

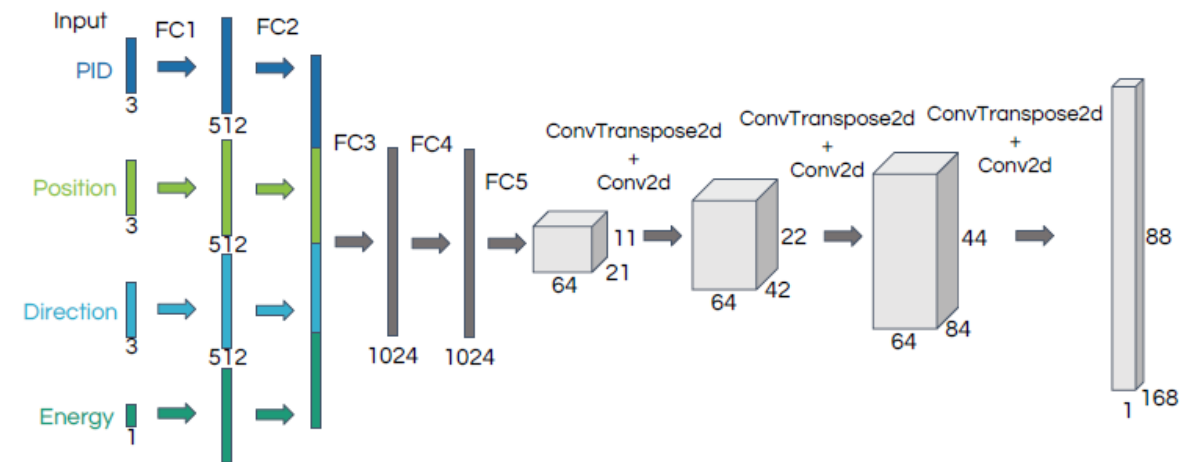
# Conv2d and ConvTransposed2d

Chiaki Yanagisawa

Water Cherenkov with Deep Learning Zoom meeting

2/19/2021

# Our Network



```

self._upconvs = torch.nn.Sequential(
    torch.nn.ConvTranspose2d(64, 64, 4, 2), torch.nn.ReLU(), # 24 x 44
    torch.nn.Conv2d(64, 64, 3), torch.nn.ReLU(), # 22 x 42
    torch.nn.ConvTranspose2d(64, 32, 4, 2), torch.nn.ReLU(), # 46 x 86
    torch.nn.Conv2d(32, 32, 3), torch.nn.ReLU(), # 44 x 84
    torch.nn.ConvTranspose2d(32, 32, 4, 2), torch.nn.ReLU(), # 90 x 170
    torch.nn.Conv2d(32, 3, 3) # 88 x 168
)

```

# Convolution

## Conv2d

```
class torch.nn.Conv2d(in_channels: int, out_channels: int, kernel_size: Union[T, Tuple[T, T]],  
                      stride: Union[T, Tuple[T, T]] = 1, padding: Union[T, Tuple[T, T]] = 0, dilation: Union[T,  
                      Tuple[T, T]] = 1, groups: int = 1, bias: bool = True, padding_mode: str = 'zeros')
```

Input :  $(N, C_{in}, H_{in}, W_{in})$   $N$  = batch size,  $C_{in}$  = input channels,  $H_{in}$  = input height,  $W_{in}$  = input width

Output:  $(N, C_{out}, H_{out}, W_{out})$   $N$  = batch size,  $C_{out}$  = output channels,  $H_{out}$  = output height,  $W_{out}$  = output width

$$H_{out} = \frac{H_{in} + 2 \times \text{padding}[0] - \text{dilation}[0] \times (\text{kernel\_size}[0] - 1) - 1}{\text{stride}[0]} + 1$$

