

CLICTD TEST-BEAM RESULTS

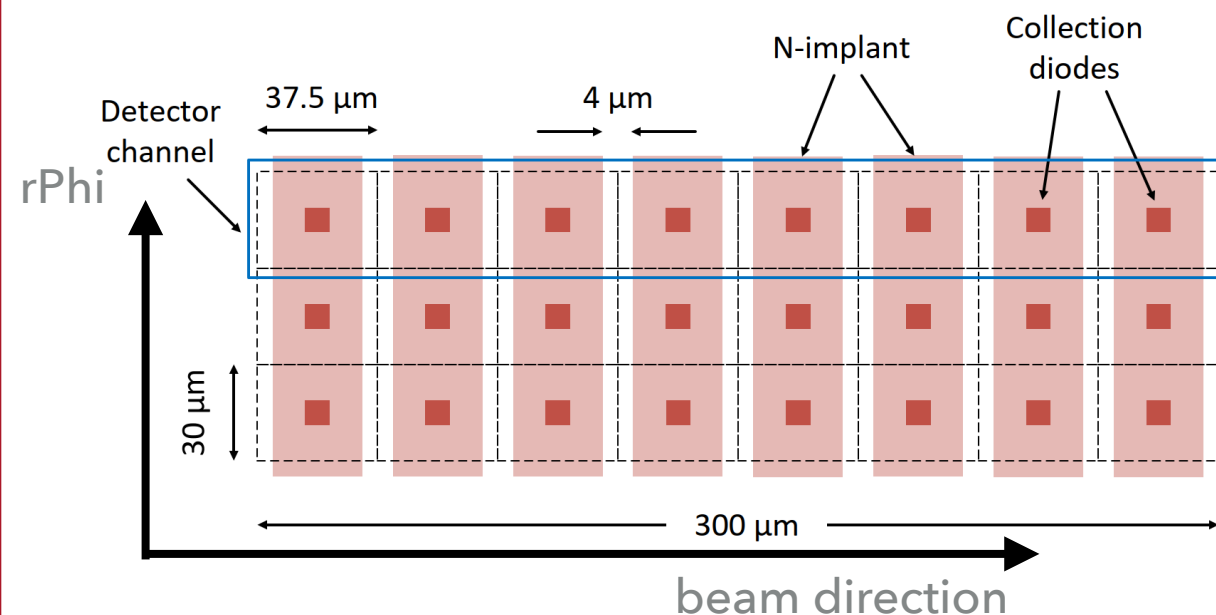
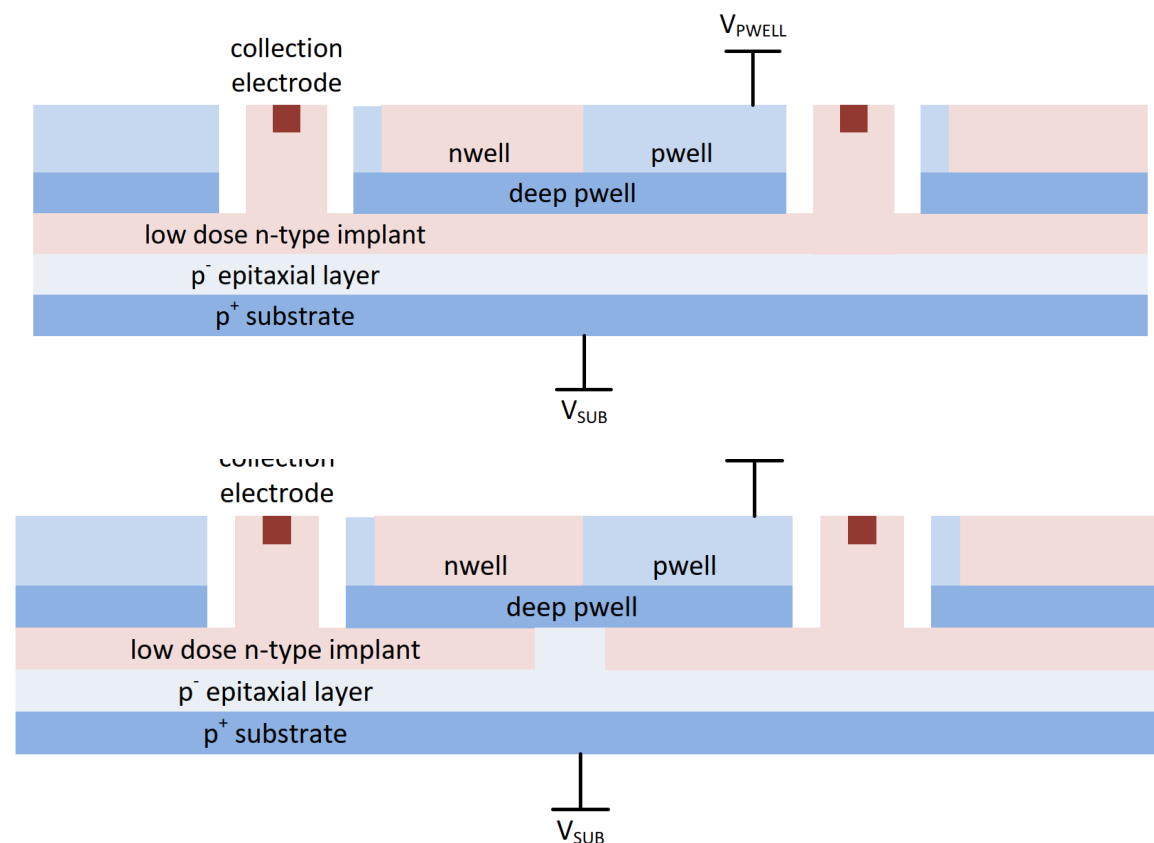
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CLICdp Collaboration Meeting

01/10/2020

- CLICTD (180 nm CMOS imaging process) was designed in **two process variants**
- Gap in the n-type implant was introduced in one spatial dimension to **speed up charge collection**
- **Epitaxial layer: 30 μm**
- **Bias voltage** applied to **substrate and p-wells**, best performance expected at -6V/-6V

- Channel pitch: 300 μm x 30 μm (16x128 channels)
- Sub-pixel pitch: **37.5 μm x 30.0 μm**
- Analogue front-end of **8 sub-pixels are grouped together** in one digital front-end (= detector channel)
- Frame-based readout with 40 MHz
- 8-bit ToA (10 ns ToA bins) + 5-bit ToT (combined ToA/ToT for every 8 sub-pixels in 300 μm dimension)



CLICTD TEST-BEAM MEASUREMENTS JULY/AUGUST 2020



Very successful test-beam periods where we tested various assemblies (different thicknesses, different processes) at different bias voltages, different thresholds and different rotation angles → **huge parameter space**

