# *Pushing the Limit of Jet Tagging With Graph Neural Networks*

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# Bag of Tricks for a Better Jet Tagger

#### INTRODUCTION

**ScilPost** 

- Jet tagging  $\mathcal{C}^{\mathcal{A}}$ 
	- powerful hammer in experimentalists' toolbox п
	- fun playground for ML enthusiasts  $\overline{\phantom{a}}$
	- Graph neural networks (GNNs) have shown lots of potential for jet tagging
		- top tagging benchmark (2019)  $\overline{\phantom{a}}$ 
			- GNN-based ParticleNet [1902.08570] achieves the best performance
		- since then:  $\mathcal{L}_{\mathcal{A}}$ 
			- ABCNet [2001.05311], Point Cloud Transformer  $\mathcal{L}_{\mathcal{A}}$ [2102.05073]: better performance in quark/gluon tagging
			- LundNet [2012.08526]: surpass ParticleNet in top  $\mathcal{L}_{\mathcal{A}}$ tagging
			- …  $\mathcal{L}_{\mathcal{A}}$
		- now: can we do even better? and how?  $\overline{\phantom{a}}$

#### *"Top Tagging Landscape"*



Figure 5: ROC curves for all algorithms evaluated on the same test sample, shown [*[1902.09914](https://arxiv.org/abs/1902.09914)*] as the AUC ensemble median of multiple trainings. More precise numbers as well as wel G. Kasieczka et al.

 $\mathcal{L}_{\mathcal{A}}$ 

# RECAP: *PARTICLENET*

- ParticleNet
	- jet treated as a permutation-invariant point cloud п
	- customized graph neural network architecture for jet tagging based on  $\mathcal{L}_{\mathcal{A}}$ Dynamic Graph CNN [Y. Wang et al., *arXiv:1801.07829*]
	- Key building block: *EdgeConv*
		- treating a point cloud as a graph: each point is a vertex  $\overline{\phantom{a}}$ 
			- for each point, a local patch is defined by finding its k-nearest neighbors
		- designing a permutation-invariant "convolution" function  $\overline{\phantom{a}}$ 
			- learn an "edge feature" for each center-neighbor pair:  $e_{ii}$  = MLP( $x_i$ ,  $x_i$ )
				- same MLP for all neighbor points, and all center points, for symmetry
			- aggregate the edge features in a symmetric way:  $\mathsf{x_i}'$  =  $\mathsf{mean}_j$   $\mathsf{e_{ij}}$







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### *PARTICLENEXT*: PAIRWISE FEATURES

- ParticleNeXt: next-generation of ParticleNet, for better performance *f*  $\mathcal{C}$
- The first enhancement is the addition of (explicit) pairwise features on the edges  $\mathcal{L}_{\mathcal{A}}$ *W±, Z*0 *f*



$$
\mathbf{e}_{ij} = \mathsf{MLP}(\mathbf{x}_i, \mathbf{x}_j)
$$



$$
e_{ij} = \mathsf{MLP}(\mathbf{x}_i, \mathbf{x}_j) \qquad \qquad e_{ij} = \mathsf{MLP}(\mathbf{x}_i, \mathbf{x}_j, \mathbf{x}_{ij})
$$

$$
\mathbf{e}_{ij} = \mathsf{MLP}(\mathbf{x}_i, \mathbf{x}_j, \mathbf{x}_{ij})
$$
\nExamples of pairwise features:

\n
$$
\Delta_{ij}^2 \equiv (y_i - y_j)^2 + (\phi_i - \phi_j)^2, \quad m^2 \equiv (p_i + p_j)^2,
$$
\n
$$
k_T \equiv \min(p_{T,i}, p_{T,j}) \Delta_{ij}, \quad z \equiv \frac{\min(p_{T,i}, p_{T,j})}{p_{T,i} + p_{T,j}}
$$
\n(use the logarithm to improve stability of the training)

#### *PARTICLENEXT*: ATTENTIVE POOLING

- Use attention-based pooling to increase the expressive power  $\mathcal{C}^{\mathcal{A}}$ 
	- for both the **local neighborhood pooling**, and the final **global pooling** г



#### *PARTICLENEXT*: MULTI-SCALE AGGREGATION

- Introduce multi-scale aggregation to better capture both short- and long-range correlations  $\mathcal{L}_{\mathcal{A}}$ 
	- perform local aggregation for the 4, 8, 16 and 32 nearest neighbors (with different attentive  $\mathcal{L}_{\mathcal{A}}$ pooling) and combine the 4 aggregated representations with a MLP
	- on the other hand: remove dynamic kNN (based on learned features), i.e., use only kNN in η—φ  $\mathbb{R}^2$ space, to reduce computational cost
		- in this case the kNN needs to be performed only once, and then the graph connectivity is fixed  $\mathcal{L}_{\mathcal{A}}$