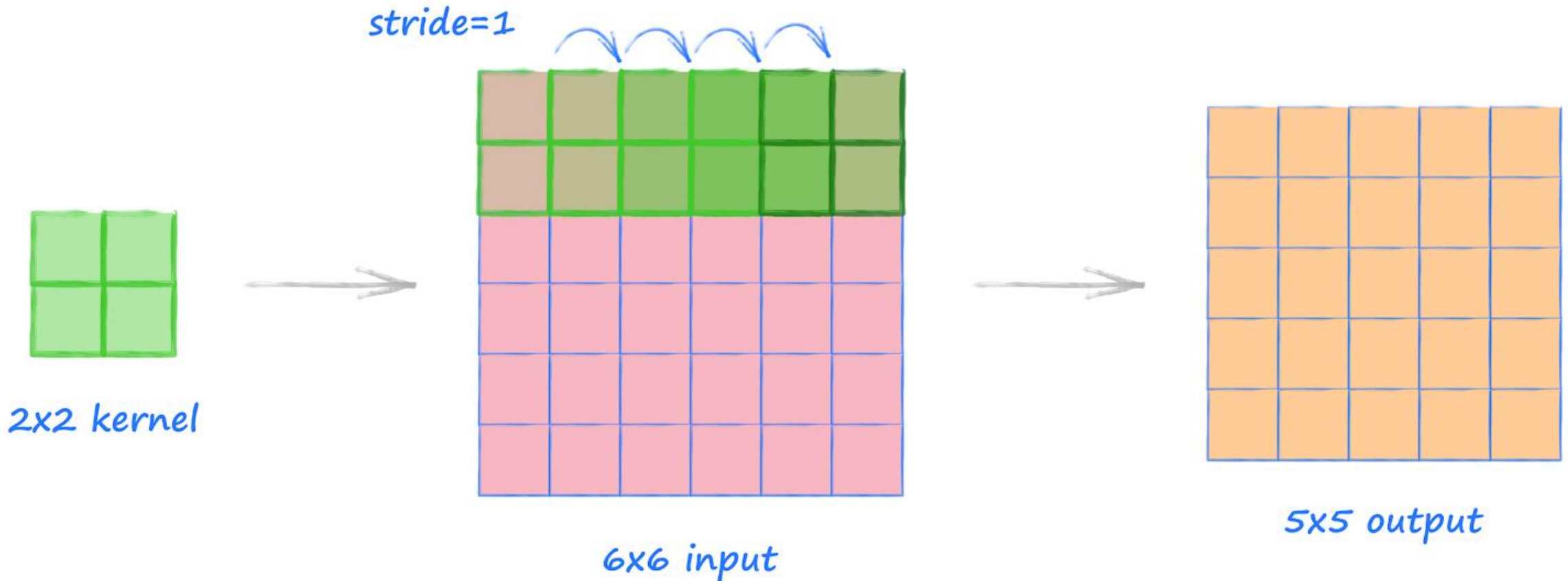
$$W_{out} = \frac{W_{in} + 2 \times \text{padding}[1] - \text{dilation}[1] \times (\text{kernel\_size}[1] - 1) - 1}{\text{stride}[1]} + 1$$

# Convolution

## Example 1: Convolution With Stride 1, No Padding

```
nn.Conv2d(in_channels, out_channels, kernel_size=2, stride=1)
```

In this first simple example we apply a **2 by 2 kernel** to an input of size **6 by 6**, with stride **1**.

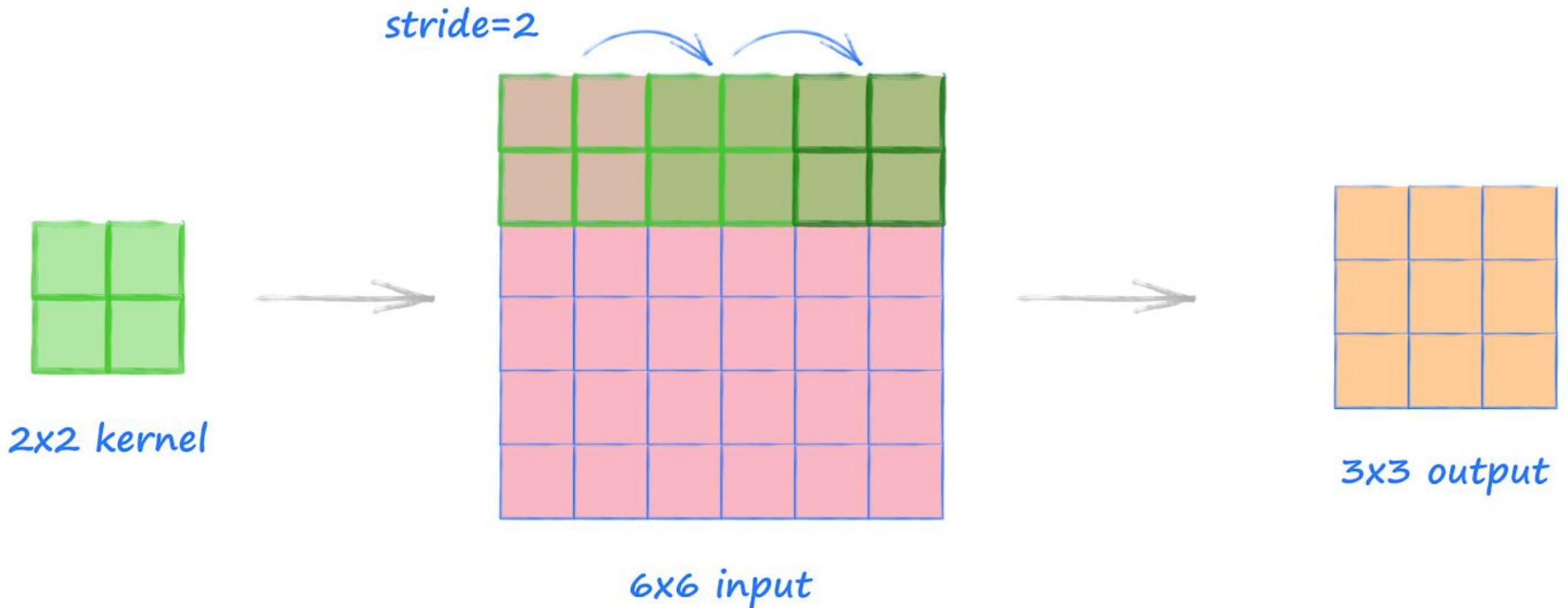


# Convolution

## Example 2: Convolution With Stride 2, No Padding

`nn.Conv2d(in_channels, out_channels, kernel_size=2, stride=2)`

This second example is the same as the previous one, but we now have a stride of 2.

