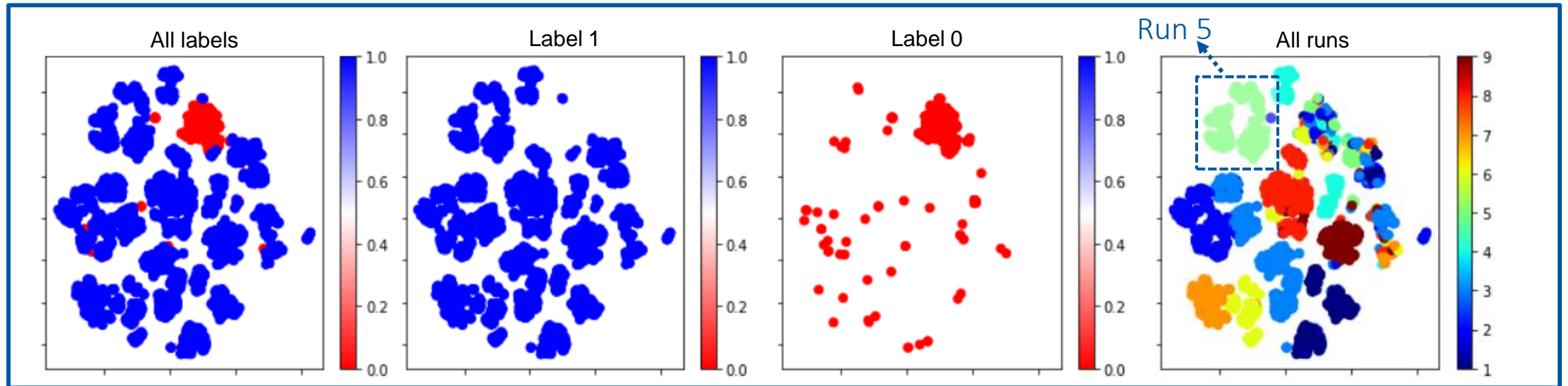
Goal: Easy and general method to explore multidimensional dataset.

- 2D t-SNE (t-Distributed Stochastic Neighbor Embedding)
- Find projection to 2D space by retaining most important information
- Axes are arbitrary



2D t-SNE of XBOX 2 Trend Data (during stable operation)

