

Multiscale pentagon integrals to all orders

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based on work in collaboration with D. Canko and C. Papadopoulos

[arXiv:2009.13917 \[hep-ph\]](#) (JHEP)

[arXiv:2010.06947 \[hep-ph\]](#) (JHEP)

[arXiv:2012.10635 \[hep-ph\]](#)

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 - One-mass pentagon
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Motivation

- Indications for the need of physics Beyond the Standard Model mostly from Cosmology (e.g. is dark matter a new particle/ particles?).
- Absence of a clear signal for BSM physics from the LHC → Collider Physics at the Precision Frontier¹.
- Measured cross sections are being compared to improved theoretical predictions looking for deviations from the SM → constraints on BSM physics.
- LHC Run 3 and HL-LHC Run will require at least NNLO corrections.
- 2 → 3 current precision frontier at NNLO.
- Numerical approaches not efficient (physical kinematics) → need for analytical results.



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¹G. Heinrich, arXiv:2009.00516 [hep-ph]



Motivation

State-of-the-art for $2 \rightarrow 3$ NNLO calculations (focus on **Master Integrals**):

- All Master Integrals involving massless particles are known.
- All planar Master Integrals with up to one off-shell leg are known.
- Recent progress in non-planar two-loop Master Integrals with one off-shell leg (see talks from C. Papadopoulos and B. Page).



Motivation

State-of-the-art for $2 \rightarrow 3$ NNLO calculations (focus on **Master Integrals**):

- All Master Integrals involving massless particles are known.
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- Recent progress in non-planar two-loop Master Integrals with one off-shell leg (see talks from C. Papadopoulos and B. Page).

Looking ahead:

- At some point we will have to go beyond processes with one massive external particle and with internal masses.
- Starting point: one-loop five-point Master Integrals with $n \geq 1$ off-shell legs and $m \geq 1$ internal masses.

This talk: **Pentagons with up to three off-shell legs.**



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Computing Master Integrals **analytically**

- IBP reduction identifies a minimal set of Master Integrals, called basis of MI \mathbf{G} .
- Use DE to compute them.

$$\frac{\partial}{\partial s_{ij}} \mathbf{G} = \mathbf{A}(\{s_{ij}\}, \epsilon) \mathbf{G} \quad (1)$$

- In general the matrix \mathbf{A} can be very complicated.
- *Canonical revolution*²: instead of \mathbf{G} use a special basis $\mathbf{g} = \mathbf{T}\mathbf{G}$ for which

$$d\mathbf{g} = \epsilon \sum_a d \log(W_a) \tilde{\mathbf{M}}_a \mathbf{g} \quad (2)$$



²J. M. Henn, Phys. Rev. Lett. **110** (2013), 251601



Computing Master Integrals **analytically**

- When W_a are *rational* functions of the differential variables, solved with recursive iterations in terms of Goncharov PolyLogarithms (GPLs)

$$\mathcal{G}(a_1, a_2, \dots, a_n; x) = \int_0^x \frac{dt}{t - a_1} \mathcal{G}(a_2, \dots, a_n; t) \quad (3)$$

$$\mathcal{G}(0, \dots, 0; x) = \frac{1}{n!} \log^n(x) \quad (4)$$

- For 5-point integrals going beyond weight 3 is a non-trivial task.
- Algebraic letters W_a prohibit a direct integration in terms of GPLs (roots arising from massive 3-point functions and Gramm determinant of external momenta).



Computing Master Integrals **analytically**

- **Simplified Differential Equations approach** (SDE)³: introduce an external parameter x and differentiate wrt it.
- Combine with canonical (pure) basis \mathbf{g} :

$$\partial_x \mathbf{g} = \epsilon \sum_b \frac{1}{x - l_b} \mathbf{M}_b \mathbf{g} \quad (5)$$

- In many cases the new letters $W'_b = x - l_b$ are fully rationalised wrt x .
- Solution of canonical SDE trivially expressed in terms of GPLs.
- Boundary terms: compute $x \rightarrow 0$ limit with expansion-by-regions method.



C. G. Papadopoulos, JHEP **07** (2014), 088



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One-mass pentagon: Kinematics

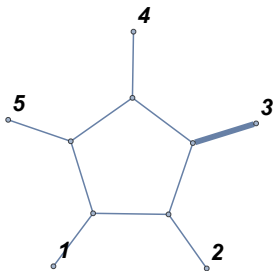


Figure: 13 MI.

