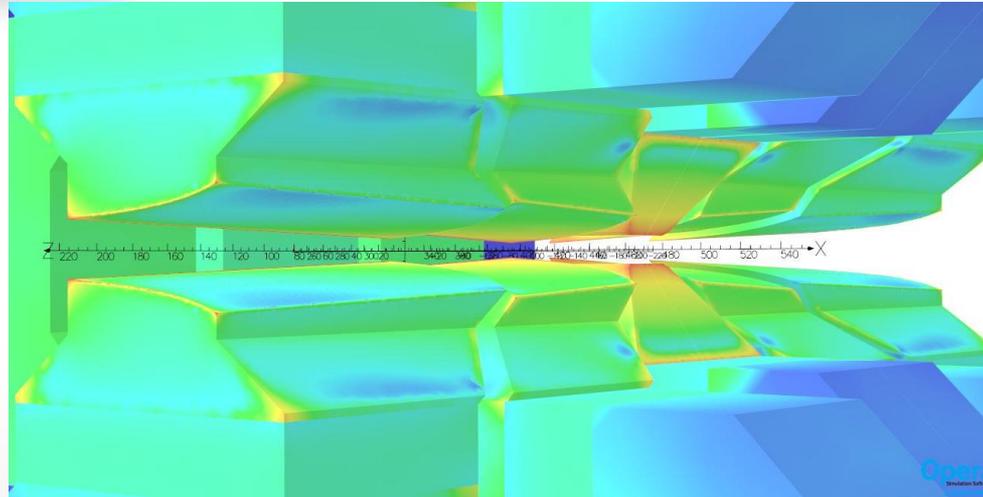


Development of a high-field longitudinal gradient dipole at CIEMAT



M. A. Domínguez, F. Toral (CIEMAT), H. Ghasem, P. S. Papadopoulou, Y. Papaphilippou (CERN)

Outline

1. Introduction
2. Technical specifications
3. Magnetic Design
4. Field trimming
5. Magnet overview
6. Mechanical design
7. Conclusions and ongoing work

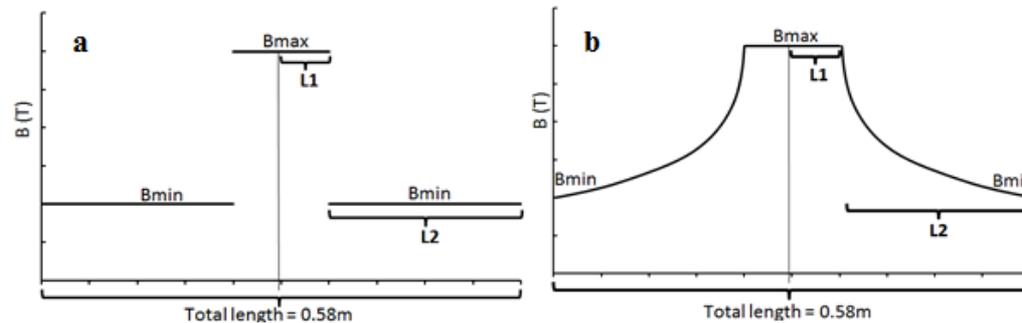
Introduction

- ❑ CLIC: Damping rings (DRs) to reduce the emittance of the injector chain incoming beams
- ❑ Lattice: theoretical minimum emittance (TME) cell and simple FODO lattice filled with high field superconducting damping wigglers.
- ❑ The **horizontal emittance** is further reduced below the TME limit for a given magnetic structure by considering **dipole magnets with longitudinal variable bending field**
- ❑ **Trapezium field profile dipoles** are preferred in the CLIC DR lattice

Technical specifications

TABLE I
TECHNICAL SPECIFICATIONS

Good field region radius [mm]	5			
Field harmonics [units 1E-4]	~1			
Transverse gradient [T/m]	11			
Magnet length [m]	0.58			
Aperture diameter [mm]	13			
	Step profile	Trapezium profile		
		Case 1	Case 2	Case 3
# of dipoles	96	90	90	90
Dip. field [T·m]	0.625	0.667	0.667	0.667
Bmax [T]	1.7666	1.7666	1.7666	1.7666
Bmin [T]	0.8737	0.7791	0.7508	0.7146
L1 [mm]	65.858	3.352	13.836	26.488
L2 [mm]	224.142	286.648	276.164	263.512