Effect of different bias voltages

- Sensor at -3V/-3V and minimum threshold
- Threshold scans for -3V / -3V

Comparison of process variants

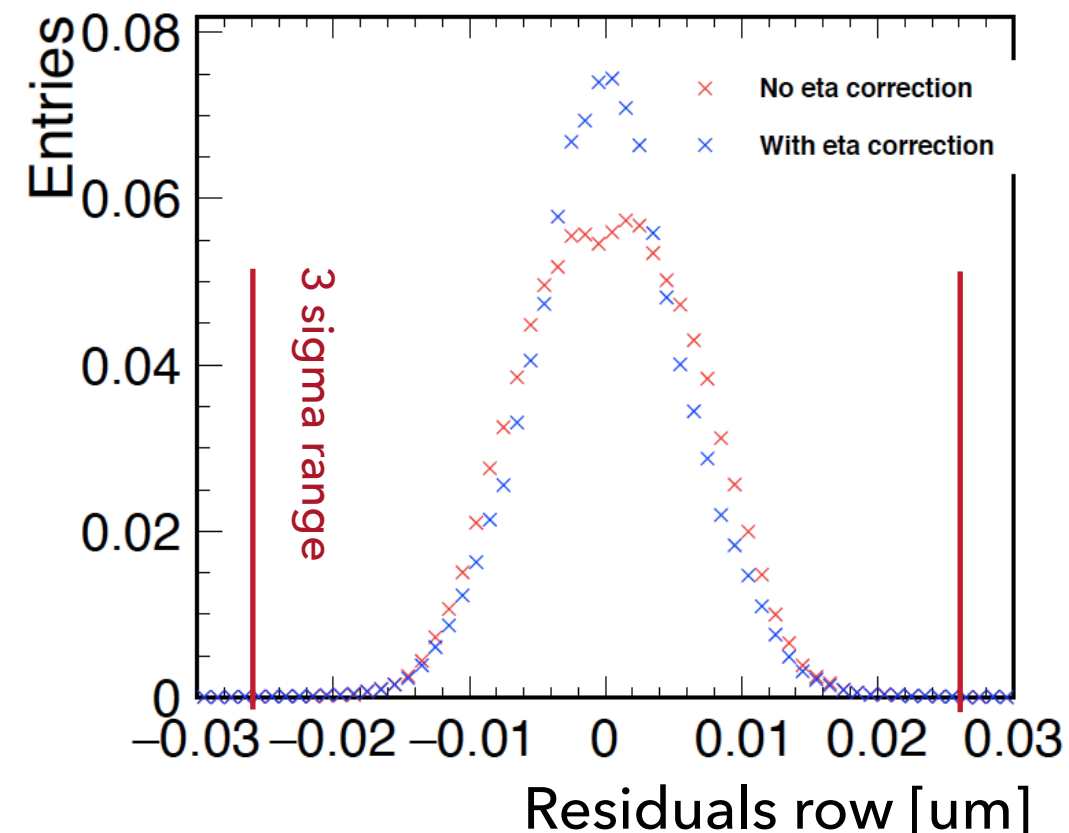
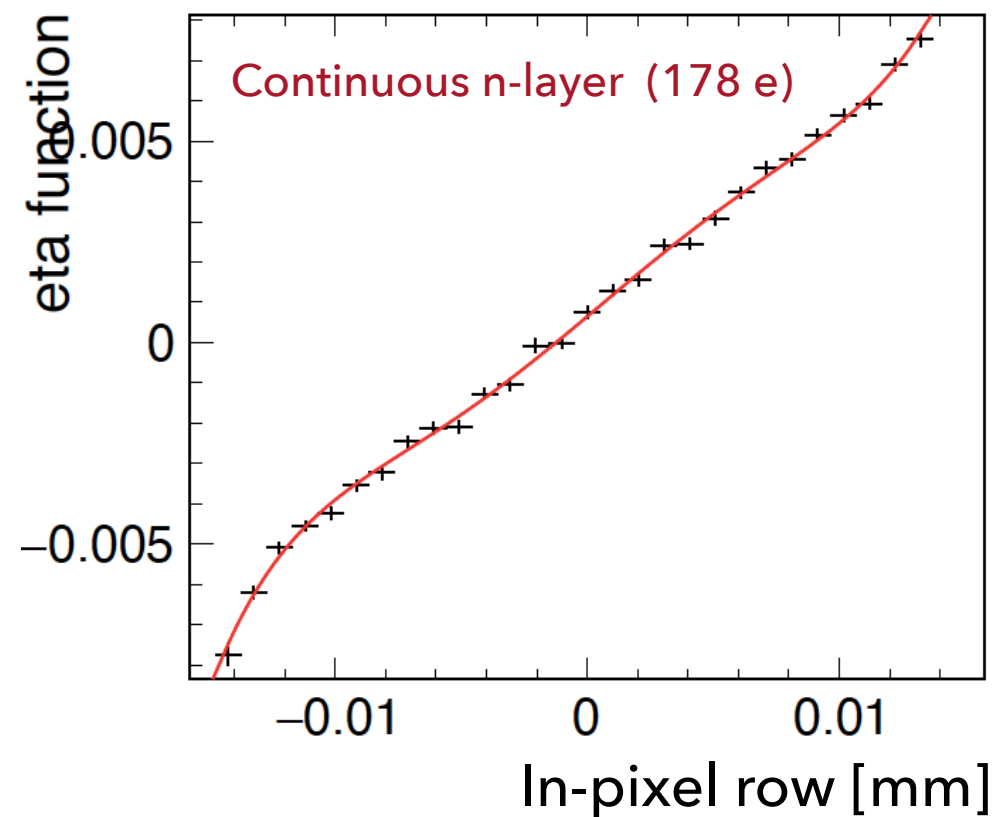
- Nominal data for an assembly with and without gap in the n-layer at the same threshold
- Threshold scans for both process variants

