

Neutron selection and software status

<u>Ciro Riccio</u>, Abraham Teklu, Guang Yang, Eric Chong SuperFGD beam test analysis meeting November, 19th 2020



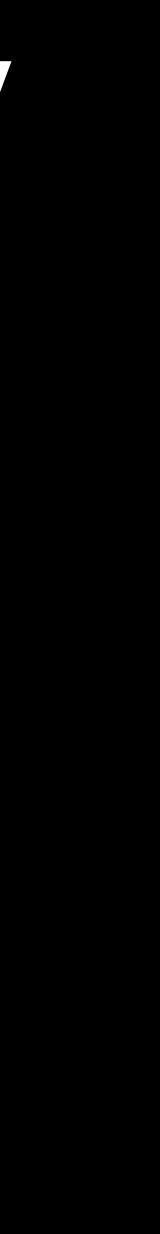


- Software development strategy
- •Software development status
- Neutron selection overview, cut flow and first results
- Conclusions and next steps



Software development strategy

- Created a group on gitlab (for non-T2K people) called Neutron Test Beam Analysis
- There are three projects (all under MIT license):
 - neutronSimulation: package for the Monte Carlo simulation of experimental set-up used @LANL
 - neutronSelection: package to select neutrons from the data taken during the test beam largely based on sfgd_framework developed by Cesar, Dana and Wilf
 - neutronXsecFitter: Package to extract the neutron xsec from the data taken during the test beam





Software development status

- neutronSimulation: ready
- neutronSelection:
 - Implemented Time clustering (Abe and Ciro) and voxelization (Eric) \bullet
 - Implemented (Eric) DBSCAN (spatial clustering similar to what Cesar implemented in sfgd_framework) and Principal component analysis (cluster geometrical properties)
 - Implemented the track fitting the vertex finding (Ciro and Guang similar to what Cesar implemented in sfgd_framework)
 - Improved documentation (Ciro) and solved some memory leak problems (Ciro and Eric)
 - Ongoing work: implementing new cuts (Ciro and Eric) and Hough transform (David)
- neutronXsecFitter: work in progress



Neutron selection overview

v neutronselection ~ 10

- G Event.cc
- G+ Event.hh
- G+ Hit.cc
- G+ Hit.hh
- C LinkDef.h
- G VoxelManager.cc
- G VoxelManager.hh

 \sim utils

- G- CommonHeader.hh
- G FindClusters.cc
- G+ FindClusters.hh
- G FindGeometricProperties.cc
- G- FindGeometricProperties.hh
- GeneralUtils.cc
- G RecoUtils.cc
- Ge TrackFitter.cc

 \sim app

- G compareHitsVoxels.cxx
- Ge geometryDistribution.cxx
- Ge optimizeGeometry.cxx
- G ReconstructClusters.cxx
- Generation RunBeamCenterStudy.cxx
- G RunNeutronSelection.cxx
- G+ tutorial.cxx

Base classes:

- Handle hits (Hit.*) information
- Handle voxel information (VoxelManager.*)
- Useful tools:
 - List of useful common header
- Some general tool for the processing Time clustering and voxelization
- •DBSCAN, PCA and track fitting
- Neutron selection and code for different optimization/studies

•Read all the events (Event.*) in a file

Tutorial: start from this to write an app



Neutron selection cut flow

Cut name	
Micropulse time window	-326 ns <
Number of hits	
Time clustering	lf
Voxelization	Build voxel based o
Voxel PE	
Spatial clustering	DBSCAN: minim
Number of clusters	
Vertex in FV	Vertex (first
3DLine-Point max distance	Max distance be
Max cluster size	If the max clust

Cut descriptions and value

Hit time < 340 ns (90 m) -281 ns < Hit time < 418 ns (20 m)

#hits > 3

 $PE > 5 \&\& t_{hit}(i+1) - t_{hit}(i) < 17.5 ns \Rightarrow same cluster$

on the hits position and time difference between hits (time tick 7, but discussing to remove it)

#PE>50 (not really effective we will remove it)

ium of 2 nodes and maximum distance of 1.8 cm (to be optimized)