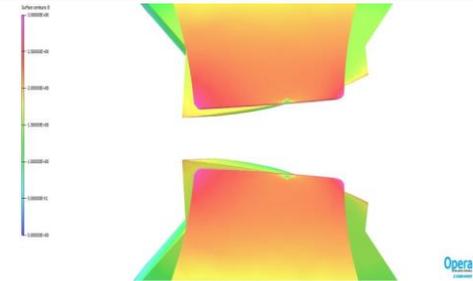


Magnetic design

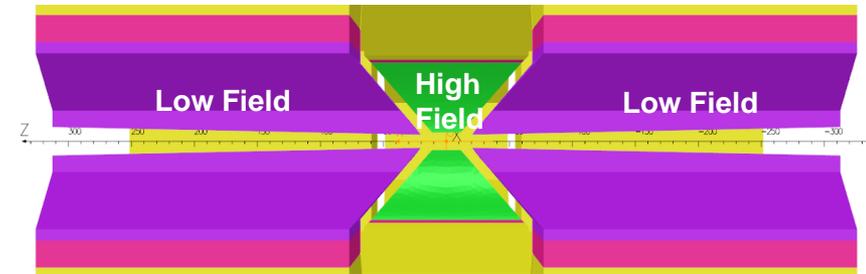
- ❑ Permanent magnets based design
- ❑ Max Temp variation $\pm 0.1^\circ\text{C}$ => No specific temperature compensation
- ❑ Extremely low energy deposition expected => No cooling
- ❑ Taking into account radiation tolerance, volume and weight, maximum remanent magnetization, cost,...:
 - SmCo in the outer modules
 - NdFeB in the inner modules
- ❑ Result comparison/validation: **Ansys Maxwell, ROXIE, COMSOL and Opera**

Magnetic design

- ❑ Combined function magnets: dipolar and quadrupolar field. Hyperbolic pole tip profiles



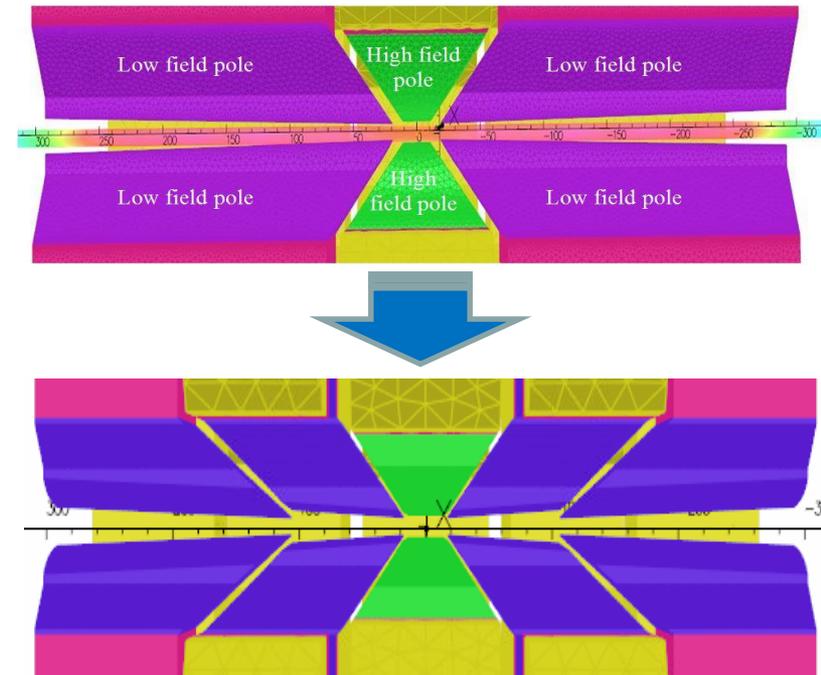
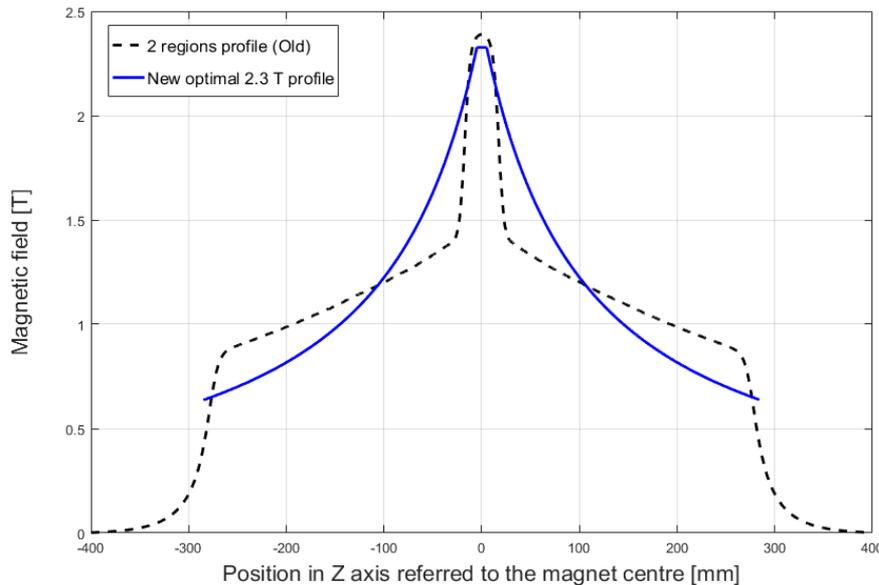
- ❑ Longitudinal trapezium profile: tough challenges. Achieved introducing a **variable gap** along Z axis



- ❑ Magnet originally limited to 1.77 T peak field as a reasonable value for a non-superconducting magnet
- ❑ 3D simulations: peak could be increased above 2 T
- ❑ A new 2.3 T optimized trapezium profile was finally proposed