Thinned assemblies

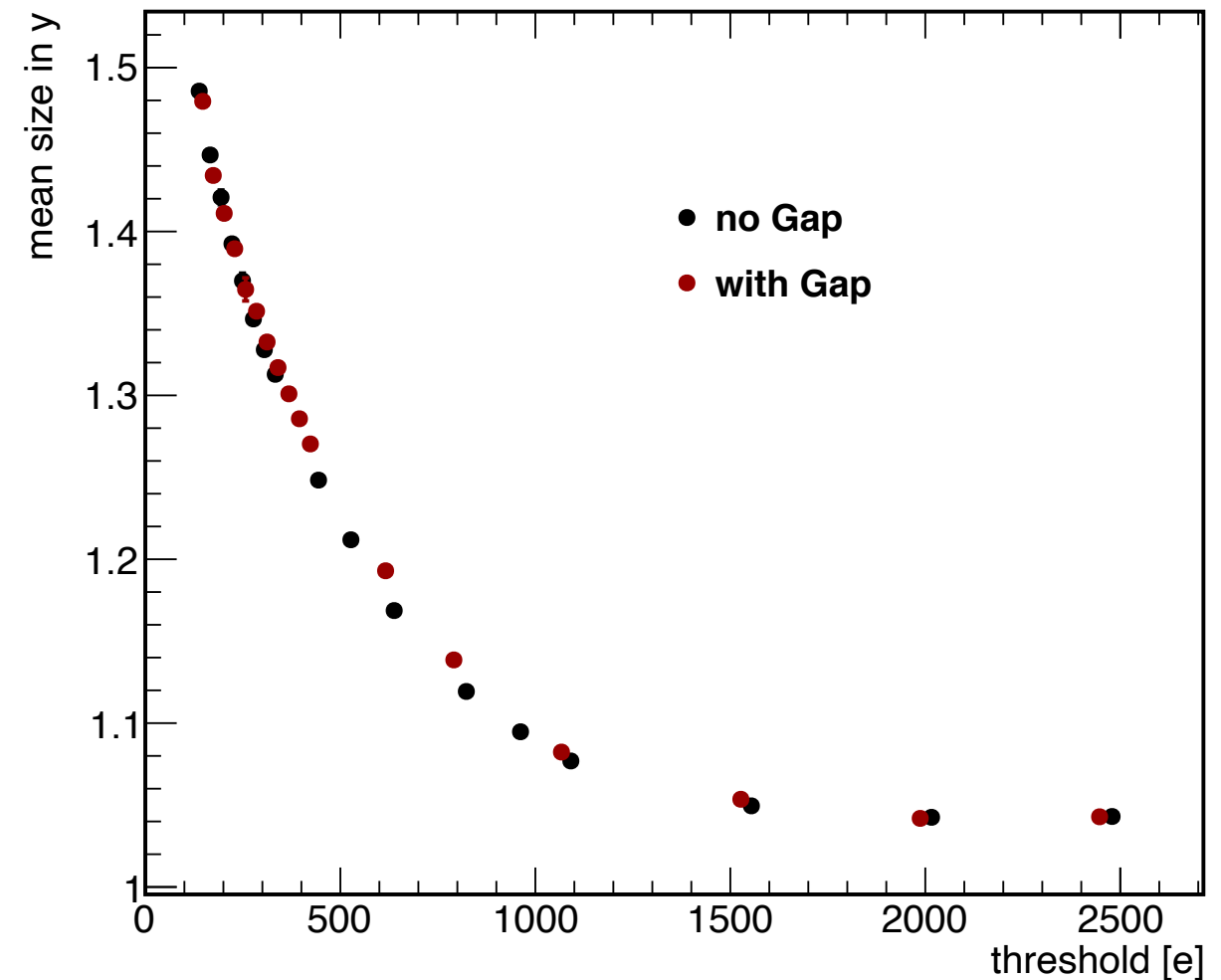
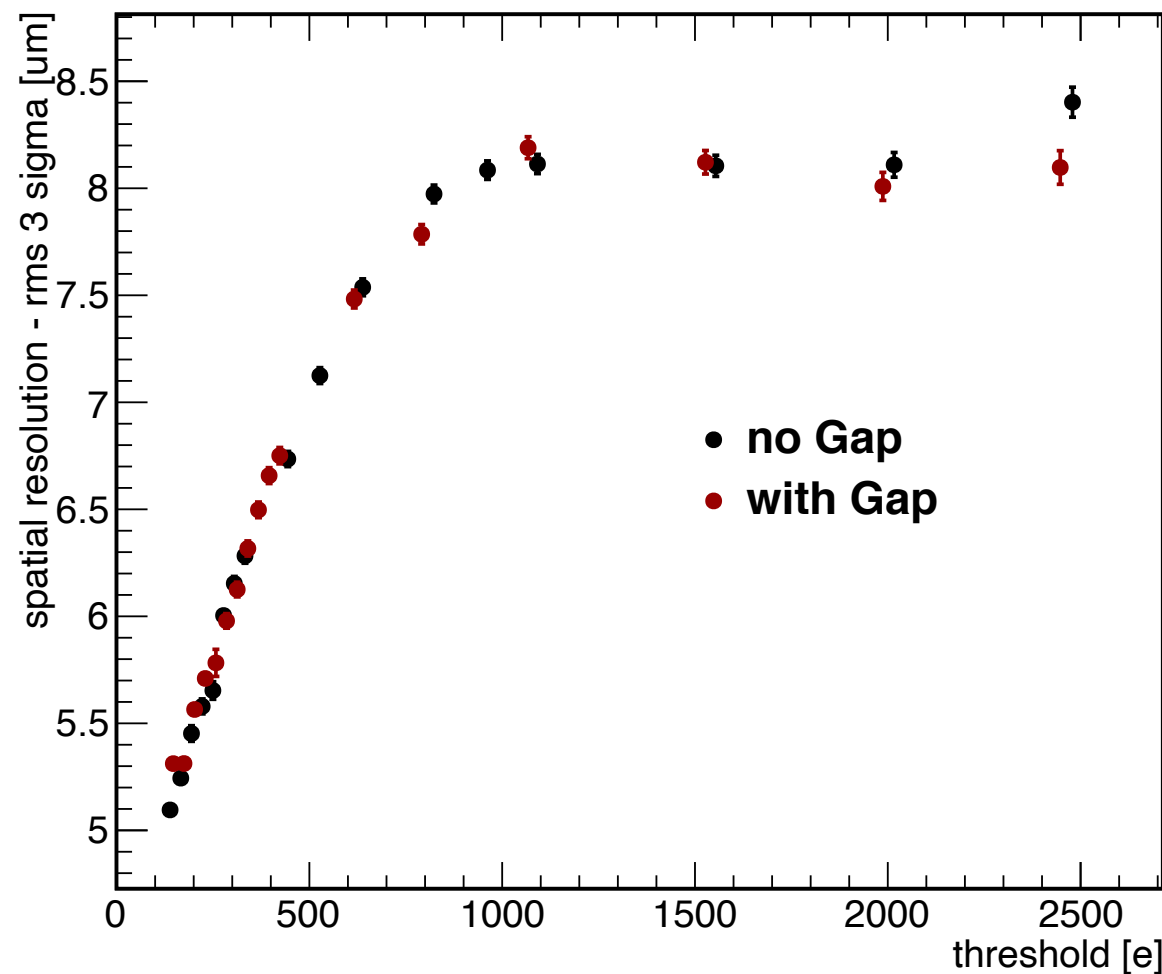
- Nominal data and threshold scans for assemblies thinned down to 50 um and 100 um of both processes variants

Rotation scans

- Rotation data (0 deg up to 90 deg) for various assemblies, including thinned assemblies around both rotation axes

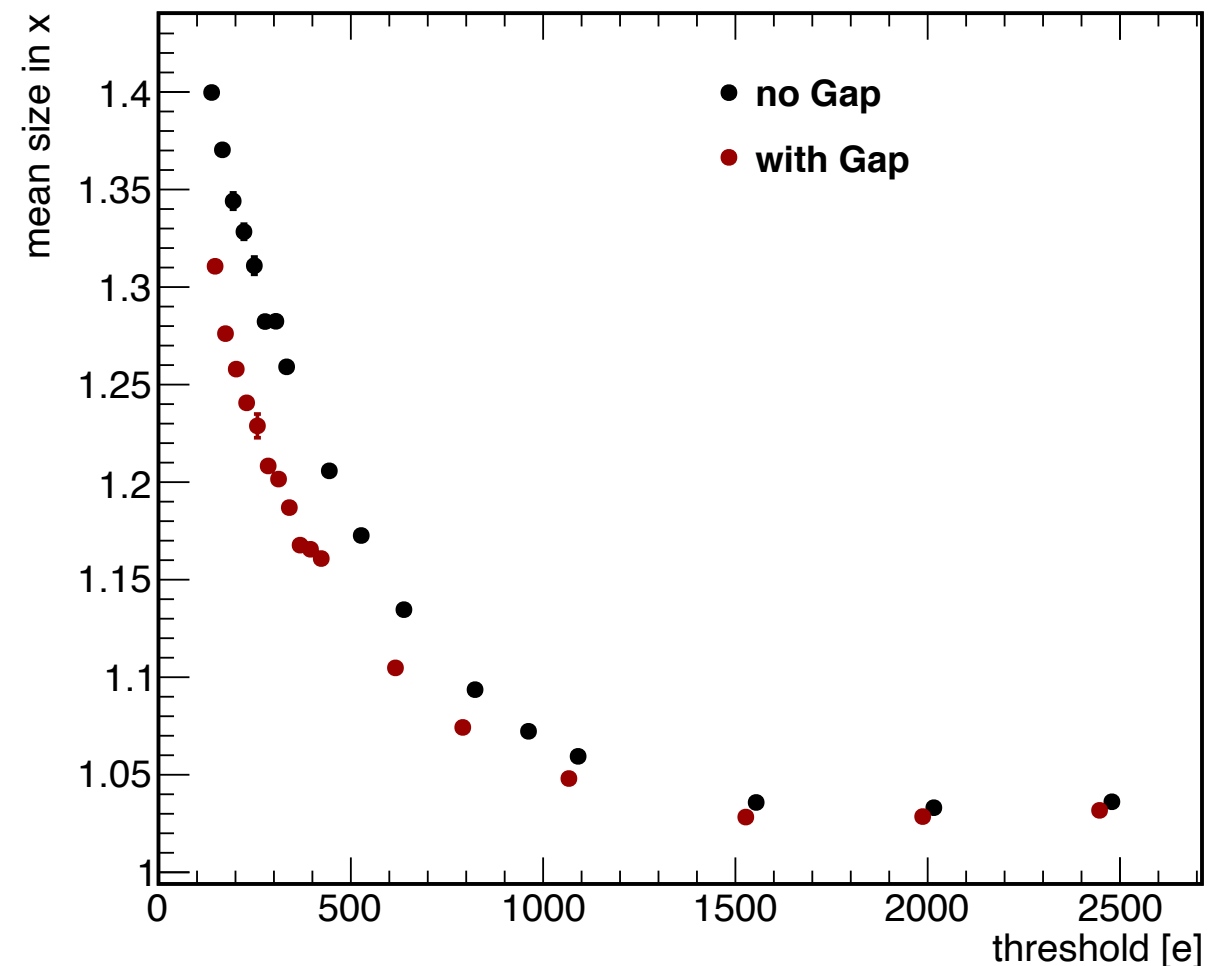
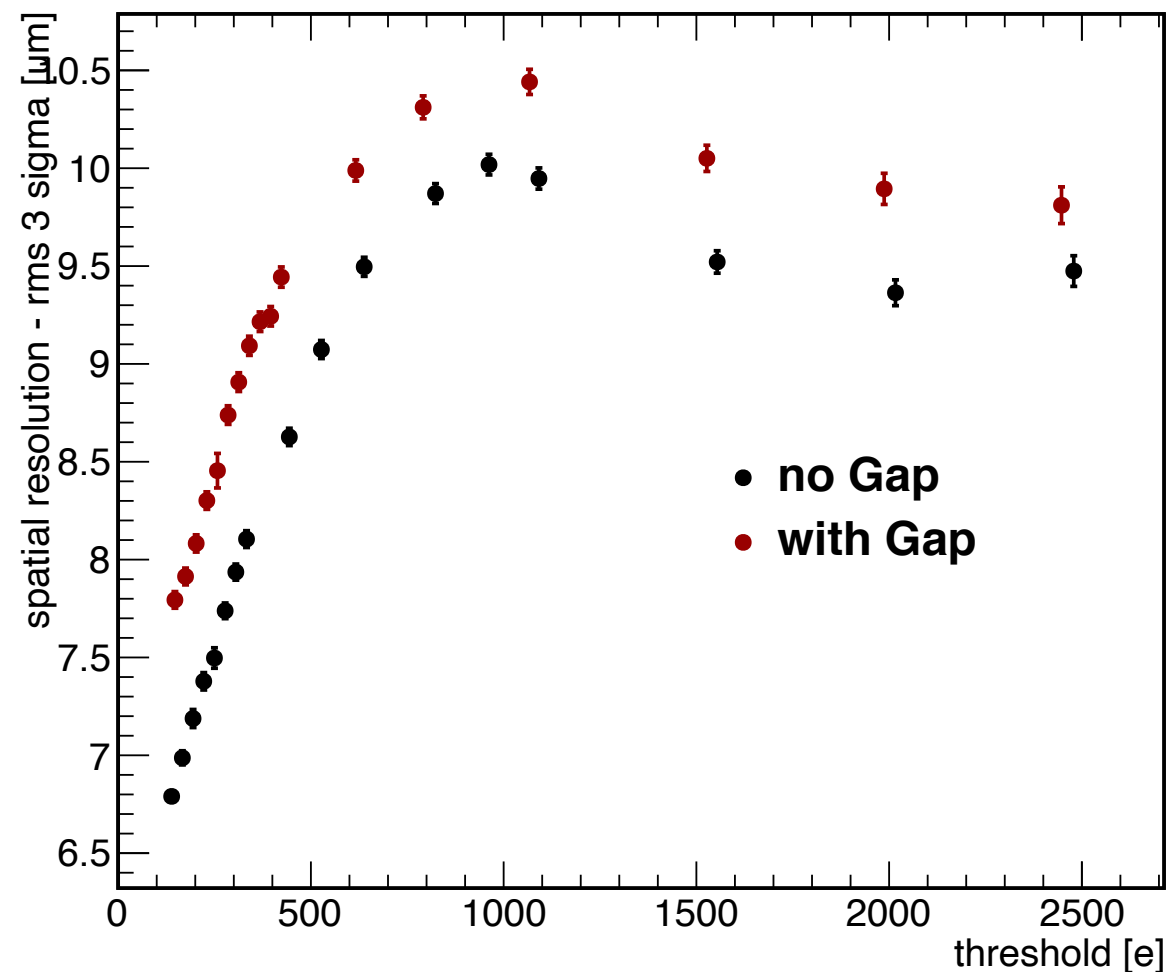