#### DATASET

- A new jet tagging dataset was generated for the development of ParticleNeXt
	- all events are generated with MadGraph5  $\alpha$ MC@NLO v3.1.1 at LO and interfaced with Pythia  $\overline{\phantom{a}}$ v8.245 for parton shower (w/ the default tune and MPI enabled)
	- fast detector simulation w/ Delphes v3.5.0, using the CMS card  $\overline{\phantom{a}}$ 
		- tracking resolution parametrization based on the CMS Run1 performance [1405.6569]
	- jets clustered from the Delphes e-flow objects using the anti-kt algorithm w/ R=0.8  $\overline{\phantom{a}}$ 
		- only consider jets w/  $500 < p_T$  1000 GeV, and  $|\eta| < 2$ m.
		- input features for each jet constituent particle: 4-momenta, PID, **impact parameters and errors** m.
	- top-tagging benchmark:  $\mathcal{L}_{\mathcal{A}}$ 
		- Top quark jets:  $pp \to t\bar{t}$   $(t \to bW, W \to qq')$  $\mathcal{L}_{\mathcal{A}}$ 
			- truth matching criteria: ΔR(jet, q) < 0.8 for all three quarks from hadronic top decay
		- $QCD$  jets:  $pp \rightarrow Z(\rightarrow \nu \bar{\nu}) + j$  ( $j = u, d, s, c, b, g$ ) ш
		- Higgs-tagging benchmark:
			- Higgs boson jets:  $pp \to hh \; (h \to b\bar{b})$  $\mathcal{L}_{\mathcal{A}}$ 
				- truth matching criteria: ΔR(jet, b) < 0.8 for both quarks from the Higgs decay  $\overline{\phantom{a}}$
			- $QCD$  jets:  $pp \rightarrow Z(\rightarrow \nu \bar{\nu}) + j$  ( $j = u, d, s, c, b, g$ )  $\mathbb{R}^n$

 $\overline{\phantom{a}}$ 

#### PERFORMANCE: TOP TAGGING



- Training/validation/test splitting:  $\overline{\phantom{a}}$ 
	- 1.6M / 0.4M / 2M n.
- Training repeated for 3 times starting from randomly initialized weights
	- the median-accuracy training is reported, and the standard deviation of the 3 trainings is quoted as the uncertainty
- Significant improvement in background rejection w/ ParticleNeXt
	- ~50% higher BKG rejection (@ $\epsilon^{}_{S}$  = 70%)  $\overline{y}$
	-



## ABLATION STUDY



- Investigated the effects of the new features of ParticleNeXt by removing
	-
- $\mathbb{Z}^{\pm}$  in the three is removed



### MODEL ENSEMBLING



- Model ensembling still helps, even for the new ParticleNeXt
	- trainings
- $\mathbb{Z}^{\perp}$   $\blacksquare$  ~30% improvement for ParticleNeXt with the 3-model ensemble
	-



#### EXTENDED TRAINING DATASET



Training on a larger dataset

training/validation/test splitting:

10M / 1M / 2M  $\mathcal{L}$ 

- i.e., 5x more jets for training compared to the baseline dataset
- Substantial gain in performance

 $\sim$ 70% higher BKG rejection (@ $\epsilon_{S}$  = 70%)

*Question:* Can we encode more physics TABLE 100 The network to make the training



#### PERFORMANCE: HIGGS TAGGING



Baseline dataset: r.

- training/validation/test splitting:
	- 1.6M / 0.4M / 2M  $\mathcal{L}_{\mathcal{A}}$
- Extended dataset: п
	- training/validation/test splitting:
		- 10M / 1M / 2M  $\blacksquare$
- Consistent improvement for ParticleNeXt r. in Higgs tagging as well
	- ~30% higher BKG rejection than ParticleNet
	-



#### PERFORMANCE ON PUBLIC BENCHMARKS ENFUNITAINUE UIN I UDLIU I  $\Gamma$ trainings Dentainings with  $\Gamma$ i Fijkin Goenic hiviarkn highest performance.

#### *Top tagging landscape*





Acc AUC 1/✏*<sup>B</sup>* (✏*<sup>S</sup>* = 0*.*5) 1/✏*<sup>B</sup>* (✏*<sup>S</sup>* = 0*.*3)



*V. Mikuni, F. Canelli*

6 Computational cost

## SUMMARY & OUTLOOK

#### ParticleNeXt

- new GNN architecture for jet tagging  $\mathcal{L}_{\mathcal{A}}$
- enhanced expressiveness w/ several new features in the network design  $\overline{\phantom{a}}$
- significant performance improvement as demonstrated in the top and Higgs tagging  $\mathcal{L}_{\mathcal{A}}$ benchmarks
- paper, code and dataset to come soon stay tuned!  $\mathcal{L}_{\mathcal{A}}$
- Still, performance can be further improved via:
	- model ensembling  $\mathcal{L}_{\mathcal{A}}$
	- extending training dataset  $\overline{\phantom{a}}$
- Models that better incorporate physically-motivated inductive biases are likely to bring better data-efficiency, and to improve the performance as well

 $\overline{\phantom{a}}$ 



#### INPUT FEATURES