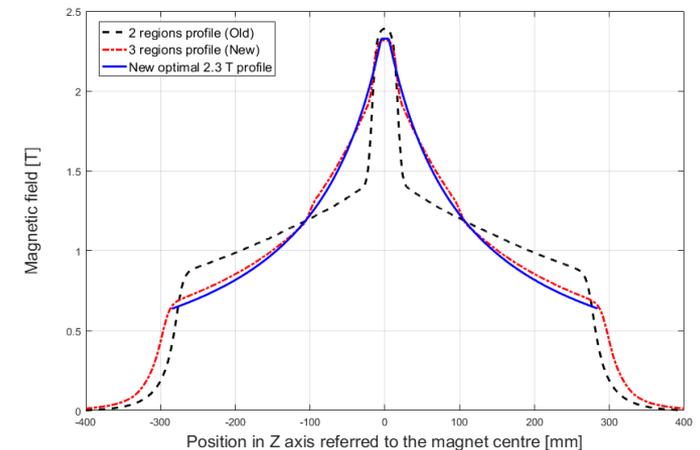
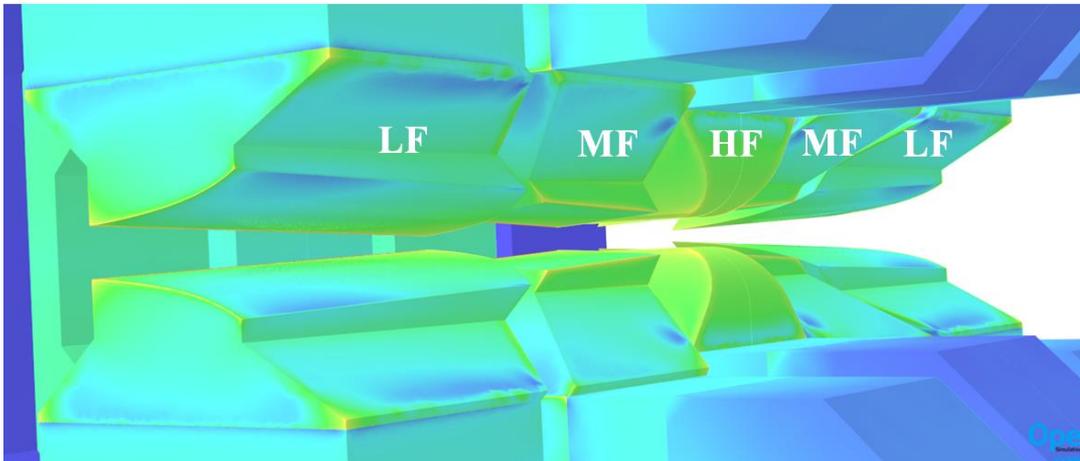
Magnetic design

- ❑ At that point the magnet was close to meet the desired specifications.
- ❑ The obtained decay –“Old profile”, black- at both sides of the peak does not match the ideal one (hyperbolic, blue)
- ❑ The **low field region is split in two parts: low and mid field region**



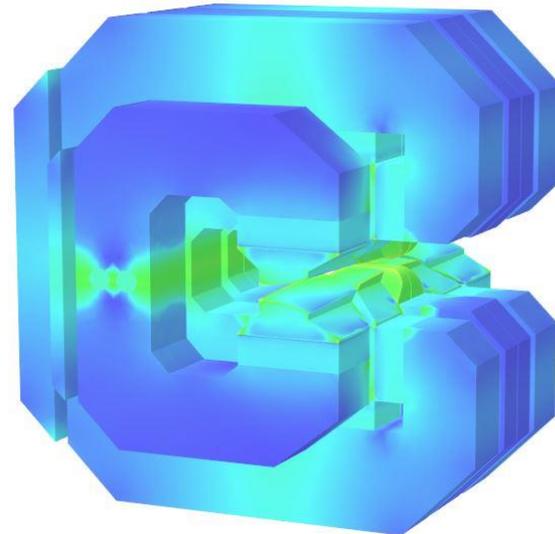
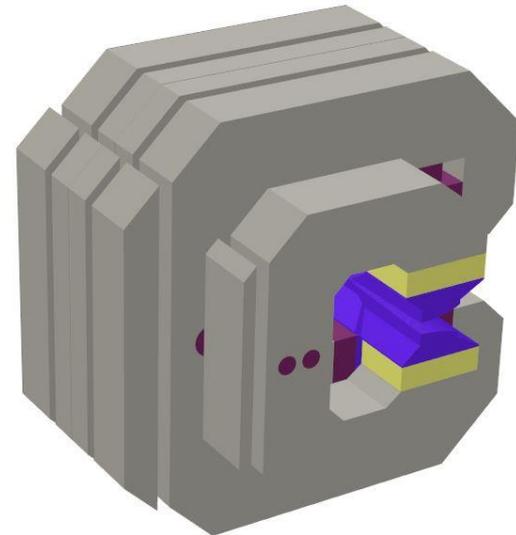
Magnetic design

- ❑ Upgrade: Three differentiated sections: **low, mid and high field**
- ❑ **Maximum field** is increased up to 2.3 T and at the same time the new field decay (red) matches more precisely the ideal hyperbolic desired profile (blue)
- ❑ This allows a higher $F_{TME} = 7$, higher than the one originally proposed (4)