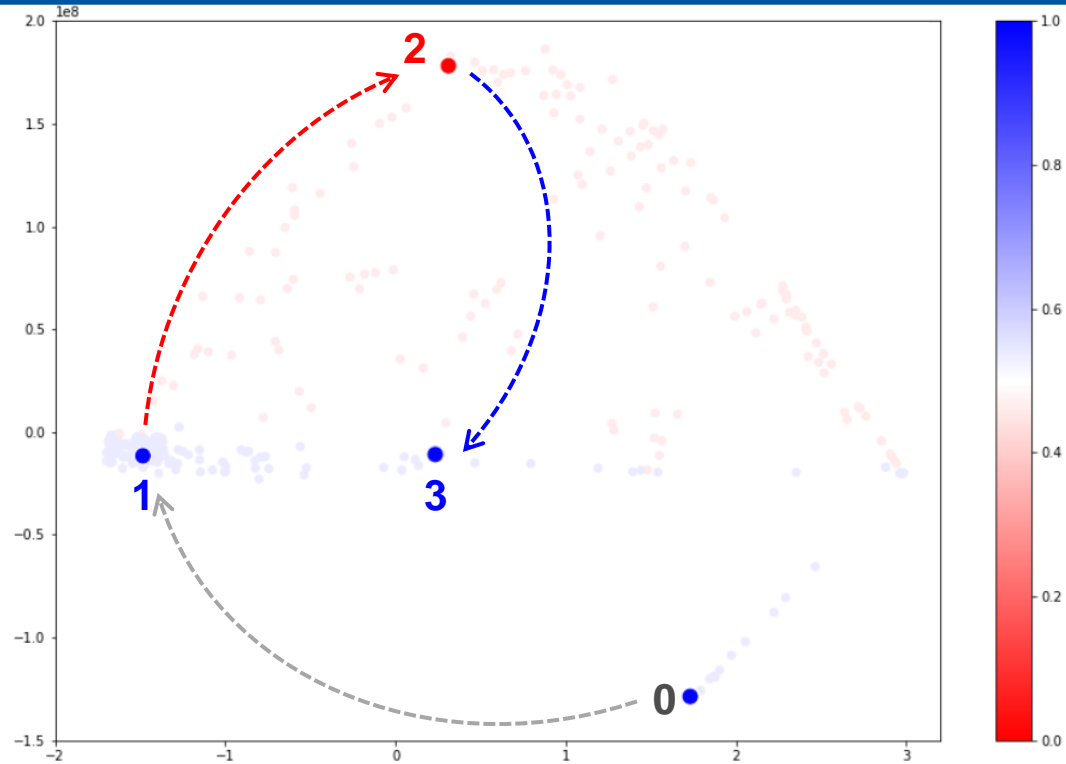
1 ... healthy
0 ... faulty



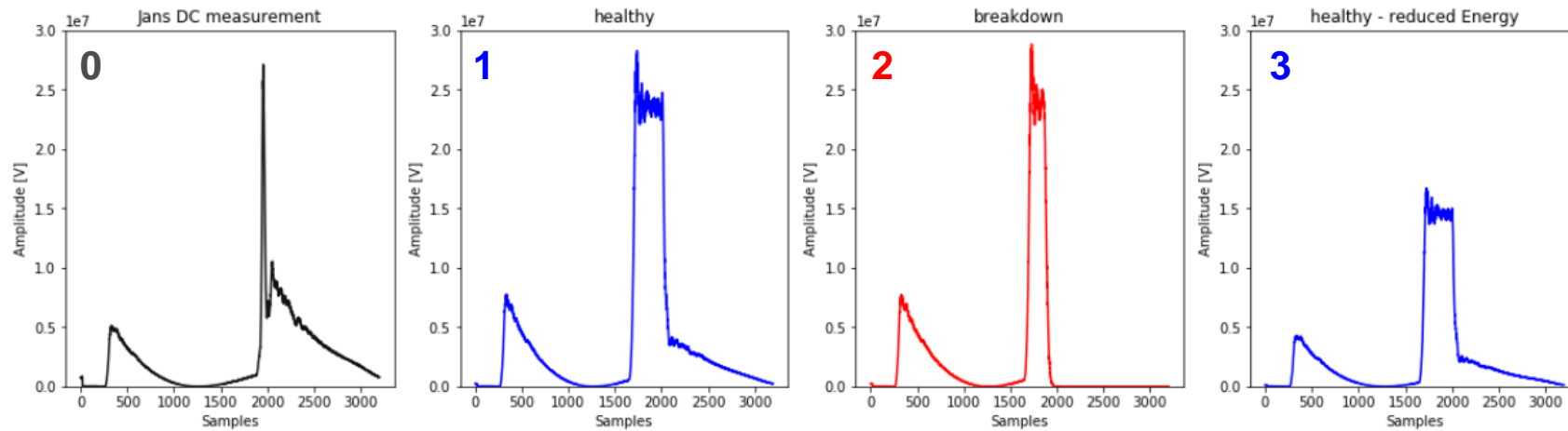
3. Dimension Reduction with 2D-tSNE

Data:

- Event data signal (timeseries):
PEI Amplitude
- Date: 20-26.01.2018
- Axes represent arbitrary



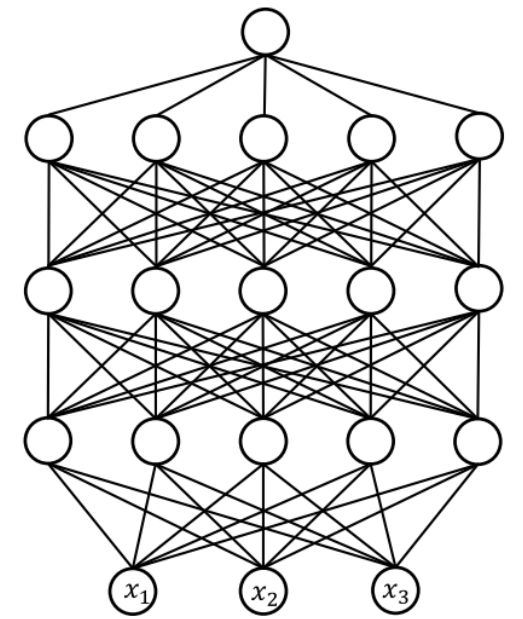
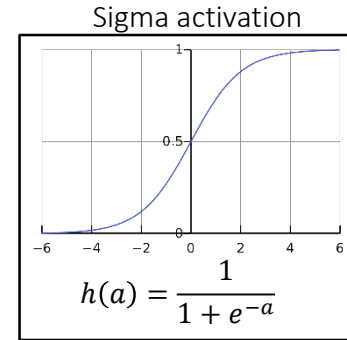
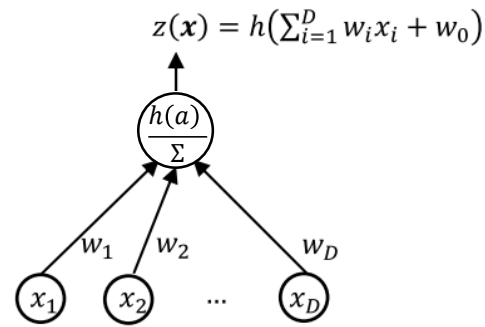
	label_CLIC	timestamp
0	1	2018-01-26 14:52:30.443347
1	1	2018-01-26 14:59:50.549269
2	0	2018-01-26 15:26:23.099318
3	1	2018-01-26 15:26:28.481433



4. Introduction to Neural Networks

Perceptron:

Main component of neural network

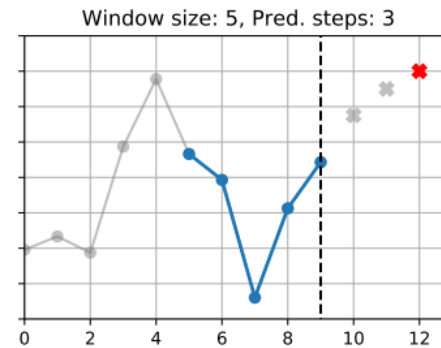
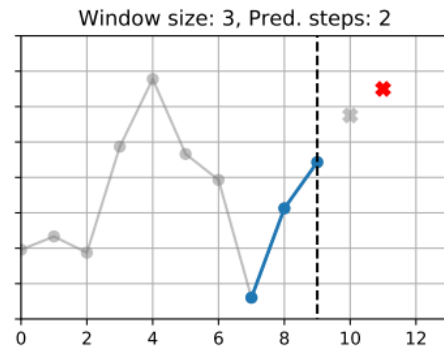
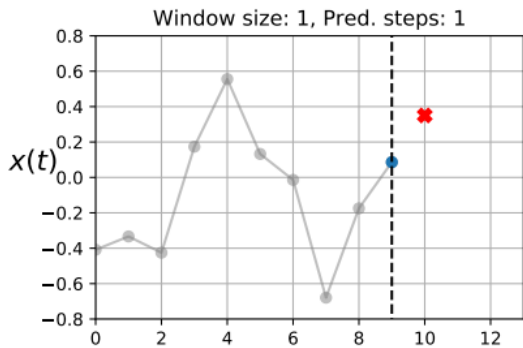


Neural networks:

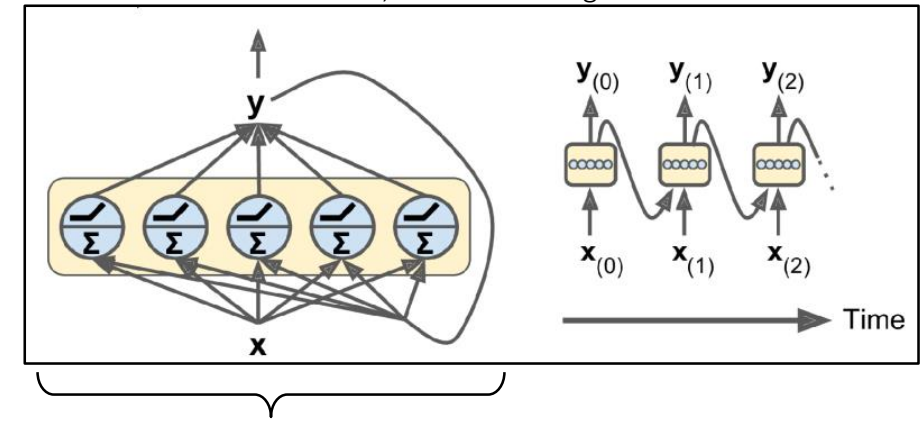
Many layers of perceptrons makes it possible to find nonlinear properties (deep learning)

Recurrent neural networks:

Neural Network, designed to handle sequential data



Recurrent Neurons, unrolled through time:



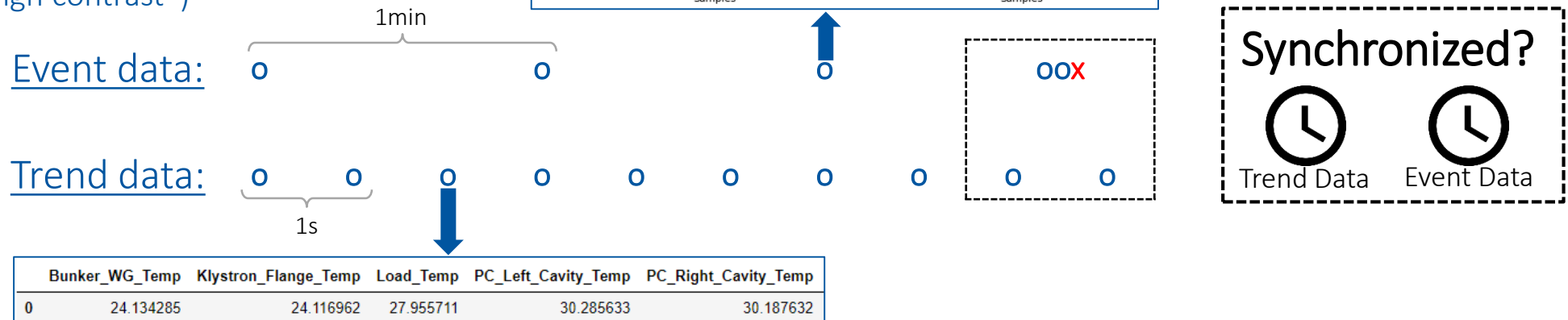
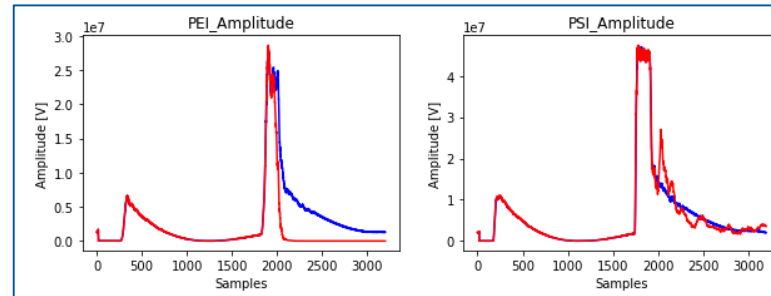
window size = 5