- **Cluster position** for multi-pixel clusters first determined with **charge-weighted centre-of-gravity algorithm** (assumes linear charge sharing)
- The **eta correction** is a data-driven method to take contributions from **non-linear charge sharing** into account
- Eta distribution is defined as **in-pixel track position as a function of in-pixel cluster position**
- Only **cluster position in row direction** is **corrected** with eta algorithm (in column direction sub-pixel scheme requires modified correction method)
- **RMS of 3 sigma (= 99.7%) of entire residual distribution** (also 1 pixel cluster): **5.1 um** (before correction: 5.7 um)
telescope resolution (= 1.78 um) unfolded
- **Requirements** for CLIC tracker: **7 um**



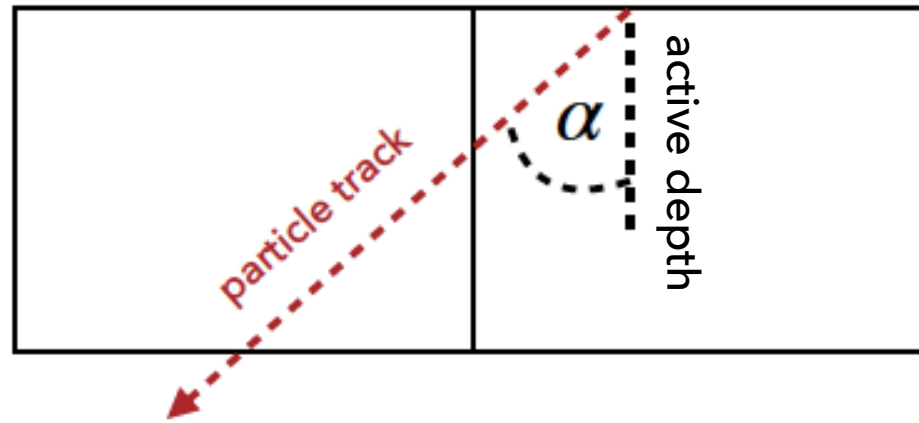
- Spatial resolution worsens with increasing threshold due to decreasing cluster size
- No difference between process variants because the gap is only introduced in column direction
- Also for high thresholds, resolution better than binary resolution of 8.7 um
Binary resolution: $30\mu\text{m}/\sqrt{12} = 8.7\mu\text{m}$

No stringent requirements for CLIC tracker in this spatial dimension



- No eta correction applied
- Less charge sharing due to gap in the n-implant leads to a smaller cluster size and worse spatial resolution
- Resolution gets slightly better at very high thresholds due to shrinking effective pixel size (decreasing efficiency at pixel edges)
- Also for high thresholds, resolution better than binary resolution of 10.8 μm
Binary resolution: $37.5\mu\text{m}/\sqrt{12} = 10.8\mu\text{m}$