- External momenta q_i , $i = 1 \dots 5$

$$\sum_1^5 q_i = 0, \quad q_3^2 \equiv m^2, \quad q_i^2 = 0, \quad i = 1, 2, 4, 5$$

$$\{q_3^2, s_{12}, s_{23}, s_{34}, s_{45}, s_{15}\}, \quad \text{with } s_{ij} := (q_i + q_j)^2$$



One-mass pentagon: SDE parametrization

$$q_1 = xp_1, \quad q_2 = xp_2, \quad q_3 = p_{123} - xp_{12}, \quad q_4 = -p_{123}, \quad q_5 = -p_{1234} \quad (6)$$

- Underline momenta p_i , $i = 1 \dots 5$
- $\sum_1^5 p_i = 0$, $p_i^2 = 0$, $i = 1 \dots 5$, with $p_{i\dots j} := p_i + \dots + p_j$
- $\{S_{12}, S_{23}, S_{34}, S_{45}, S_{51}, x\}$, with $S_{ij} := (p_i + p_j)^2$
- Mapping of kinematic invariants:

$$m^2 = (x - 1)(S_{12}x - S_{45}), \quad s_{12} = S_{12}x^2, \quad s_{23} = S_{23}x - S_{45}x + S_{45},$$

$$s_{34} = x(S_{12}(x - 1) + S_{34}), \quad s_{45} = S_{45}, \quad s_{51} = S_{51}x$$



One-mass pentagon: Pure basis

Top-sector pure basis element:

$$\epsilon^2 \frac{\mathcal{P}_{11111}}{\Delta_5} G_{11111} \quad (8)$$

- $$G_{a_1 a_2 a_3 a_4 a_5} = \int \frac{d^d k_1}{i\pi^{(d/2)}} \frac{e^{\epsilon\gamma E}}{\mathcal{D}_1^{a_1} \mathcal{D}_2^{a_2} \mathcal{D}_3^{a_3} \mathcal{D}_4^{a_4} \mathcal{D}_5^{a_5}}$$

$$\mathcal{D}_1 = -(k_1)^2, \quad \mathcal{D}_2 = -(k_1 + q_1)^2, \quad \mathcal{D}_3 = -(k_1 + q_1 + q_2)^2$$

$$\mathcal{D}_4 = -(k_1 + q_1 + q_2 + q_3)^2, \quad \mathcal{D}_5 = -(k_1 + q_1 + q_2 + q_3 + q_4)^2 \quad (9)$$

- \mathcal{P}_{11111} is the Baikov polynomial of G_{11111} .

$$\Delta_5 = \sqrt{\det[q_i \cdot q_j]}$$



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One-mass pentagon: Canonical SDE & boundaries

$$\partial_x \mathbf{g} = \epsilon \left(\sum_{i=1}^{11} \frac{\mathbf{M}_i}{x - l_i} \right) \mathbf{g} \quad (10)$$



One-mass pentagon: Canonical SDE & boundaries

$$\partial_x \mathbf{g} = \epsilon \left(\sum_{i=1}^{11} \frac{\mathbf{M}_i}{x - l_i} \right) \mathbf{g} \quad (10)$$

- \mathbf{M}_i independent of the kinematics.
- All kinematic dependence in l_i .
- Resummation matrix for $l_1 = 0$, ($\mathbf{M}_1 = \mathbf{S}\mathbf{D}\mathbf{S}^{-1}$)

$$\mathbf{R} = \mathbf{S} e^{\epsilon \mathbf{D} \log(x)} \mathbf{S}^{-1} \quad (11)$$

- $\mathbf{g} = \mathbf{T}\mathbf{G}$
- Expansion-by-regions: $G_i \underset{x \rightarrow 0}{=} \sum_j x^{b_j + a_j \epsilon} G_i^{(b_j + a_j \epsilon)}$

$$\mathbf{R}\mathbf{b} = \lim_{x \rightarrow 0} \mathbf{T}\mathbf{G} \Big|_{\mathcal{O}(x^{0+a_j \epsilon})}, \quad \mathbf{b} = \sum_{i=0}^n \epsilon^i \mathbf{b}_0^{(i)}$$