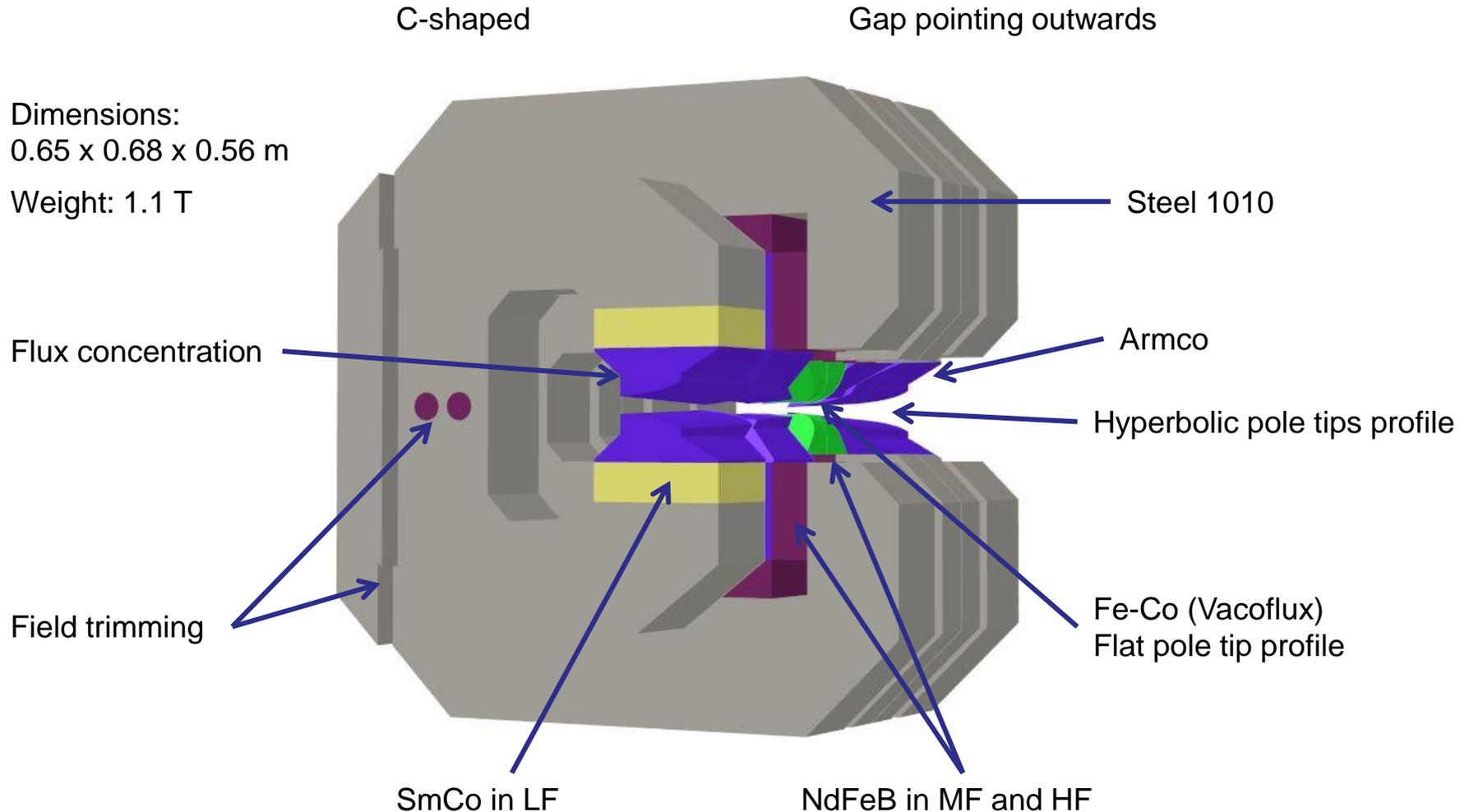


Field trimming

- ❑ Split yoke. Moving parts allow to adjust the magnetic circuit reluctance
- ❑ This solution could not reach the desired $\pm 5\%$ regulation
- ❑ Backup solution: Yoke holes will be filled with steerable permanent magnet rods if more regulation is needed
- ❑ It will reach the $\pm 5\%$ easily



Magnet Overview



Mechanical design

- Forces (analytically calculated with VW method):