4. Merging of Event Data with Trend Data

Input data:

- Different sampling time of event data (~20ms/1min) and trend data (~1s)
- Clean the data such that we do not give the answer (“high contrast”)



4. Modeling Properties

Class imbalance (within runs):

“healthy”: 124448, “faulty”: 479 (250 are follow up bd)

Balanced accuracy:

Accuracy which takes class imbalance into consideration.

Labels:

Own labels were created:

$$label = \begin{cases} 0 & \text{if } \min(dc \text{ up}) \text{ or } \min(dc \text{ down}) < -0.05 \\ 1 & \text{otherwise} \end{cases}$$

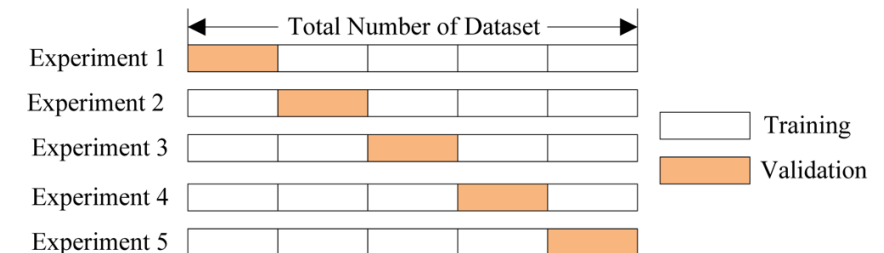
We ignored reflected signals, because DC signal is the most reliable filter for structure breakdown

Leave one out crossvalidation:

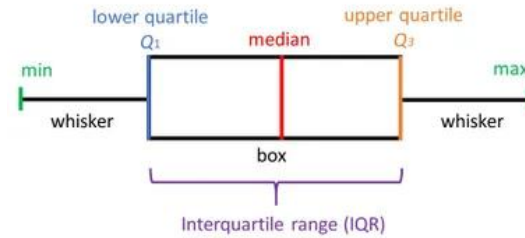
Iterate through dataset using a different run for validation each time

e.g. train model on run 1-8, validate on run 9 - transfer information of run 1-8 to run 9

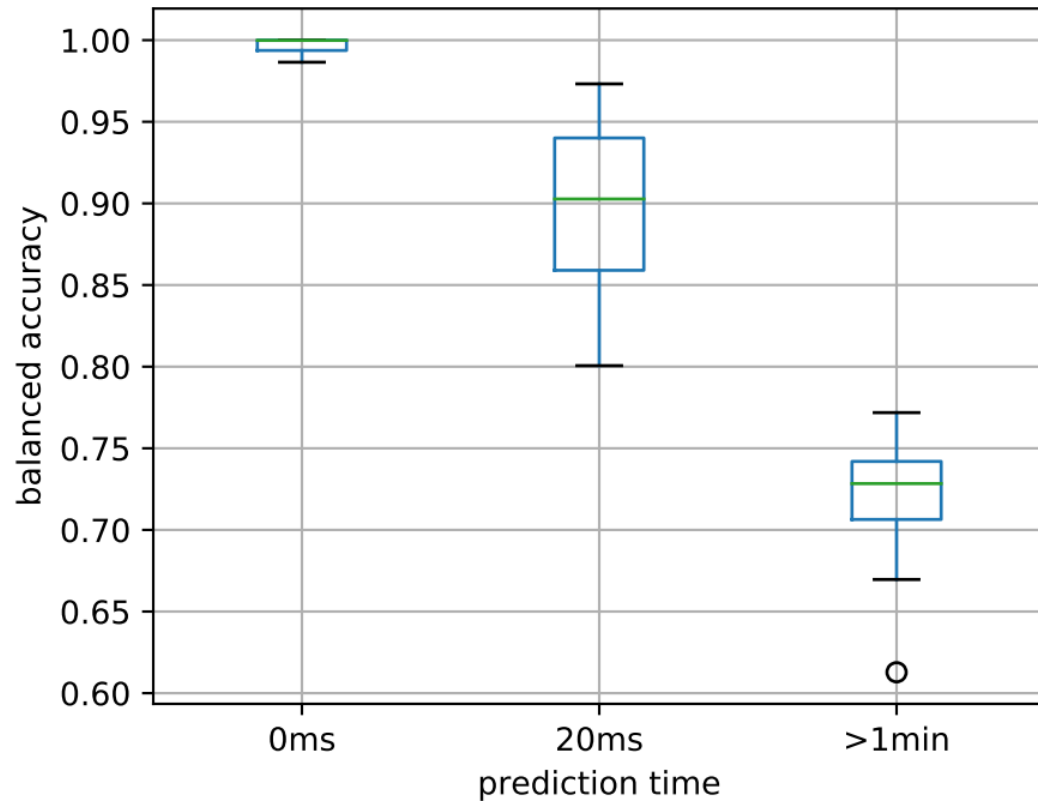
then train model on run 1-7,9, validate on run 8...