One-mass pentagon: Solution up to weight four

$$\begin{aligned}
 \mathbf{g} = & \epsilon^0 \mathbf{b}_0^{(0)} + \epsilon \left(\sum \mathcal{G}_a \mathbf{M}_a \mathbf{b}_0^{(0)} + \mathbf{b}_0^{(1)} \right) \\
 & + \epsilon^2 \left(\sum \mathcal{G}_{ab} \mathbf{M}_a \mathbf{M}_b \mathbf{b}_0^{(0)} + \sum \mathcal{G}_a \mathbf{M}_a \mathbf{b}_0^{(1)} + \mathbf{b}_0^{(2)} \right) \\
 & + \epsilon^3 \left(\sum \mathcal{G}_{abc} \mathbf{M}_a \mathbf{M}_b \mathbf{M}_c \mathbf{b}_0^{(0)} + \sum \mathcal{G}_{ab} \mathbf{M}_a \mathbf{M}_b \mathbf{b}_0^{(1)} + \sum \mathcal{G}_a \mathbf{M}_a \mathbf{b}_0^{(2)} + \mathbf{b}_0^{(3)} \right) \\
 & + \epsilon^4 \left(\sum \mathcal{G}_{abcd} \mathbf{M}_a \mathbf{M}_b \mathbf{M}_c \mathbf{M}_d \mathbf{b}_0^{(0)} + \sum \mathcal{G}_{abc} \mathbf{M}_a \mathbf{M}_b \mathbf{M}_c \mathbf{b}_0^{(1)} \right. \\
 & \left. + \sum \mathcal{G}_{ab} \mathbf{M}_a \mathbf{M}_b \mathbf{b}_0^{(2)} + \sum \mathcal{G}_a \mathbf{M}_a \mathbf{b}_0^{(3)} + \mathbf{b}_0^{(4)} \right) \tag{13}
 \end{aligned}$$

$$\mathcal{G}_{ab\dots} := \mathcal{G}(l_a, l_b, \dots; x)$$



Boundaries in closed form.

Solution trivially extended to higher weights!



Two-mass pentagon: Kinematics

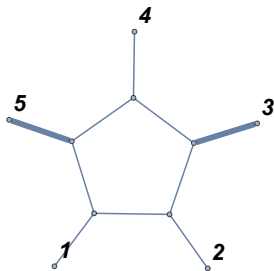


Figure: 15 MI.

- External momenta q_i , $i = 1 \dots 5$

$$\sum_1^5 q_i = 0, \{q_3^2 \equiv m_3^2, q_5^2 \equiv m_5^2\}, q_i^2 = 0, i = 1, 2, 4$$

$$\{m_3^2, m_5^2, s_{12}, s_{23}, s_{34}, s_{45}, s_{15}\}, \text{ with } s_{ij} := (q_i + q_j)^2$$



Two-mass pentagon: SDE parametrization

$$q_1 = xp_1, \quad q_2 = xp_2, \quad q_3 = p_{123} - xp_{12}, \quad q_4 = -p_{123}, \quad q_5 = -p_{1234} \quad (14)$$

- Underline momenta p_i , $i = 1 \dots 5$
- $\sum_1^5 p_i = 0$, $p_i^2 = 0$, $i = 1, 2, 3, 4$, $p_5^2 = m_5^2$, with $p_{i\dots j} := p_i + \dots + p_j$
- $\{m_5^2, S_{12}, S_{23}, S_{34}, S_{45}, S_{51}, x\}$, with $S_{ij} := (p_i + p_j)^2$



Two-mass pentagon: Canonical SDE

- Top-sector pure basis element as for one-mass pentagon.
-

$$\partial_x \mathbf{g} = \epsilon \left(\sum_{i=1}^{14} \frac{\mathbf{M}_i}{x - l_i} \right) \mathbf{g} \quad (15)$$

- Alphabet rational in x .
- Boundaries in closed form.
- Solution in terms of GLPs effectively to all orders in ϵ .



Three-mass pentagon: Kinematics

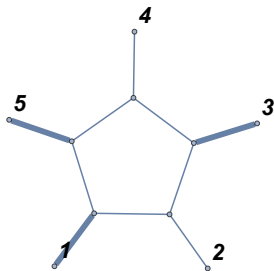


Figure: 18 MI.

- External momenta q_i , $i = 1 \dots 5$

$$\sum_1^5 q_i = 0, \{q_1^2 \equiv m_1^2, q_3^2 \equiv m_3^2, q_5^2 \equiv m_5^2\}, q_i^2 = 0, i = 2, 4$$

$$\{m_1^2, m_3^2, m_5^2, s_{12}, s_{23}, s_{34}, s_{45}, s_{15}\}, \text{ with } s_{ij} := (q_i + q_j)^2$$



Three-mass pentagon: SDE parametrization

$$q_1 = xp_1, \quad q_2 = xp_2, \quad q_3 = p_{123} - xp_{12}, \quad q_4 = -p_{123}, \quad q_5 = -p_{1234} \quad (16)$$

- Underline momenta p_i , $i = 1 \dots 5$
- $\sum_1^5 p_i = 0$, $p_i^2 = 0$, $i = 2, 3, 4$, $p_1^2 = \hat{m}_1^2$, $p_5^2 = m_5^2$, with $p_{i\dots j} := p_i + \dots + p_j$
- $\{\hat{m}_1^2, m_5^2, S_{12}, S_{23}, S_{34}, S_{45}, S_{51}, x\}$, with $S_{ij} := (p_i + p_j)^2$



Three-mass pentagon: Canonical SDE

- Top-sector pure basis element as for one-mass pentagon.
-

$$\partial_x \mathbf{g} = \epsilon \left(\sum_{i=1}^{19} \frac{\mathbf{M}_i}{x - l_i} \right) \mathbf{g} \quad (17)$$

- Alphabet rational in x .
- Boundaries in closed form.
- Solution in terms of GLPs effectively to all orders in ϵ .