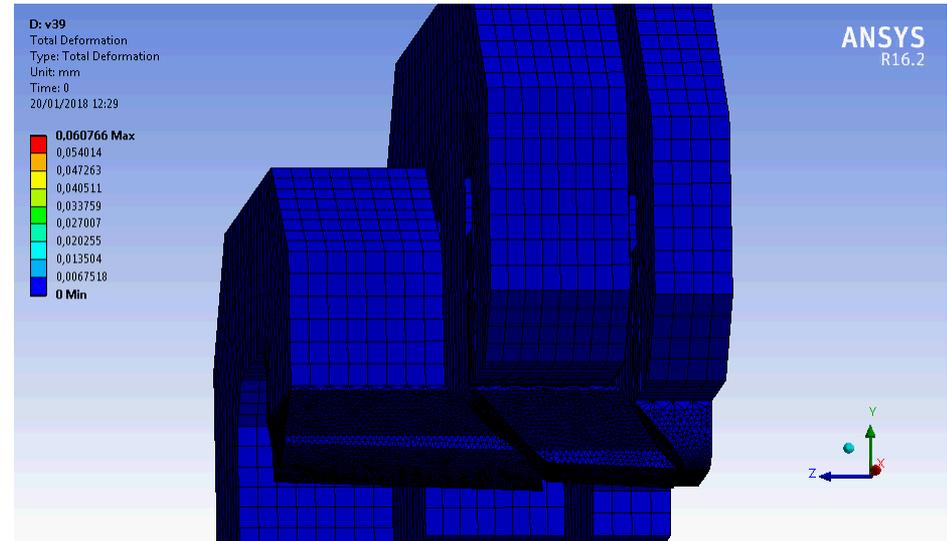
	LF	MF	HF
Y axis	5272 N	5957 N	5425 N
Z axis	1047 N	1210 N	0 N (symmetry)

- Maximum Stress: 69 Mpa

- Max. Deformations:

- Y axis: 0.06 mm
- Z axis: 0,009 mm

- Including these deformations in the Opera model, the multipole values are still kept within the desired values:

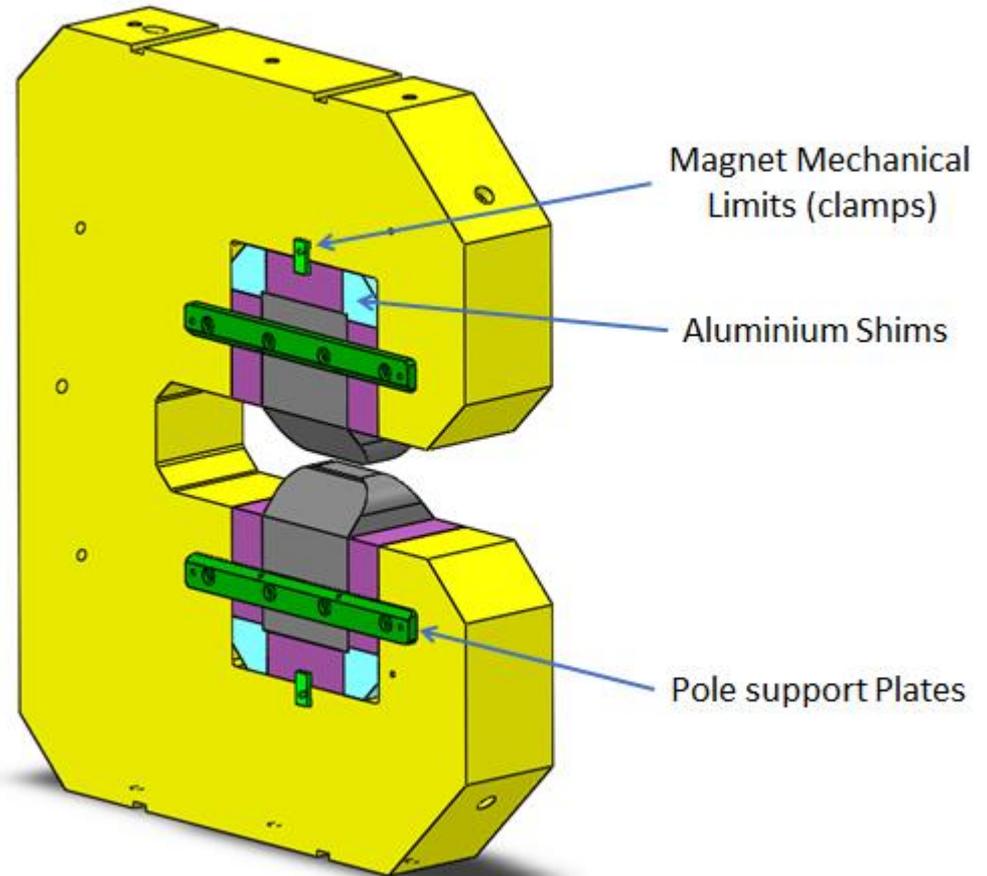


	b1	b2	b3	b4	b5	b6	b7	b8	b9	b10
Base	10000	-567.9	5.5	2.1	-0.1	-0.1	-0.0	0.0	-0.0	0.0
Def	10000	-567.7	5.6	2.0	-0.2	-0.2	-0.1	0.0	-0.0	0.0