4. Results



Window size: 1



Conclusion:

0ms: Almost 100% accuracy on classification

- 0ms: Network only had to restore thresholds on DC
- Important features: DC

20ms: Still good prediction accuracy

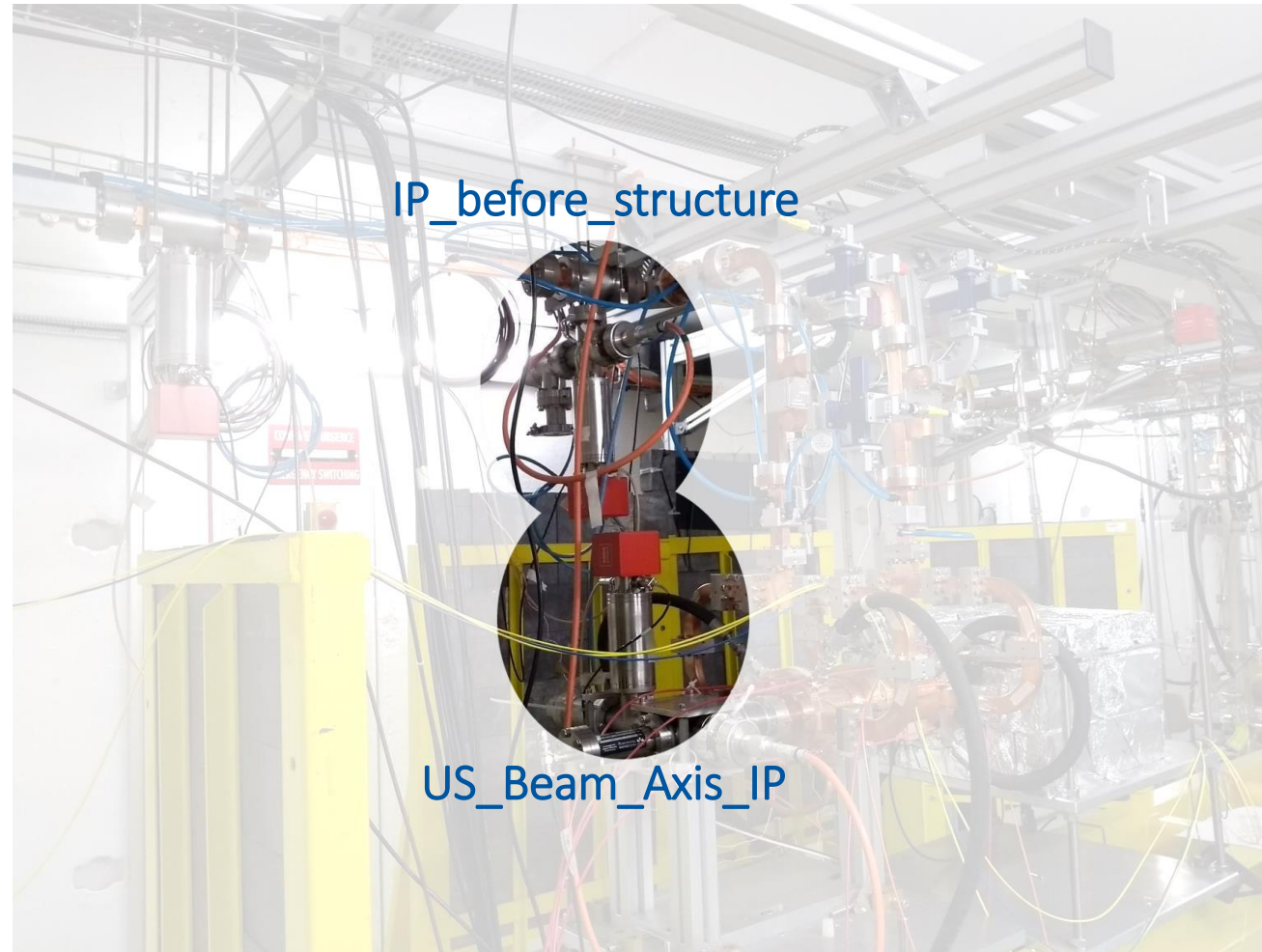
- Important features:
 - US_Beam_Axis_IP
 - IP_before_structure

>1min: Prediction of follow up breakdowns possible

Best results with window size 1:

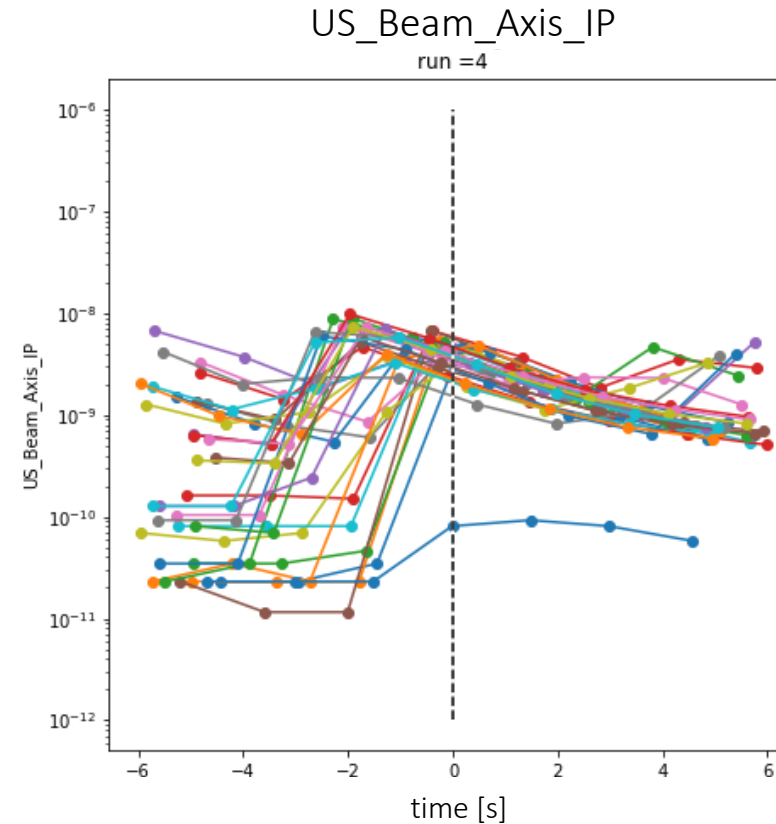
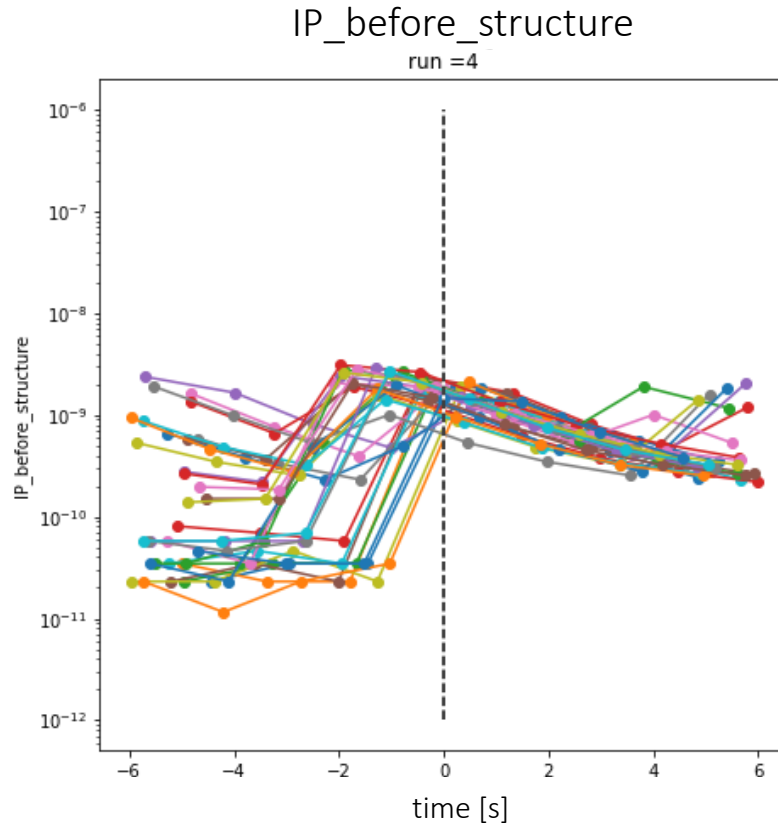
- Breakdowns depend strongest on last value

4. Important Features



4. Important Features

20ms: Does the good result come from data misalignment or is it a real precursor?



5. Conclusion

- Framework for Transformation, Exploration, Modeling available on gitlab
- Transformation:
 - Significant data cleaning performed
- Exploration:
 - Unsupervised: Clear clusters visible when using dimension reduction with 2D t-SNE
- Modeling:
 - Supervised: Good performance on prediction, (if sampling is correct).
- More refinement of the models needed with the ultimate goal of having an operational tool for precursor identification
- Support / comments from RF experts essential: Does it make sense that those features have such a high impact?