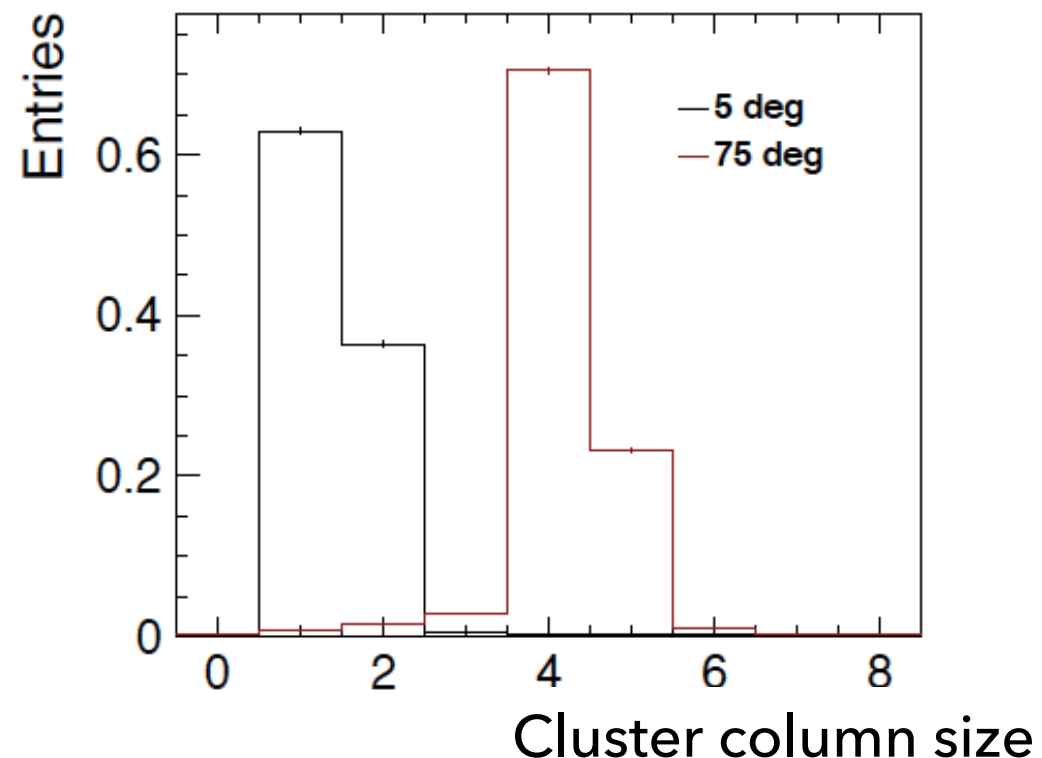
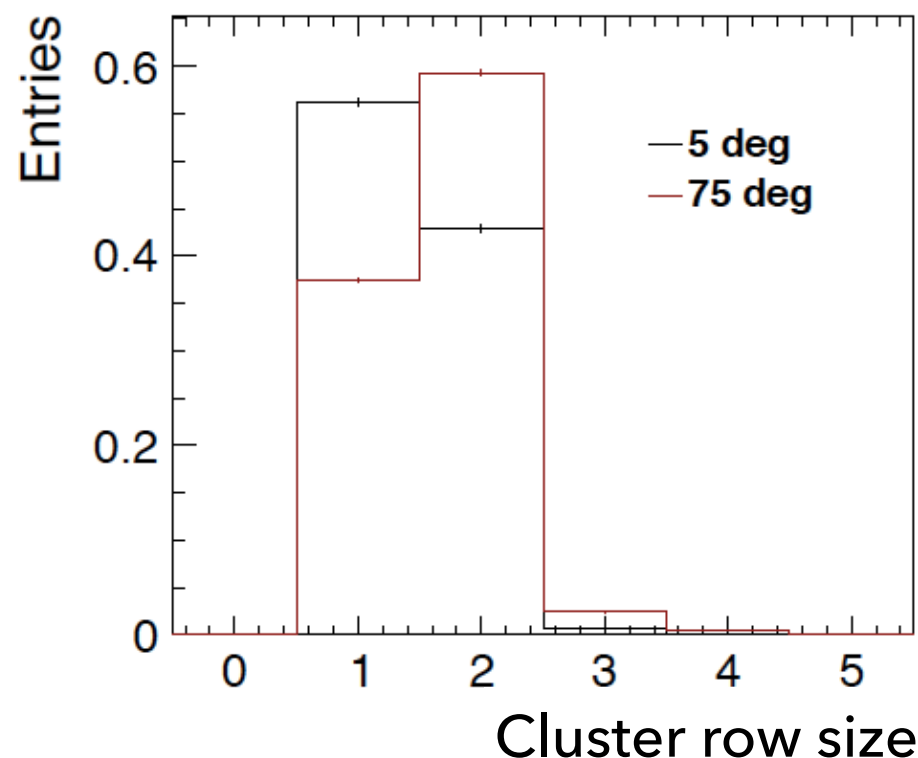
Geometrical model:



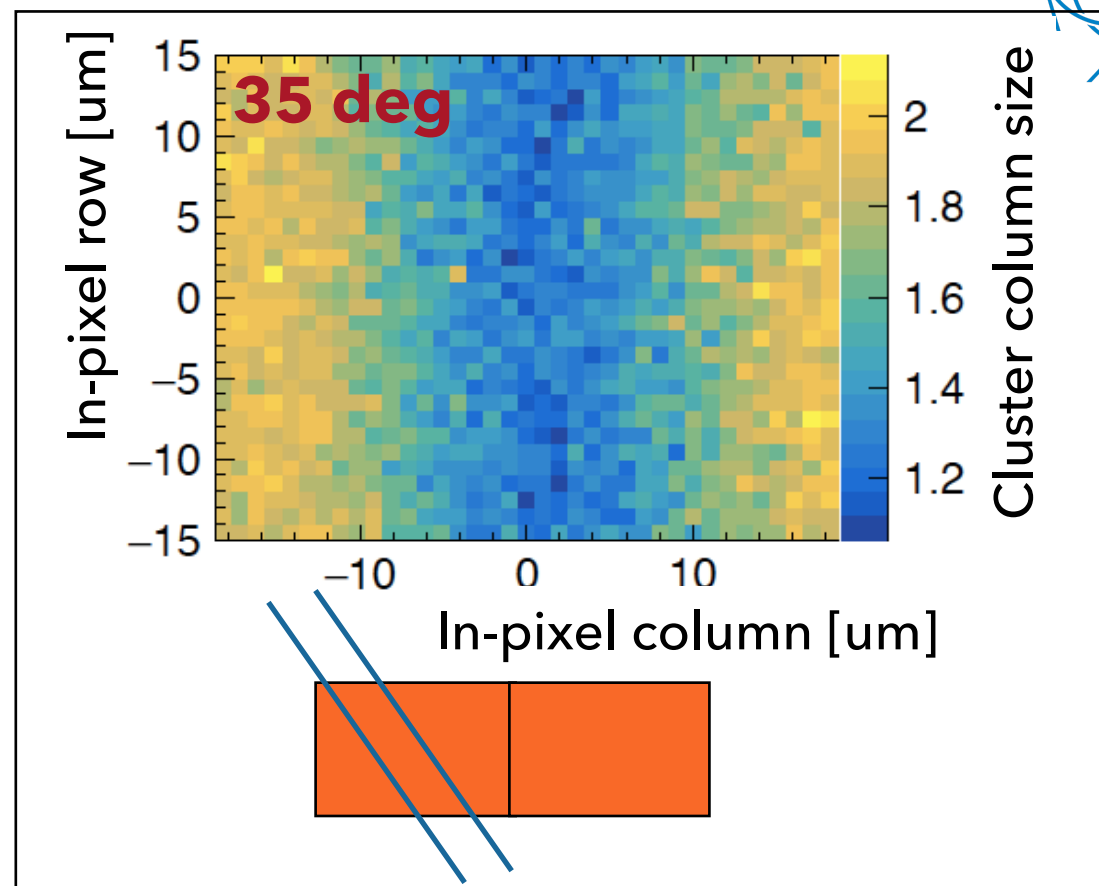
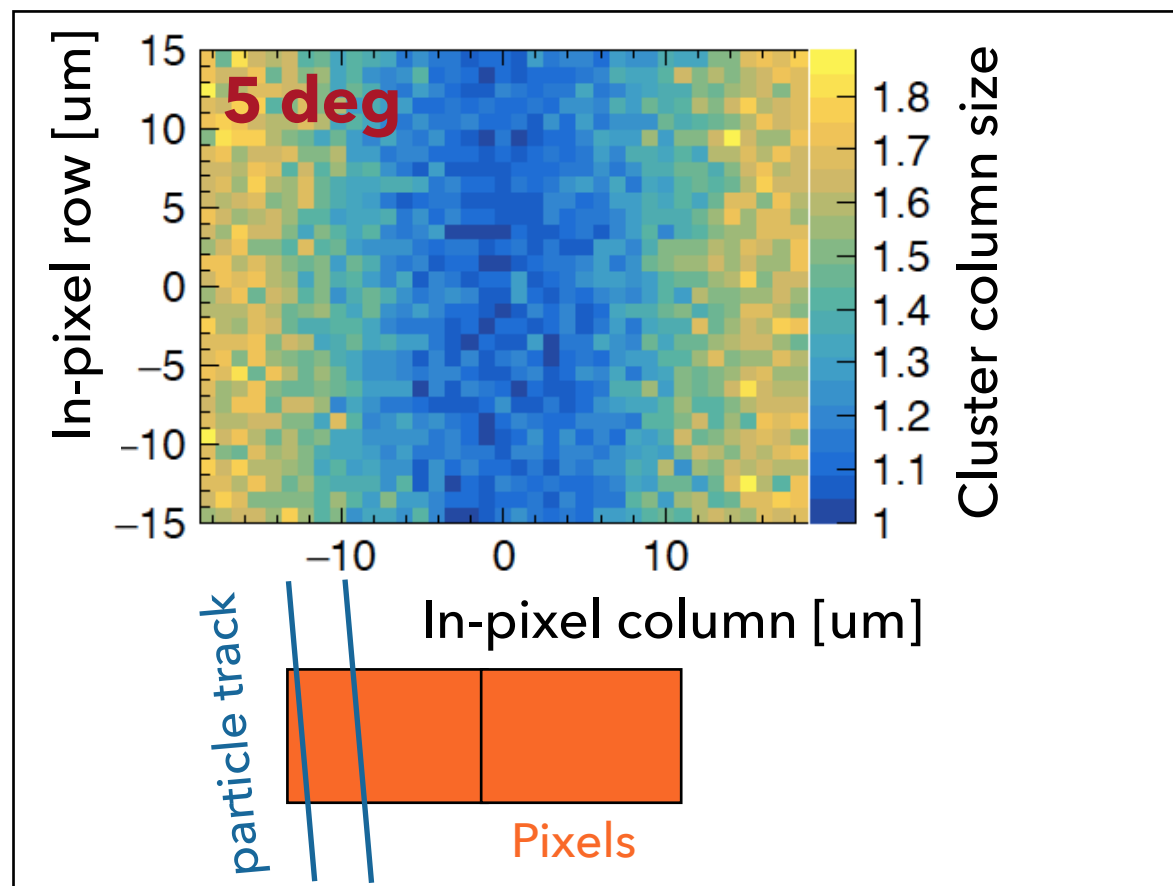
$$\text{size}_x = \frac{d_{\text{depth}} \cdot \tan(\alpha)}{\text{pitch}_x}$$