Mechanical design

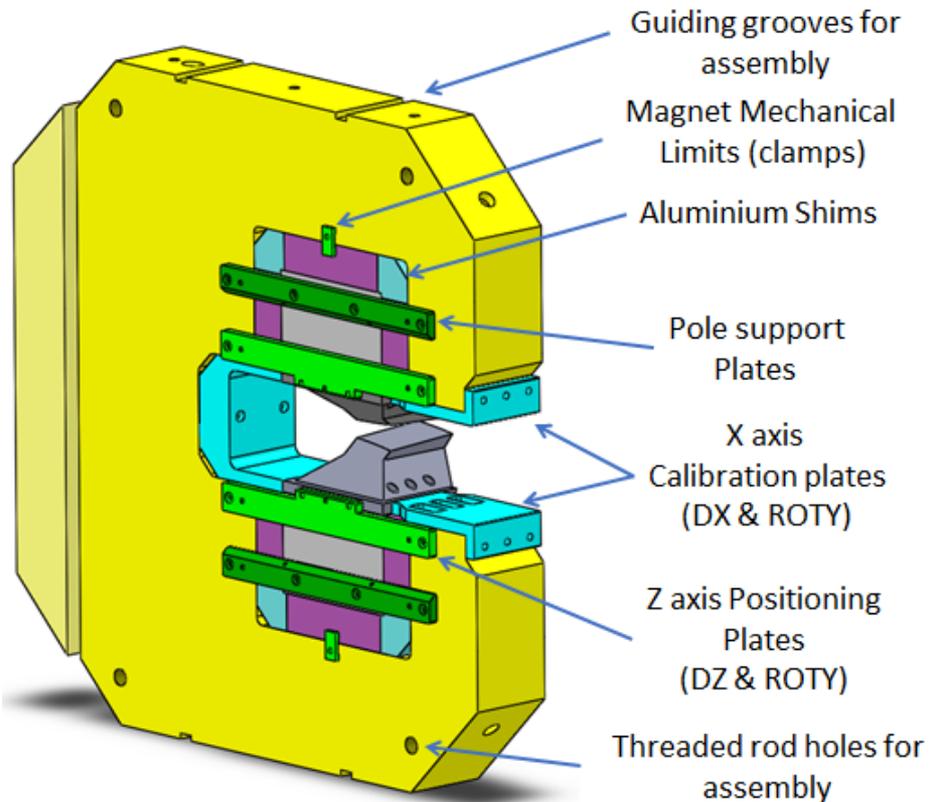
□ HF Module:

- This module will be fixed
- No pole regulation
- Reference

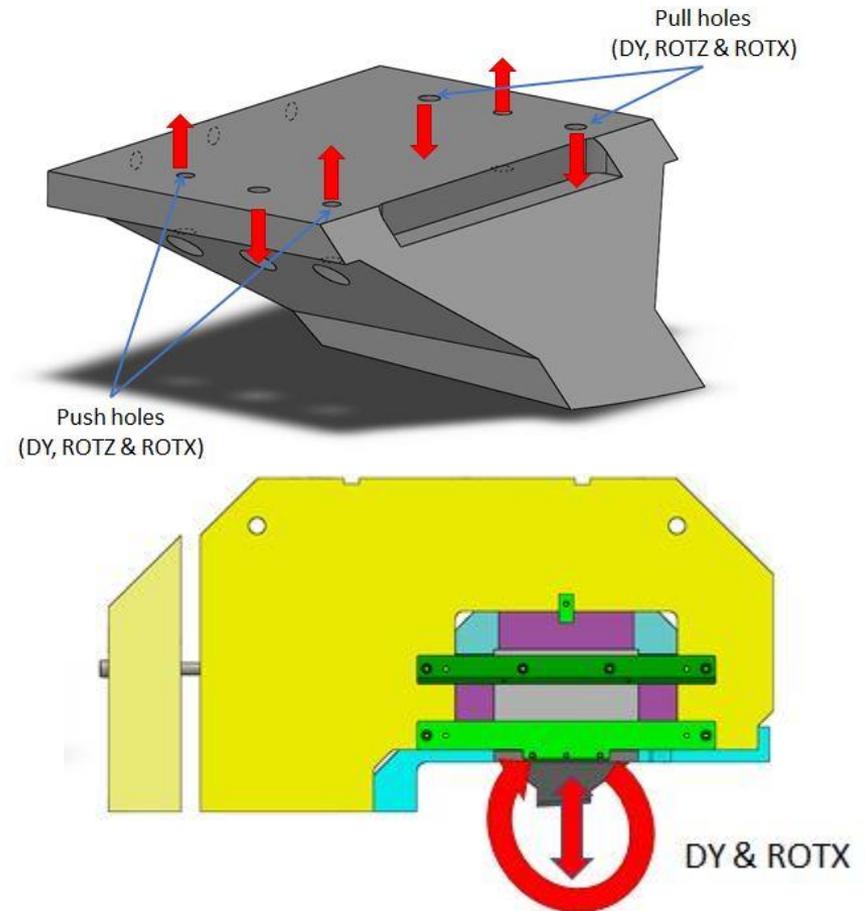


Mechanical design

MF Module:

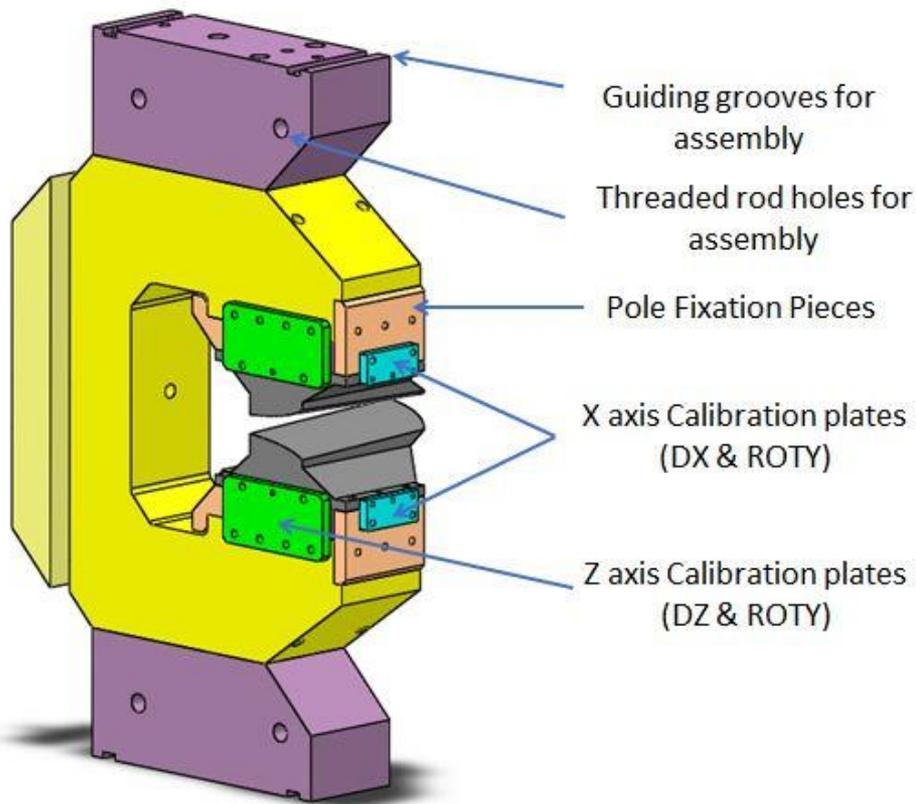


➤ Pole adjustments in X, Y and Z (± 1 mm)

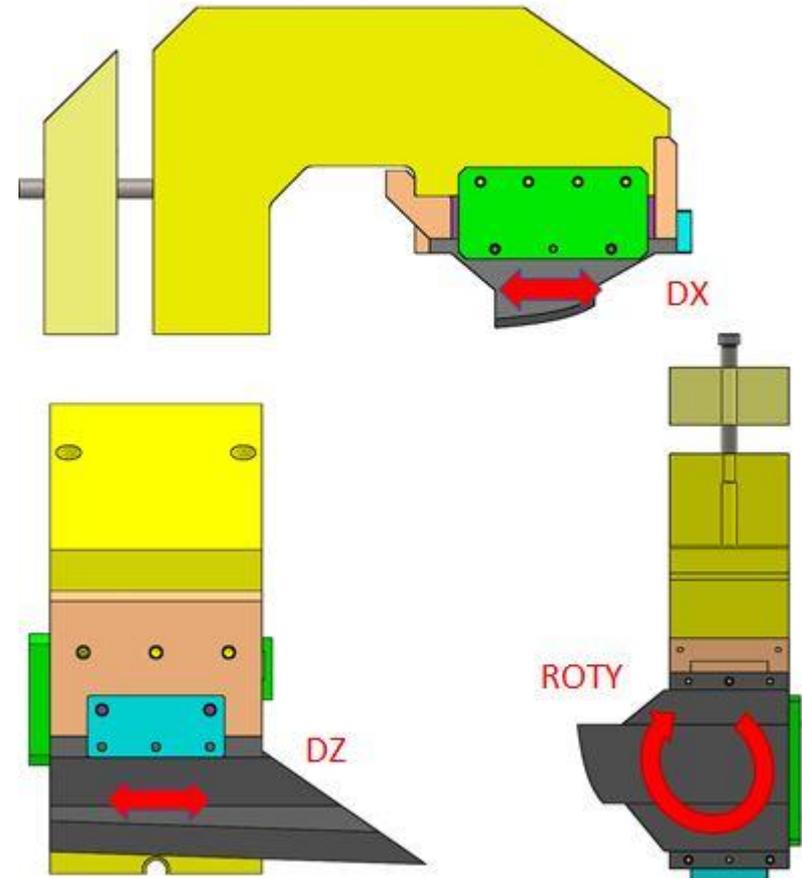


Mechanical design

□ LF Module:

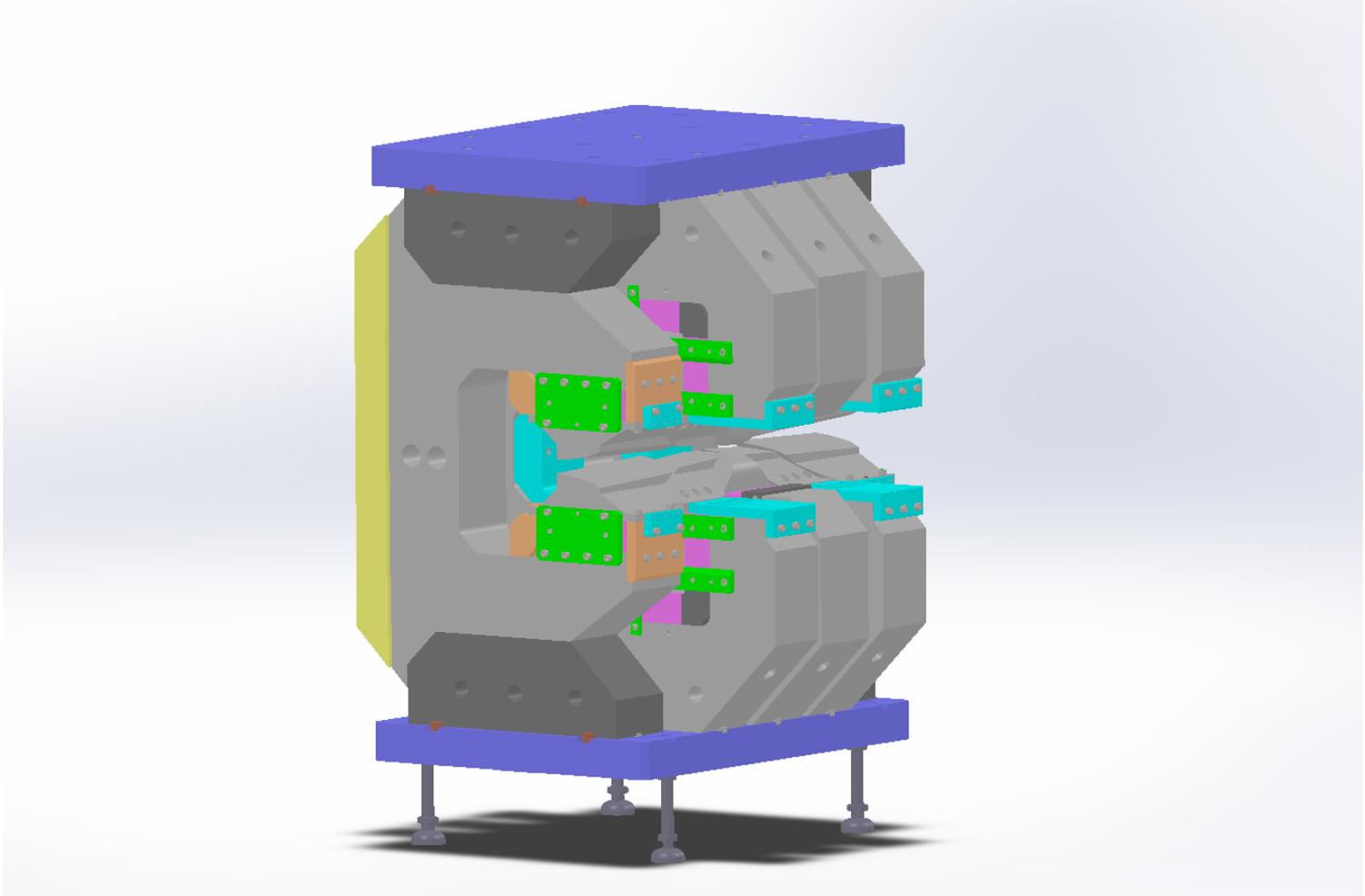


➤ Pole adjustments in X, Y and Z (± 1 mm)



Mechanical design

□ Assembly:



Mechanical design



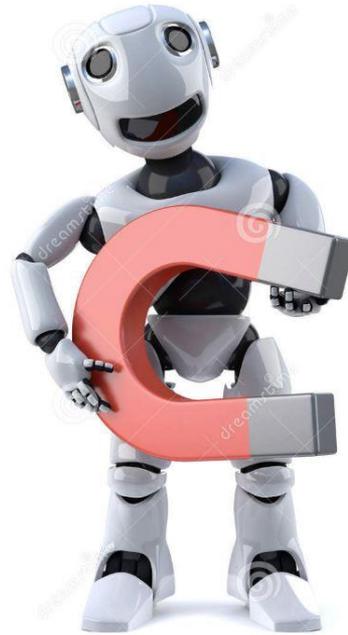
Conclusions

- ❑ PM based design: compact, no power consumption and no maintenance
- ❑ High peak field (saturation)
- ❑ Important challenge: **longitudinal gradient with trapezoidal decay**. Solved splitting the magnet in **three differentiated field regions**
- ❑ The final design **meets –and even exceeds** in terms of beam emittance reduction- the specifications. This achievement is due to the trapezoidal field profile, which has been implemented **for the first time in an accelerator magnet**
- ❑ Multiple backup solutions and adjustments implemented to achieve the desired field quality and specifications

Ongoing work

- ❑ 98% of the pieces produced, received and checked!
- ❑ Remaining 2% already under production
- ❑ Based on this magnet, a proposal was sent to Horizon 2020 Innovation Pilot Project for Particle Accelerators, and finally awarded with the third position in the prototypes category
- ❑ A new version of these magnets will be used in the Elettra new upgrade (*)

➤ (*) For further information, see Emanuel's presentation:
<https://agenda.infn.it/event/20813/contributions/110196/>



Thank you for your attention!