6. Outlook

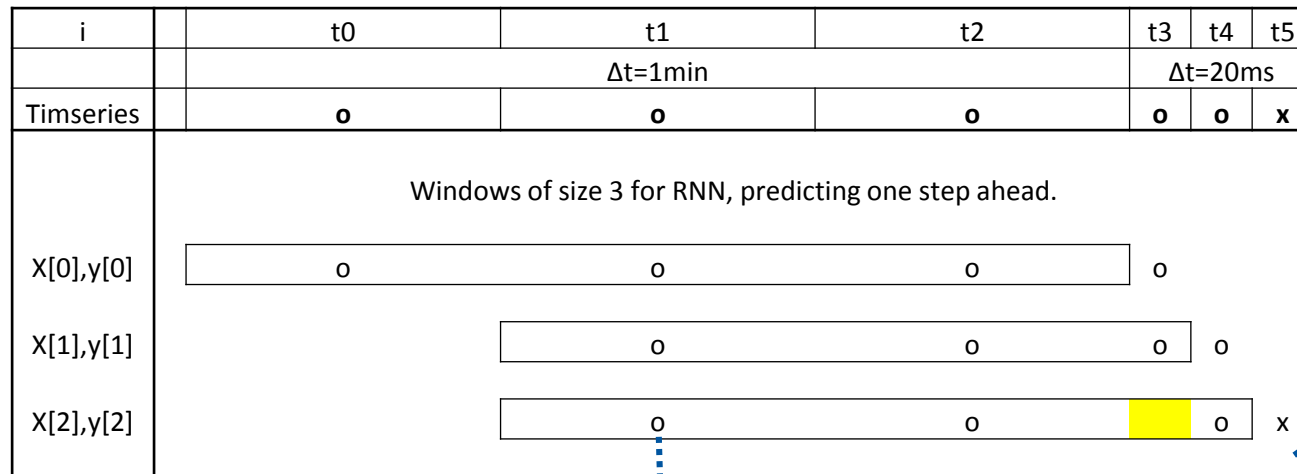
- Use raw time series for prediction, automatic feature calculation
 - Higher accuracy expected, but CPU / GPU expensive
 - Has there been any prior similar analysis?
 - Are there additional representative features which we could calculate out of the time series, to improve accuracy?
- Is it possible to log trend data with same frequency of BD event data for upcoming tests?
- Find physics meaning of good classification result
 - Support / comments from RF experts essential
- Use additional data from other test runs
- Long term goal: Implement model in test stand (if model proves to be robust enough)



High Contrast Function

Clean the data such that we do not give the answer:

- Δt is not stored in Matrix, but RNN can detect the different Gradient
- “High Contrast” example for window size = 3, predicting 1 step into the future.



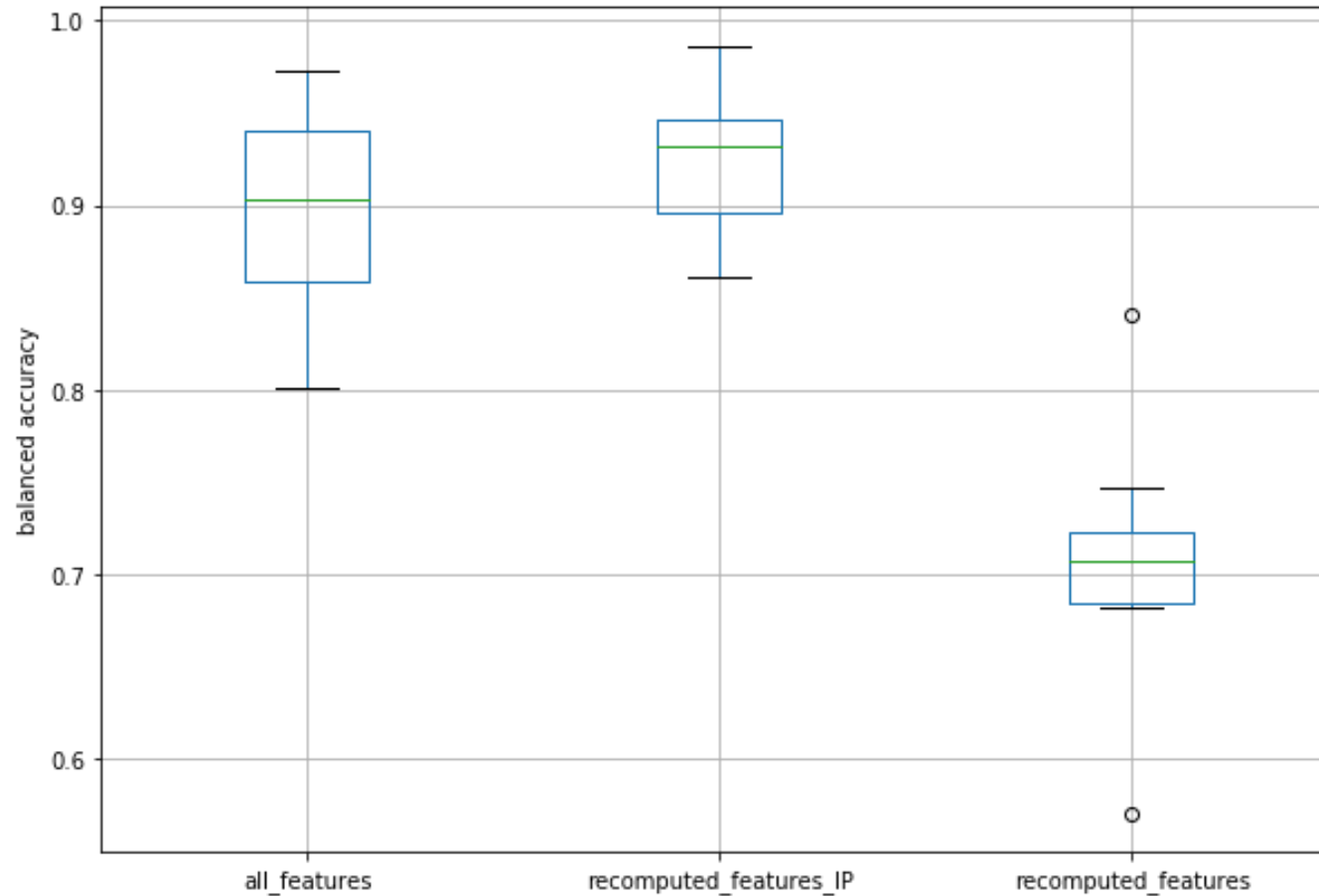
Bunker_WG_Temp	Klystron_Flange_Temp	Load_Temp	PC_Left_Cavity_Temp	PC_Right_Cavity_Temp
24.134285	24.116962	27.955711	30.285633	30.187632