Select events with only one cluster

voxel in Z) must be in 2x2 FV (build around the beam center)

etween 3D line from PCA and voxels in a cluster must be < 1.8 cm

ter size in one of the direction is below 5 cm the event is rejected

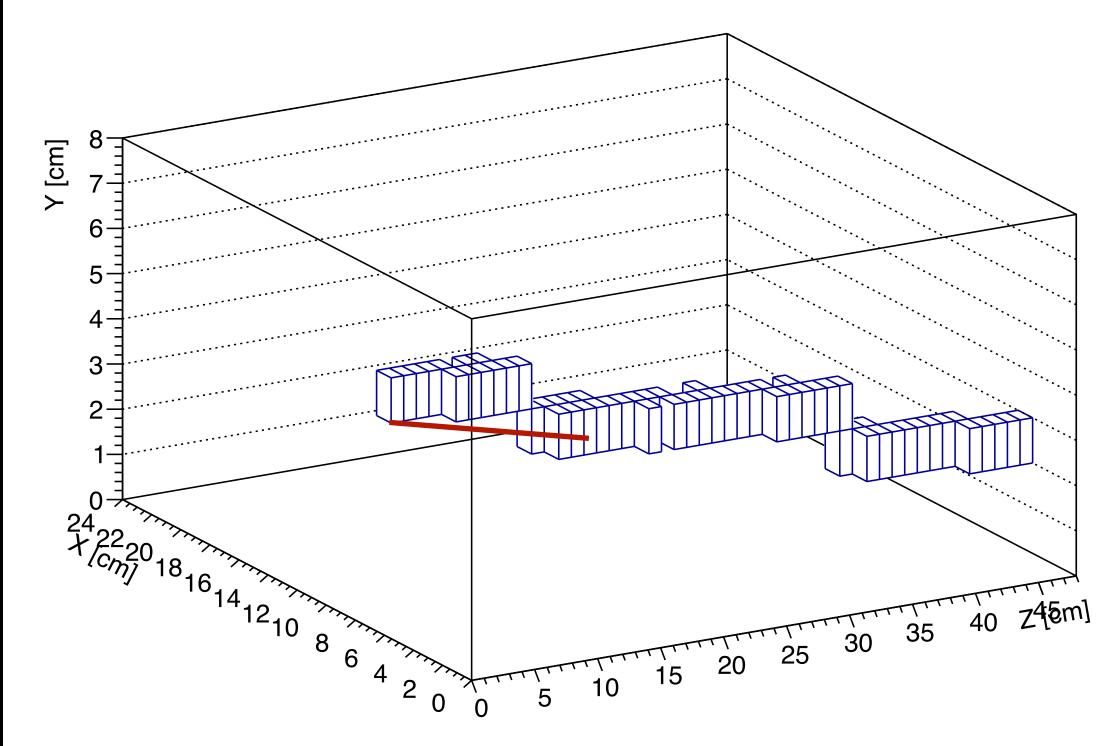




3DLine-Point max distance

- Select only event with one cluster
- Perform a PCA
- The main vector represents the direction of 3D line with origin the vertex of the track (red line in figure)
- Compute the distance between the voxel and this line
- If the maximum distance is greater than 1.8 cm the event is rejected