- Cluster size increases for inclined particle tracks since energy is deposited in several adjacent pixel cells
- Active depth can be estimated by analysis of rotation-dependent cluster size
- This model neglects contributions from diffusion and sub-threshold effects

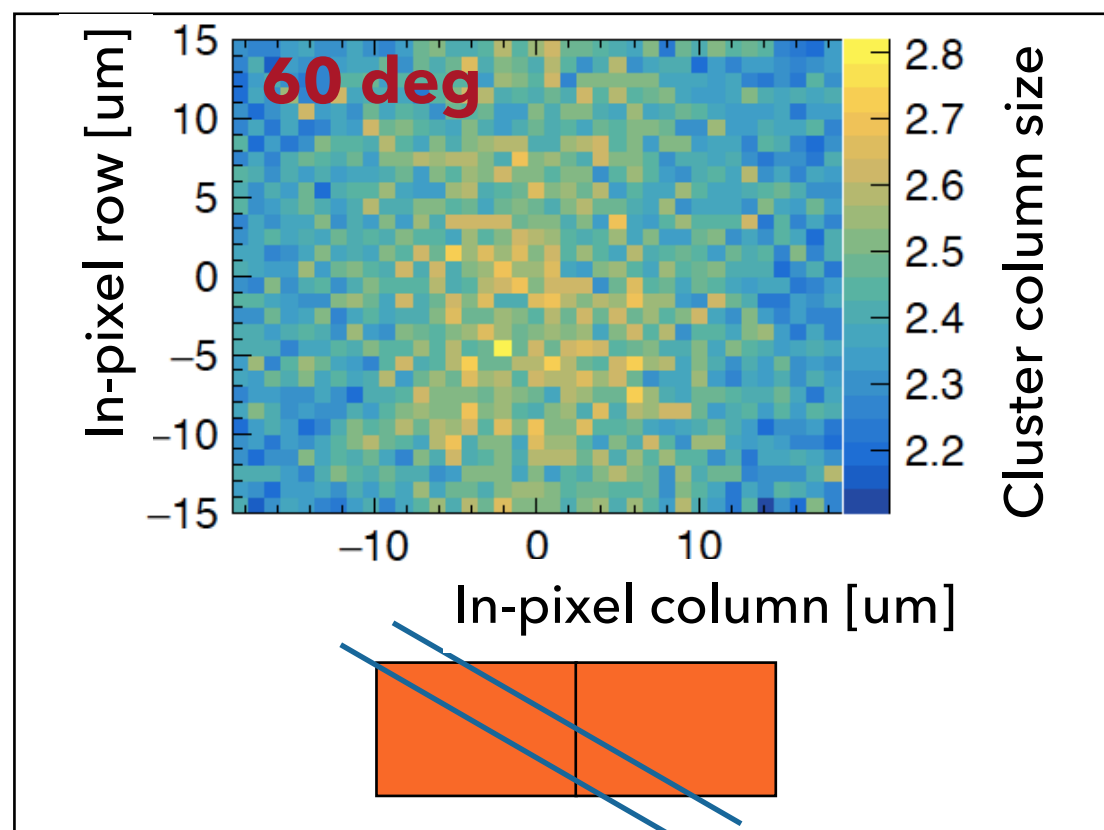
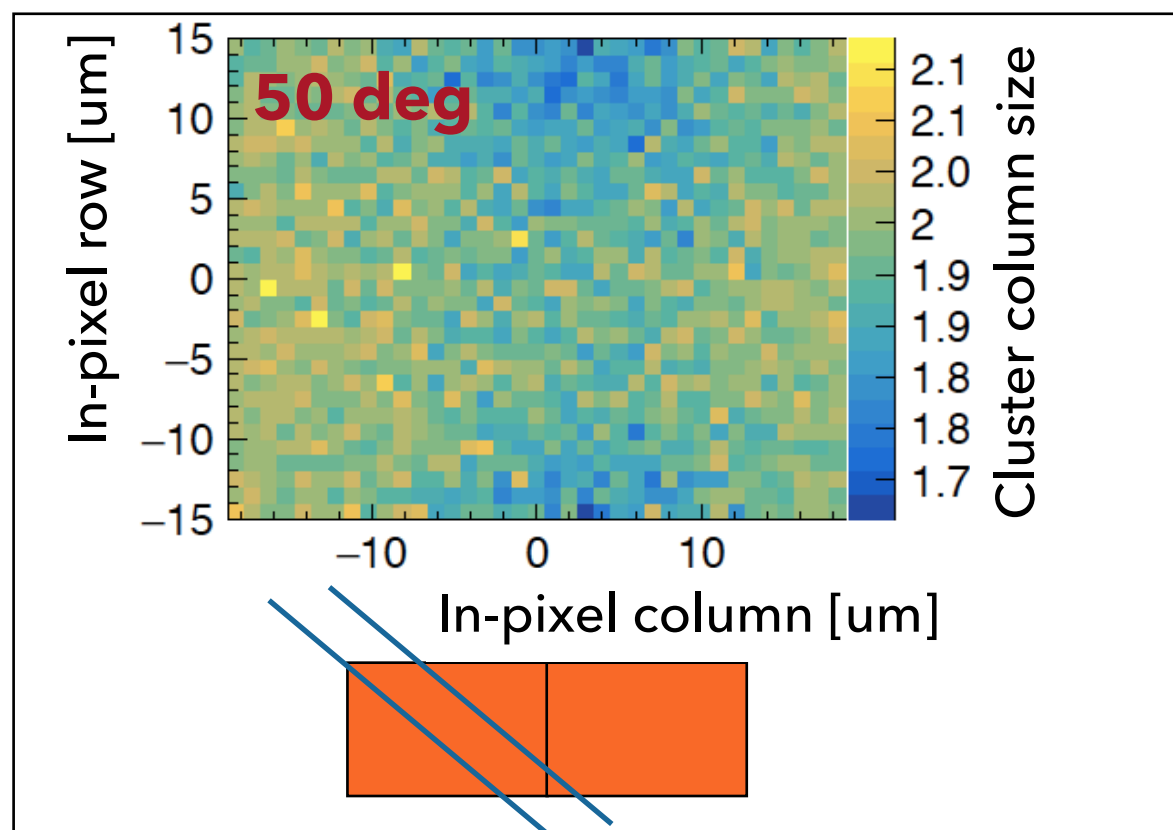
Rotation performed around row axis



