



COMPUTING ISSUES IN PHASE SPACE INTEGRALS

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WHAT WE CALCULATE

$$\sigma^{\text{NLO}} = \int_{m+1} d\sigma^R + \int_m d\sigma^V + \int_m d\sigma^B$$

‘Real emission’
NLO corrections

‘Virtual’ or ‘one-loop’
NLO corrections

‘Born’ or ‘LO’
contribution

WHAT WE CALCULATE

$$\sigma^{\text{NLO}} = \int_{m+1} d\sigma^R + \int_m d\sigma^V + \int_m d\sigma^B$$

- ✱ Phase space integration with possible restrictions in form of cuts: very complicated (nested) integration bounds
- ✱ Up to $O(10-20)$ dimensional integrals
- ✱ Using Monte-Carlo techniques with VEGAS (or similar in-house routines) for adaptive importance sampling
- ✱ Our code (called 'MadFKS') is written in Fortran77. Okay for pure 'number crunching'

THE INTEGRAND

- ✱ Because the integrand has many more peaks than integration variables, a single phase space mapping cannot align integration variables along peaks
- ✱ Need for multi-channel integration

MULTI CHANNELS

✱ For example

$$\int d\sigma^R(x) = \sum_i \int d\sigma_i^R(x)$$
$$\int d\sigma_i^R(x) = \int \frac{d\sigma^R(x)}{\sum_j f_j(x)} f_i(x)$$

✱ Sum over $f_j(x)$ damps peaks in $d\sigma^R(x)$

✱ $f_i(x)$ has many less peaks, and therefore we can flatten them using a simple change of integrations variables

✱ $O(50)$ channels needed

STRUCTURE OF THE CODE

$$\sigma^{\text{NLO}} = \int_{m+1} d\sigma^R + \int_m d\sigma^V + \int_m d\sigma^B$$

- ✱ In fact, each of the contributions contains $O(50)$ subprocesses: we have a single executable for each of them that is put in a separate directory
- ✱ Size of the executable (with libraries linked statically) is $O(10\text{-}20 \text{ MB for } d\sigma^R)$ and $O(0.1\text{-}1 \text{ GB for } d\sigma^V)$
- ✱ Within those, multi-channel integration is used: $O(50)$ channels per directory
- ✱ In total, $O(1\text{-}5\text{k})$ integration channels for complicated processes



TRIVIALY PARALLELIZED

- ✿ Each of these integration channels can be executed independently
- ✿ That means that we have $O(1-5k)$ jobs
- ✿ We cannot lose any job. All results need to be collected and summed to get the correct final answer

RUNNING

1. Jobs are executed with relatively low statistics. Takes 5 min to 1 hour per job
2. Results are collected
3. Jobs with the largest integration uncertainties are resubmitted with higher statistics, starting with the VEGAS grids generated before. A couple of 100 jobs, and can take up to a couple of days per job to finish
4. Results are collected
5. If not satisfied, resubmit again with even higher statistics

RUNNING

- ✱ So far, running of the code has been done on a cluster (in Louvain-la-Neuve, Belgium) of $O(25)$ machines with 8 cores each: maximally 200 jobs can be executed in parallel
- ✱ Code is compiled on a central node with all libraries linked statically
- ✱ All jobs are submitted to the Condor batch system that takes care of queueing, scheduling etc.
- ✱ No shared file system: executable is copied to the node when the run starts

WRITING OUT NTUPLES

- ✱ Usually, the ntuples are not written to disk
 - ✱ Results are simply accumulated while running and plots for predictions for physical observables are generated on the fly
- ✱ If the data is written, it can easily lead to terabytes of data
 - ✱ The advantage is clear: generation of plots/cuts can be redone, without redoing the calculation

SUMMARY

- ✿ Also in theoretical high energy physics computing demands are increasing
- ✿ Clusters with more than 100 machines are needed to generate reliable predictions for the complicated processes at the LHC in a reasonable amount of time (i.e. days)
- ✿ Disk space is not a problem when not saving the events
- ✿ Grid running?