3D View of Voxels Eve#1209 TotPE=1.000000



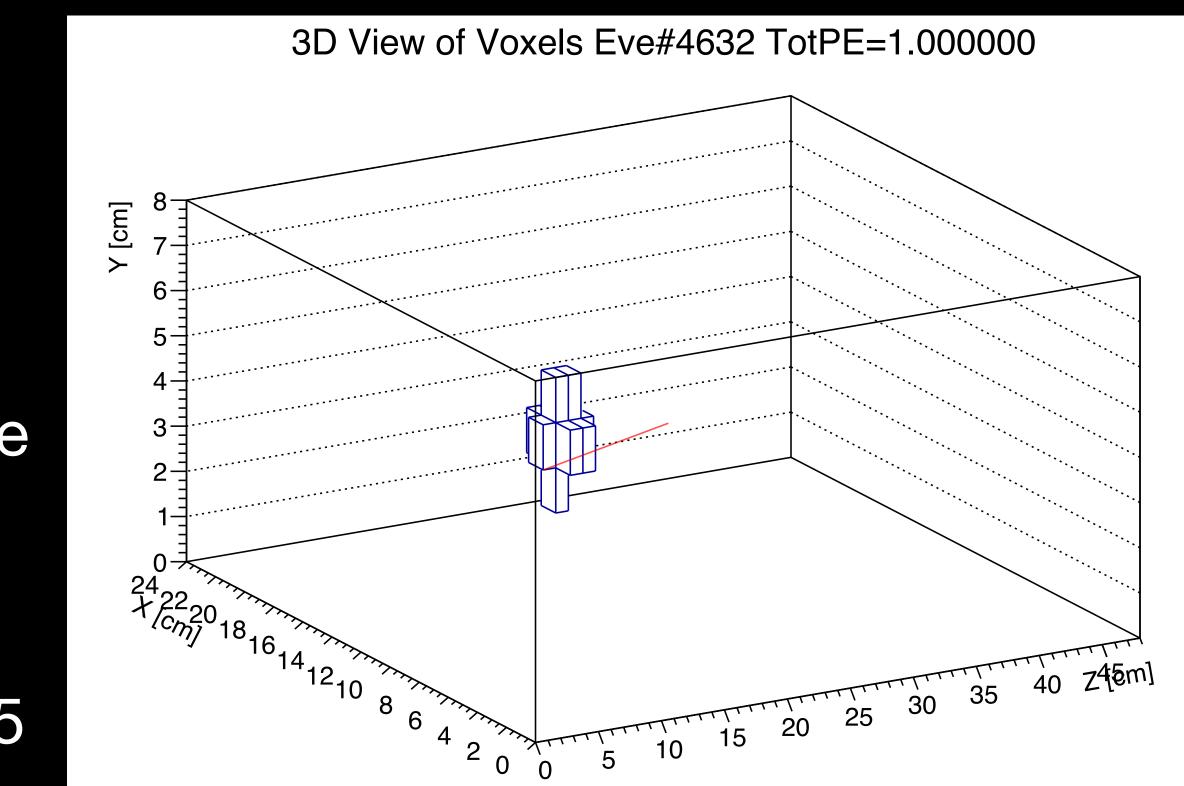




Max cluster size

- Can have very small clusters (blobs)
- To reject them we compute the cluster length in X, Y and Z
- This length is compute as the difference between the last and first voxel in a certain direction
- If the maximum distance is lower than 5 then we reject the event

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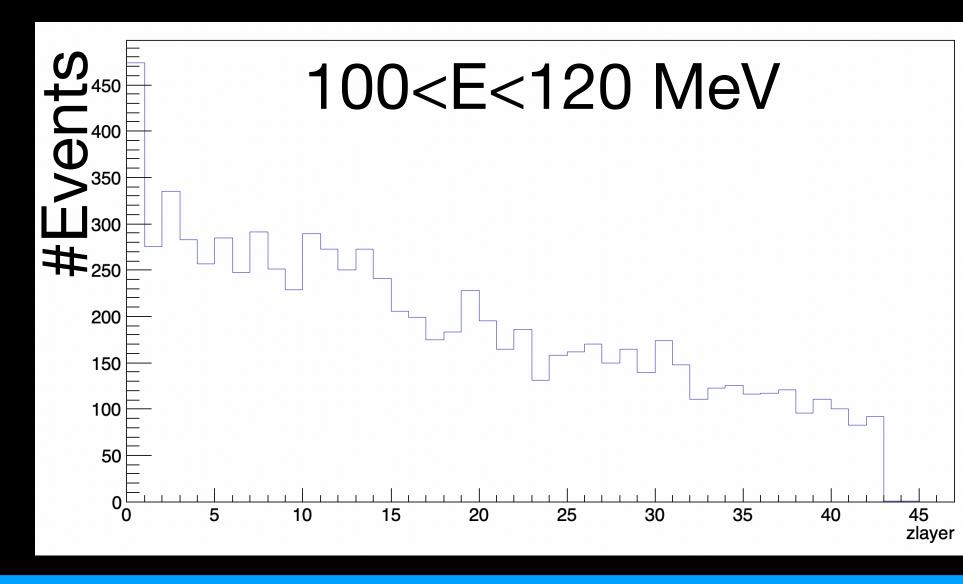