X[2,0]

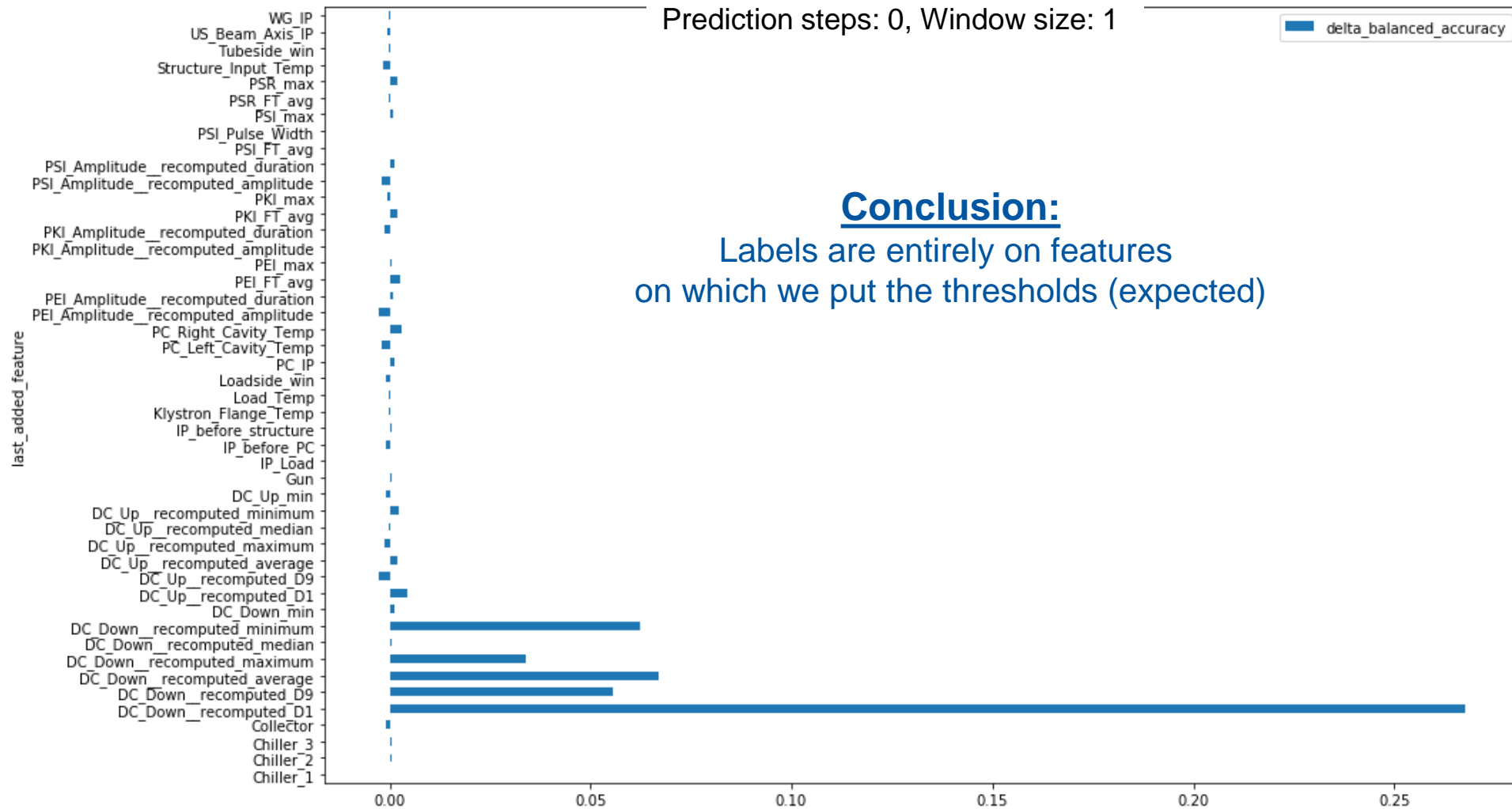
y[2]=0

Results

Prediction steps: 1, Window size: 1



Feature Importance



Feature Importance