Analysis of resulting functions

Family	W=1	W=2	W=3	W=4
P_{1m}	10 (2)	50 (21)	170 (99)	496 (339)
P_{2m}	9 (0)	54 (16)	204 (106)	628 (406)
P_{3m}	13 (0)	87 (24)	349 (172)	1115 (696)

Table: Number of GPLs entering in the solution. Top-sector b.e. in parenthesis.

Family	W=5	W=6
P_{1m}	1322 (959)	2983 (1924)
P_{2m}	1728 (1254)	4341 (2656)
P_{3m}	3145 (2228)	7849 (4656)

Table: Number of GPLs entering in the solution. Top-sector b.e. in parenthesis.



Numerical results in Euclidean points

Top-Sec	Time (sec)	Result
g_{13}	1.90759	$0.0944261\epsilon^3 + 0.31615\epsilon^4 + 0.666923\epsilon^5 + 1.09948\epsilon^6$
g_{15}	3.75112	$-0.120811\epsilon^3 - 0.314547\epsilon^4 - 0.616424\epsilon^5 - 0.985647\epsilon^6$
g_{18}	9.27125	$-0.0215131\epsilon^3 - 0.0332408\epsilon^4 - 0.0501992\epsilon^5 - 0.057848\epsilon^6$

Table: Numerical computation of GPLs using GiNaC.

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Conclusions

- Pure basis + SDE + Exp-by-reg. efficient computational framework for analytical computation of multiscale MI.
- Application to multiloop problems, see talks by C. Papadopoulos and D. Canko.
- Rational alphabet in $x \rightarrow$ need to study different parametrizations.
- Analytic continuation of GPLs for fast and stable numerical results in physical phase-space points.
- Next step: **introduce internal masses**.



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Thank you for your attention!



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Automated tools

- Ginac^4 for the numerical calculation of GPLs.
- PolyLogTools^5 for the algebraic manipulation of GPLs.
- FIRE6^6 and KIRA2^7 for the IBP reduction.
- FIESTA4^8 for Expansion-By-Regions.
- pySecDec^9 and FIESTA4 for numerical computation of FI, used for cross-checking our results.

⁴J. Vollinga and S. Weinzierl, *Comput. Phys. Commun.* **167** (2005), 177

⁵C. Duhr and F. Dulat, *JHEP* **08** (2019), 135

⁶A. V. Smirnov and F. S. Chuharev, arXiv:1901.07808 [hep-ph]

⁷J. Klappert, F. Lange, P. Maierhöfer and J. Usovitsch, arXiv:2008.06494 [hep-ph]

⁸A. V. Smirnov, *Comput. Phys. Commun.* **204** (2016), 189-199

⁹S. Borowka, G. Heinrich, S. Jahn, S. P. Jones, M. Kerner, J. Schlenk and T.

Comput. Phys. Commun. **222** (2018), 313-326



Scattering kinematics

- Results in Euclidean region (all initial kinematic invariants are negative).
- GPLs and solutions are real there.
- Analytic continuation to get results in physical regions for phenomenology.
- Fibration basis techniques (exploit symbol algebra and coproduct to analytically continue GPLs).
- Numerically: $\{S_{ij}, x\} \rightarrow \{S_{ij} + i\delta_{ij}\eta, x + i\delta\eta\}$ for $\eta \rightarrow 0$.
- Constraints on δ_{ij} , δ_x from one-scale integrals and second graph polynomial of top sector FI.



Accumulated results

- Fully analytical results for all MI for $2 \rightarrow 2$ with up to one mass in all kinematic regions.
- Analytical results for all MI for $2 \rightarrow 2$ with two masses in Euclidean region (numerical analytic continuation for physical regions)¹⁰¹¹¹².
- All planar 2-loop MI for $2 \rightarrow 3$ with up to one mass.
- Two planar families for $2 \rightarrow 2$ with up to one mass at three loops¹³.
- Pentagon with up to one massive leg to all orders¹⁴.

¹⁰C. G. Papadopoulos, D. Tommasini and C. Wever, JHEP **01** (2015), 072

¹¹J. M. Henn, K. Melnikov and V. A. Smirnov, JHEP **05** (2014), 090

¹²F. Caola, J. M. Henn, K. Melnikov and V. A. Smirnov, JHEP **09** (2014), 043

¹³D. D. Canko and NS, [arXiv:2010.06947 [hep-ph]]

¹⁴NS, [arXiv:2012.10635 [hep-ph]]