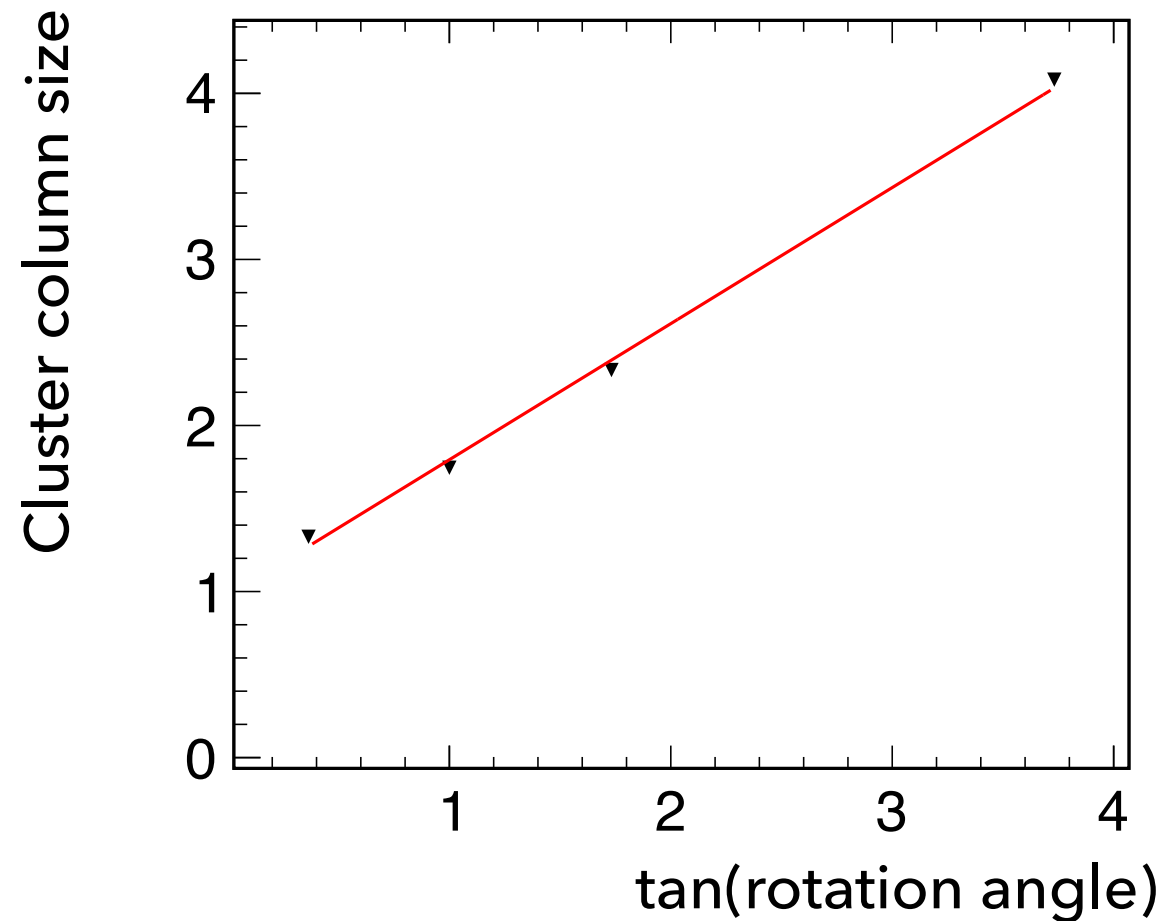
IN-PIXEL CLUSTER SIZE IN X



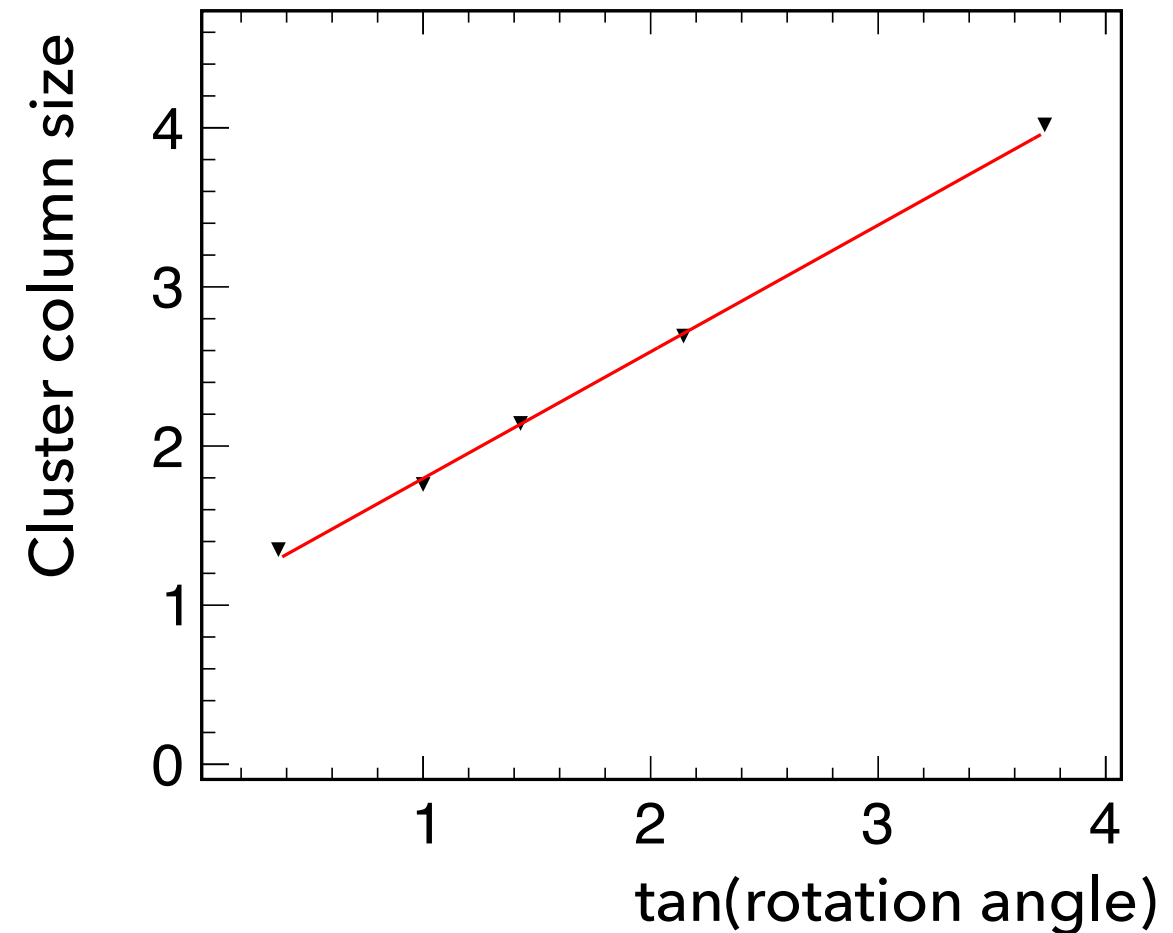
In-pixel plots illustrate that cluster size at low angles is still dominated by [charge sharing via diffusion](#)



Nominal thickness (300 μm)