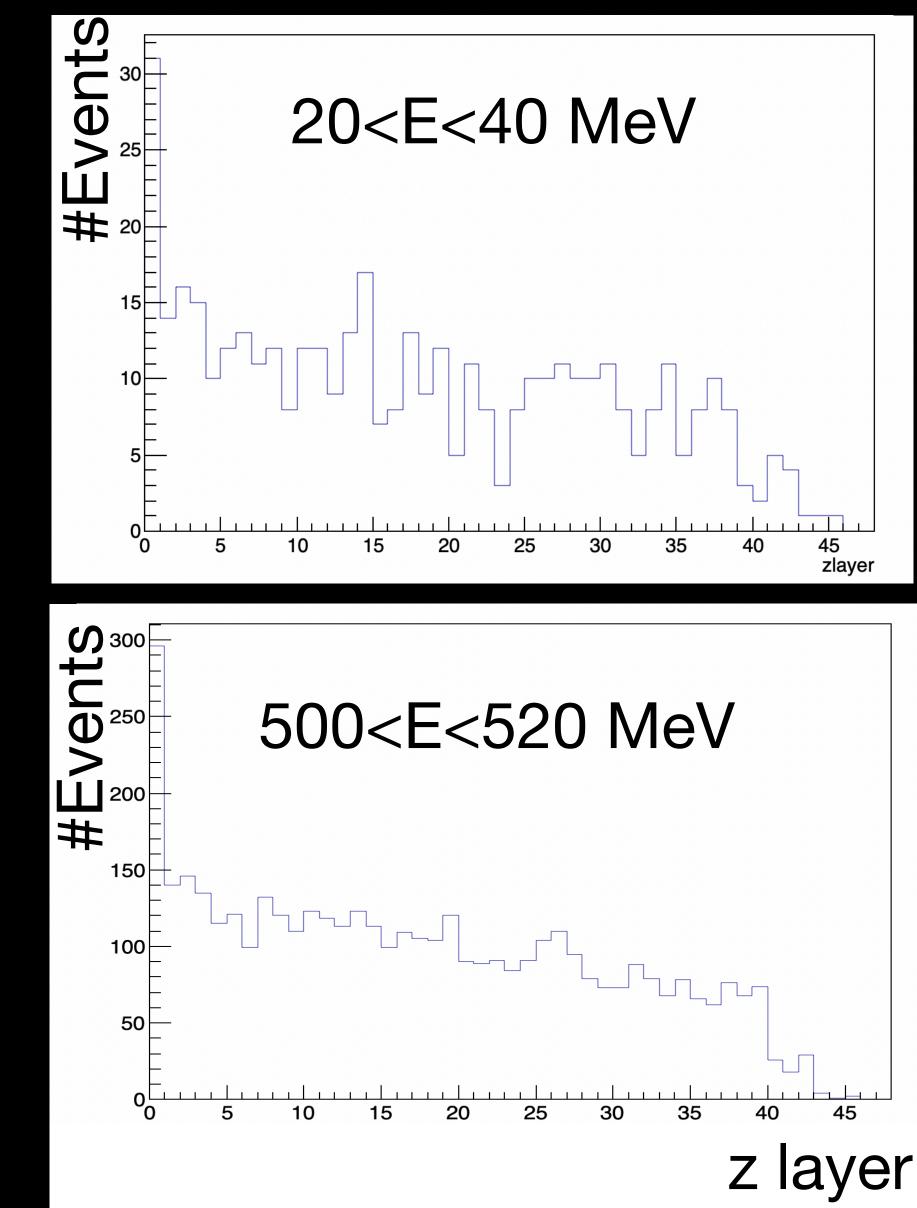


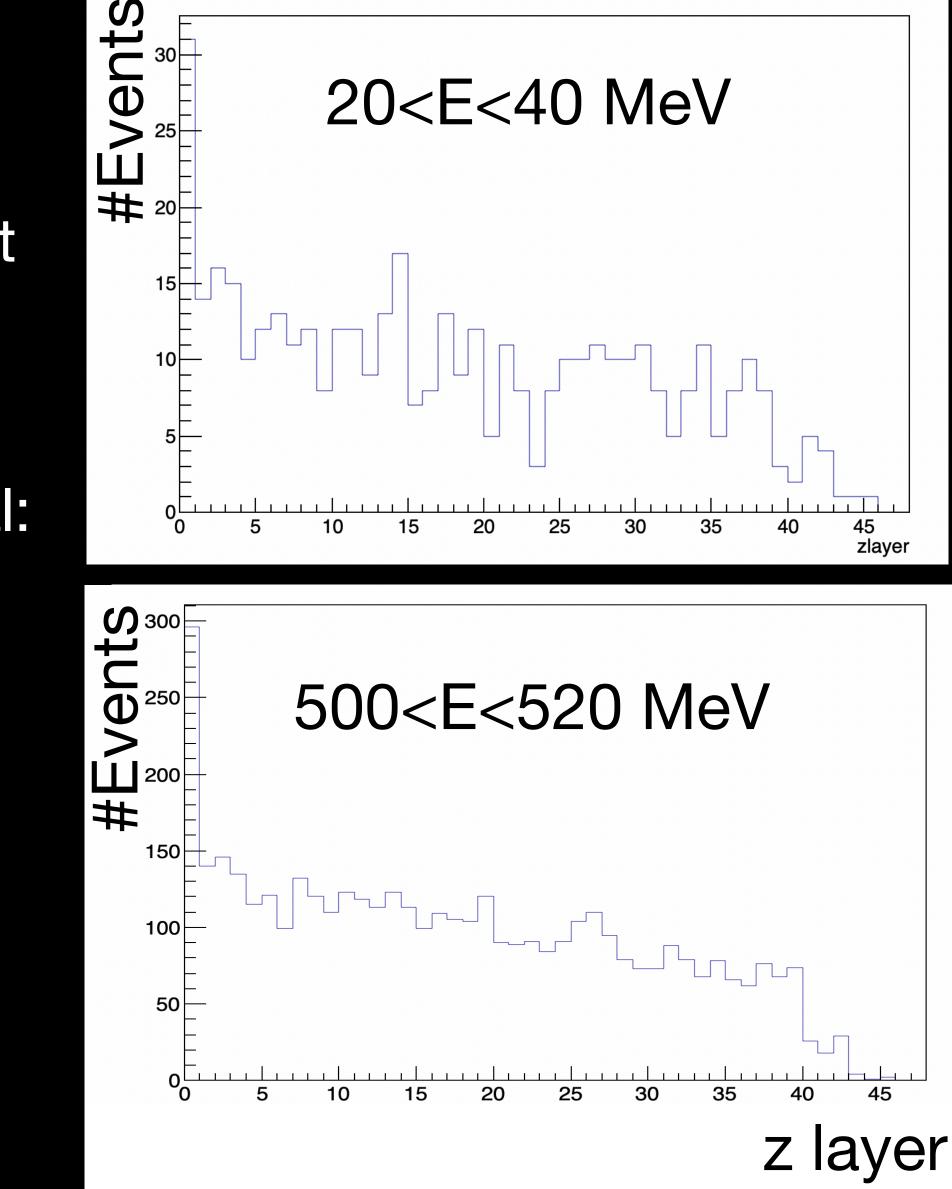


Selection: first look

- Analyzed run8 take on Dec. 7, 2019 (16 min)
- Histogram every 20 MeV of the #events vs layers (just 3 shown here)
- The cuts reject many low energy events
- For high energies the behavior seems not exponential: need further investigation





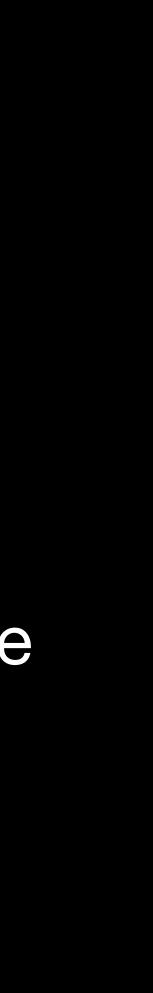




Other possible cuts

- Select only event with one cluster
- Perform a PCA
- Compute the linearity as (principal value second principal value)/principal value and require it to be greater than 0.9 to remove blobs
- Project the voxels on the second principal vector and compute the distance between the max and min point. This is a measure of the cluster spread
- If this different is greater than 2.5 cm the event is rejected. This should remove multiple track events