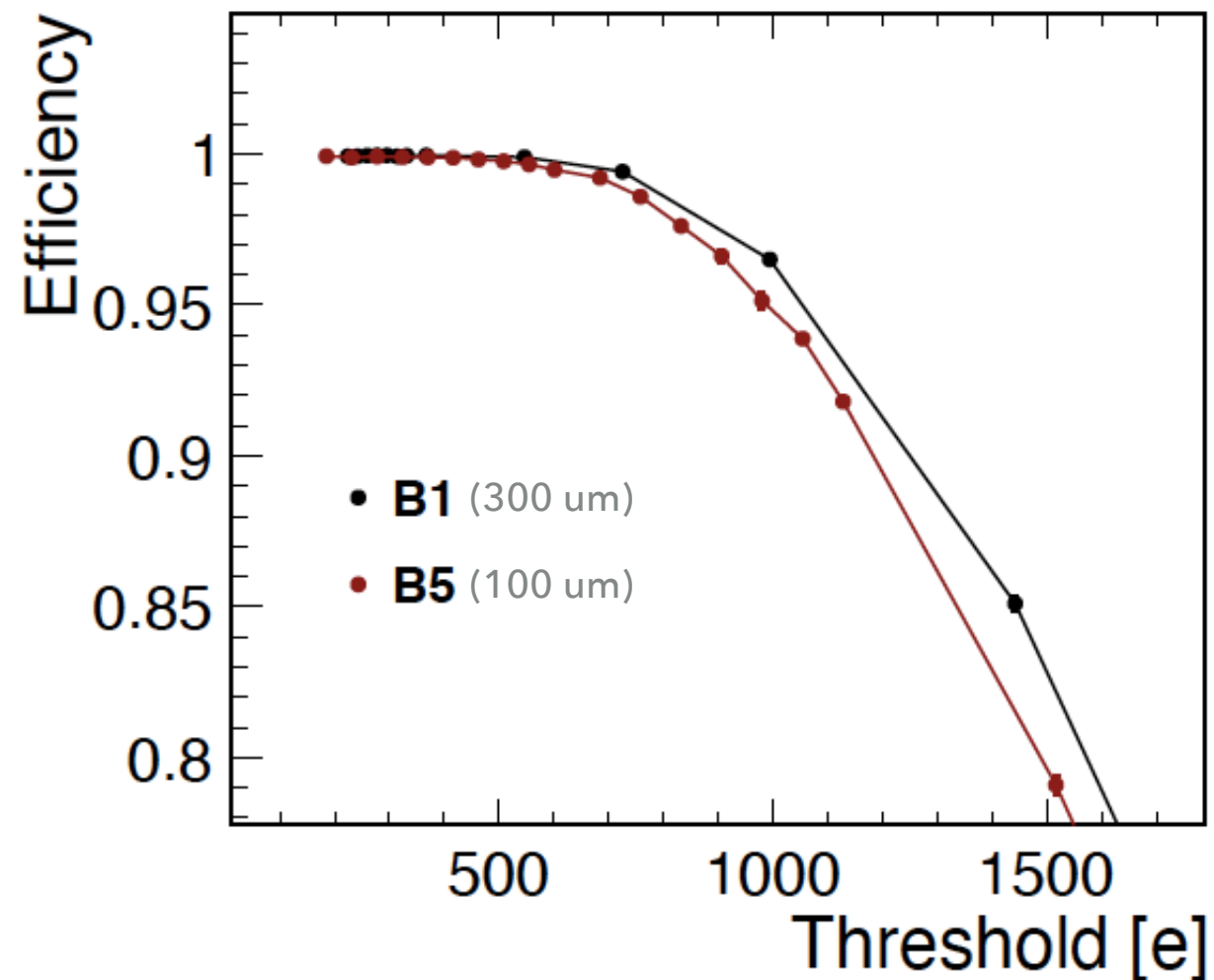


Thickness : 50 μm

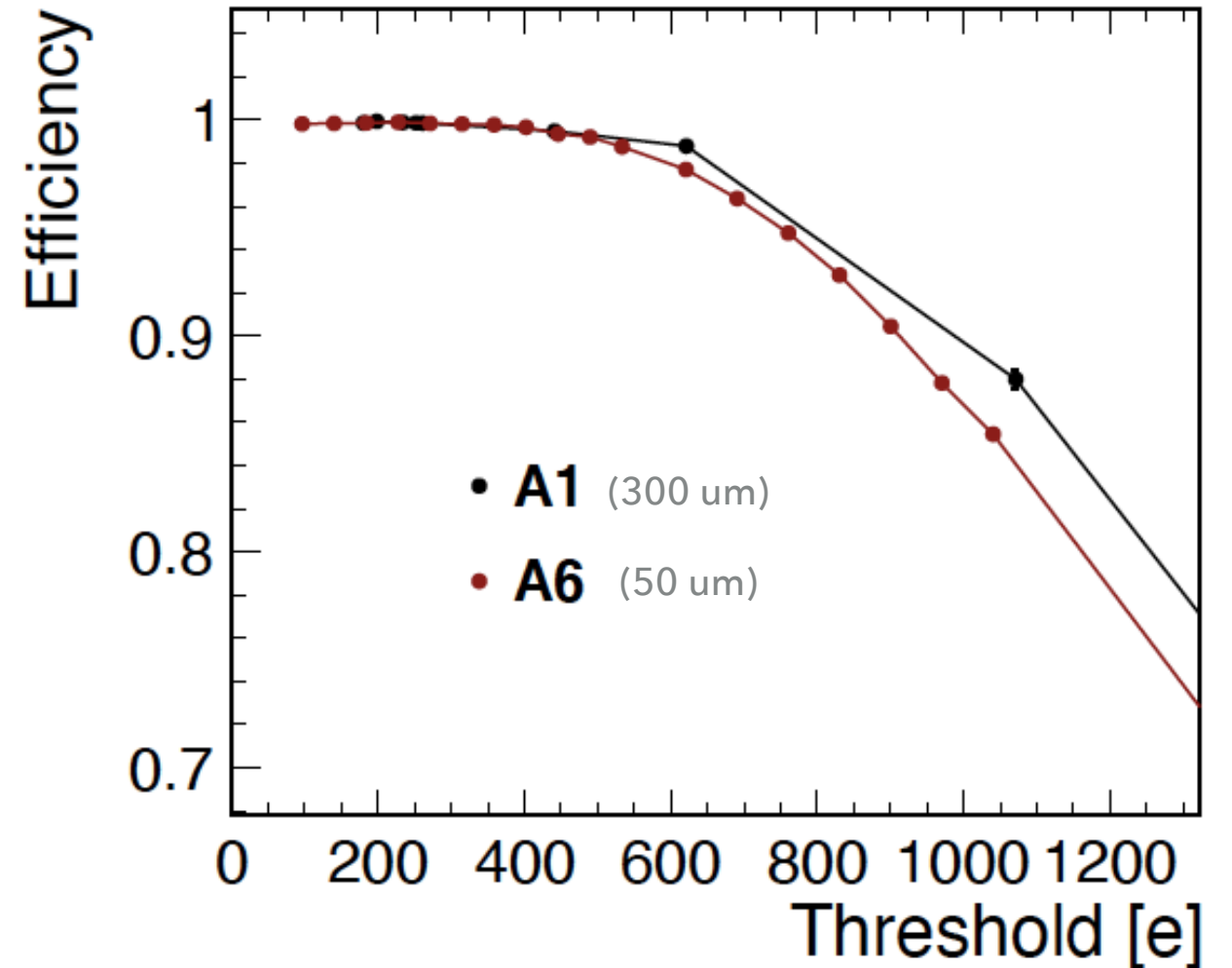


- Active depth from fit: $(30.7 + 0.3 - 3.4) \mu\text{m}$
- Active depth from fit: $(29.8 + 0.9 - 1.0) \mu\text{m}$
- For now, **uncertainties** estimated by **removing first/last point** and fitting again
- Thickness of epitaxial layer: 30 μm , depletion depth (TCAD): 23 μm
- As expected, **no difference in active depth** for assemblies with nominal thickness and thinned ones
- Contribution of charge sharing via diffusion and sub-threshold effects will be investigated in simulation

With gap



No gap



- Similar efficient operation window for thinned assemblies supports the notion that the **thinning does not alter the active depth**

- Paper about initial CLICTD test-beam results is in preparation
- Analysis of parameter scans turned out to be a very time-consuming task since we took data at many different thresholds
- Currently working on the **correct treatment of the ToT calibration**

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1. Introduction

2. The CLICTD chip

CLICTD features a matrix of 16 x 128 detection channels with a size of $300\text{ }\mu\text{m} \times 30\text{ }\mu\text{m}$. In the $300\text{ }\mu\text{m}$ dimension, the channels are segmented into eight sub-pixels, each with its own collection diode and analogue front-end. The analogue information from the eight sub-pixels is combined in the digital front-end of one channel. This segmentation

SUMMARY / OUTLOOK



- CLICTD spatial resolution was found to be 5.1 μm after eta correction (Fulfil CLIC tracker requirements of $< 7 \mu\text{m}$)
- Estimation of active depth from simple geometrical model yields $\sim 30 \mu\text{m}$ for nominal thickness (300 μm) and thinned assemblies (down to 50 μm)
 - In agreement with expectations from sensor layout and 3D TCAD simulations
- CLICTD test-beam paper in preparation

Thank you very much!



Part of the measurements leading to these results have been performed at the Test Beam Facility at DESY Hamburg (Germany)



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