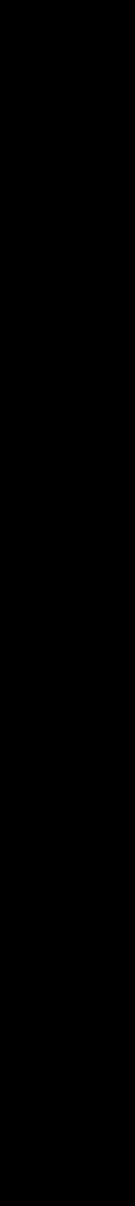
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Conclusions

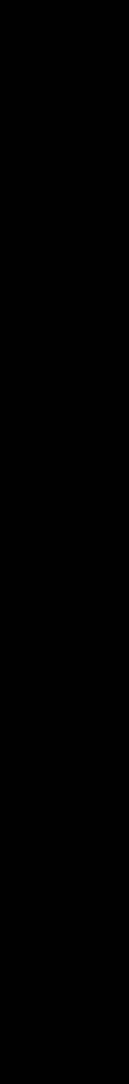
- neutronSimulation: ready
- neutronSelection next steps:
 - Optimize the cuts value
 - Test the Hough Transform implemented by David
 - Speed up the code
 - Improve the handling of the file IO (minor)
- neutronXsecFitter: WIP D

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Neutron energy

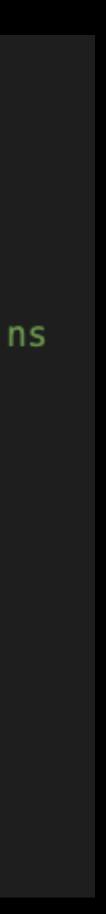
```
double ComputeNeutronEnergy(double time, double d)
 double energy=0.;
 Double_t m = 939.5654133;//neutron mass in MeV
 Double_t c = 299792458; //speed of light in m/s
 Double_t gammaToF = d/c; //photon travel time in secs
 Double_t ToF = (time+offset)*2.5*1e-9+gammaToF; //neutron time of flight in seconds
 Double_t v = d/ToF; //neutron velocity using time of flight and
  energy = m/sqrt(1-pow(v/c,2)) - m;
  return energy;
```

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Double_t offset = 352; //time between FEB12 signal and the center of the gamma flash peak in units of 2.5 ns



Neutron selection: track fitting

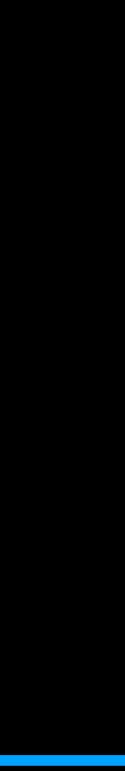
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- •Compute the angle w.r.t. z and select forward going tracks
- Validating with CERN TB proton data we are observing good results (more quantitive results soon) and MC samples
- Find the vertex (preliminary): obtained by finding the intersection of the beam center and the track line on XZ and YZ planes.

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• Fit the linear cluster with a 3D line



Neutron Xsec Fitter overview

- \sim neutronxsecfitter
 - .gitignore
- M CMakeLists.txt
- LICENSE
- README.md
- G* RunNeutronXsecFitter.cxx

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Introduction

This package is intended to provide all the necessary tools to extract the neutrons cross section from the data taken at LANL.

Download

To dowloand it:

```
$ git clone git@gitlab.com:neutron-lanltb-analysis/neutronxsecfitter.git
$ git checkout -b <choose a branch name>
```

Installation

There are several requirements for building the fitter:

- GCC 4.8.5+ or Clang 3.3+ (a C++11 enabled compiler)
- CMake 3.10+
- ROOT 6

Set up the ROOT environment before attempting to build by:

\$ source /path/to/ROOT/bin/thisroot.sh

To build:

\$ mkdir build; cd build
\$ cmake ../
\$ make

Running the Code

If the installation succed the application to te used for the selection is saved under build:

\$./RunNeutronXsecFitter.exe



Neutron Xsec Fitter workflow

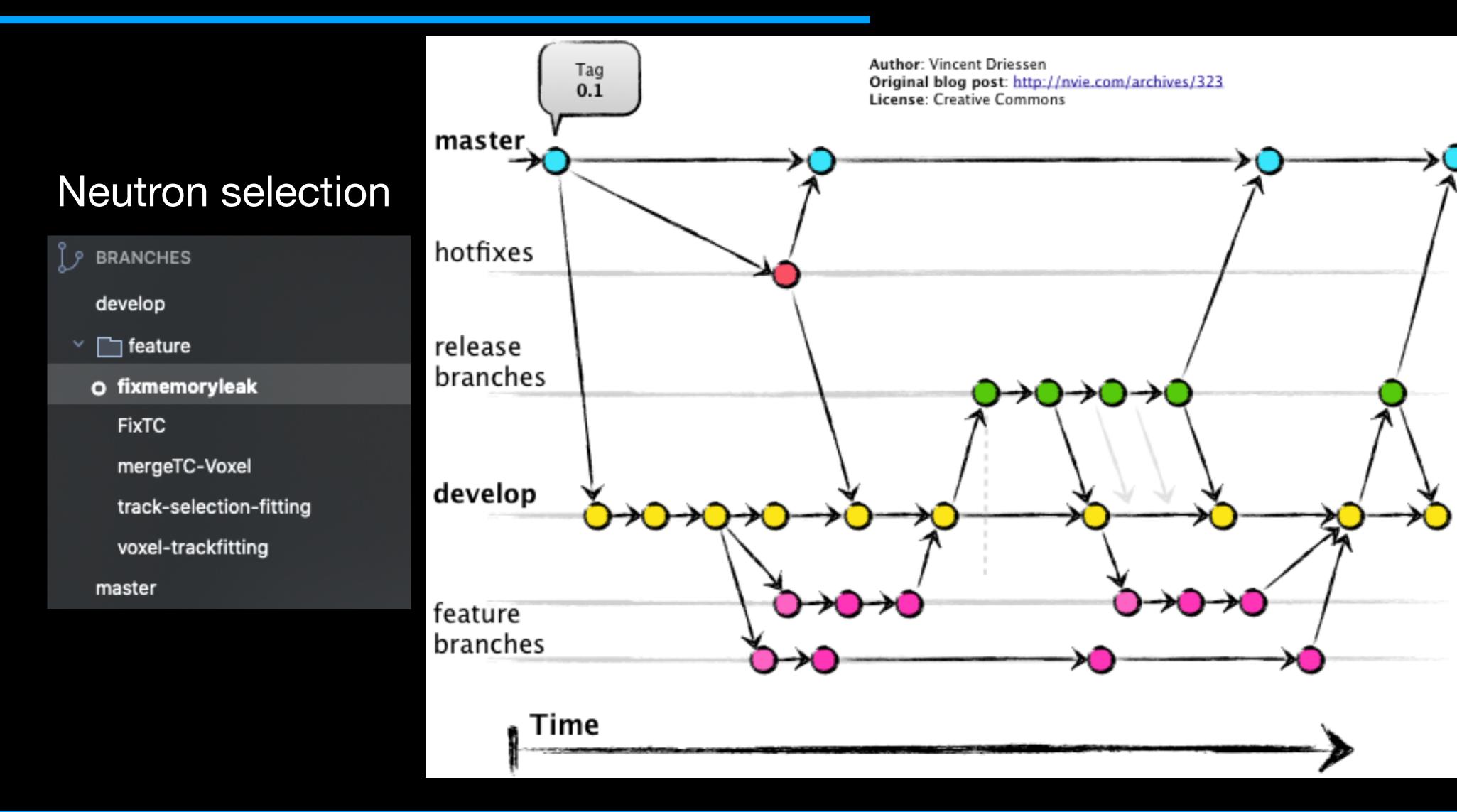
- Fill an histogram for every energy bin (20 MeV)
- Fit this histogram with an exponential
- Inclusion of systematics:
 - Repeat the fit for every variation of a systematic uncertainty
 - Fill an histogram with every value of the cross-section extracted
 - The systematic uncertainty will be the RMS of this distribution
- Statistical uncertainty: similar to systematics but varying the number of events using a Poisson distribution







Git workflow



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