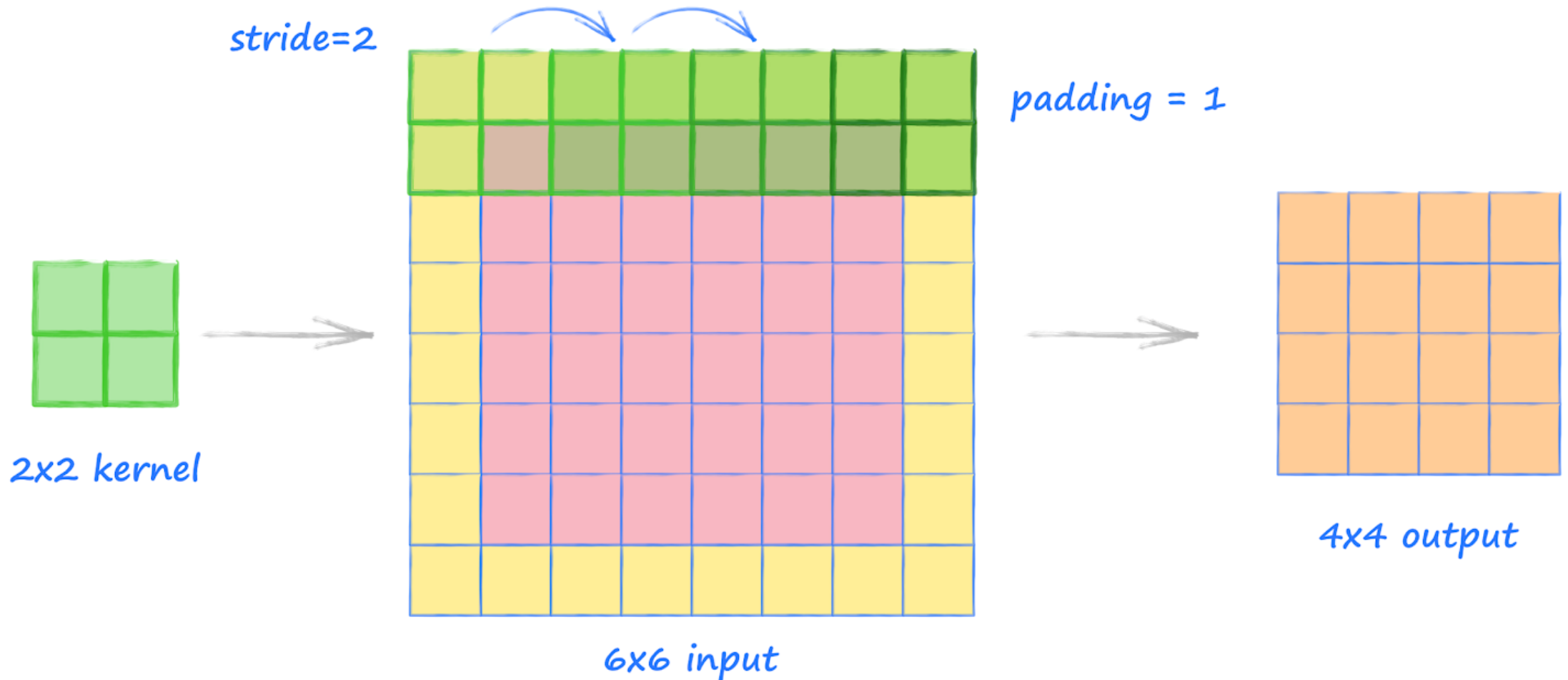


# Convolution

## Example 3: Convolution With Stride 2, With Padding

`nn.Conv2d(in_channels, out_channels, kernel_size=2, stride=2, padding=1)`

This third example is the same as the previous one, but this time we use a padding of 1.



# Transposed Convolution

## ConvTranspose2d

*class torch.nn.ConvTranspose2d(in\_channels: int, out\_channels: int, kernel\_size: Union[T, Tuple[T, T]], stride: Union[T, Tuple[T, T]] = 1, padding: Union[T, Tuple[T, T]] = 0, output\_padding: Union[T, Tuple[T, T]] = 0, groups: int = 1, bias: bool = True, dilation: int = 1, padding\_mode: str = 'zeros')*

Input :  $(N, C_{in}, H_{in}, W_{in})$   $N$  = batch size,  $C_{in}$  = input channels,  $H_{in}$  = input height,  $W_{in}$  = input width

Output:  $(N, C_{out}, H_{out}, W_{out})$   $N$  = batch size,  $C_{out}$  = output channels,  $H_{out}$  = output height,  $W_{out}$  = output width

$$H_{out} = (H_{in} - 1) \times \text{stride}[0] - 2 \times \text{padding}[0] + \text{dilation}[0] \times (\text{kernel\_size}[0] - 1) + \text{output\_padding}[0] + 1$$

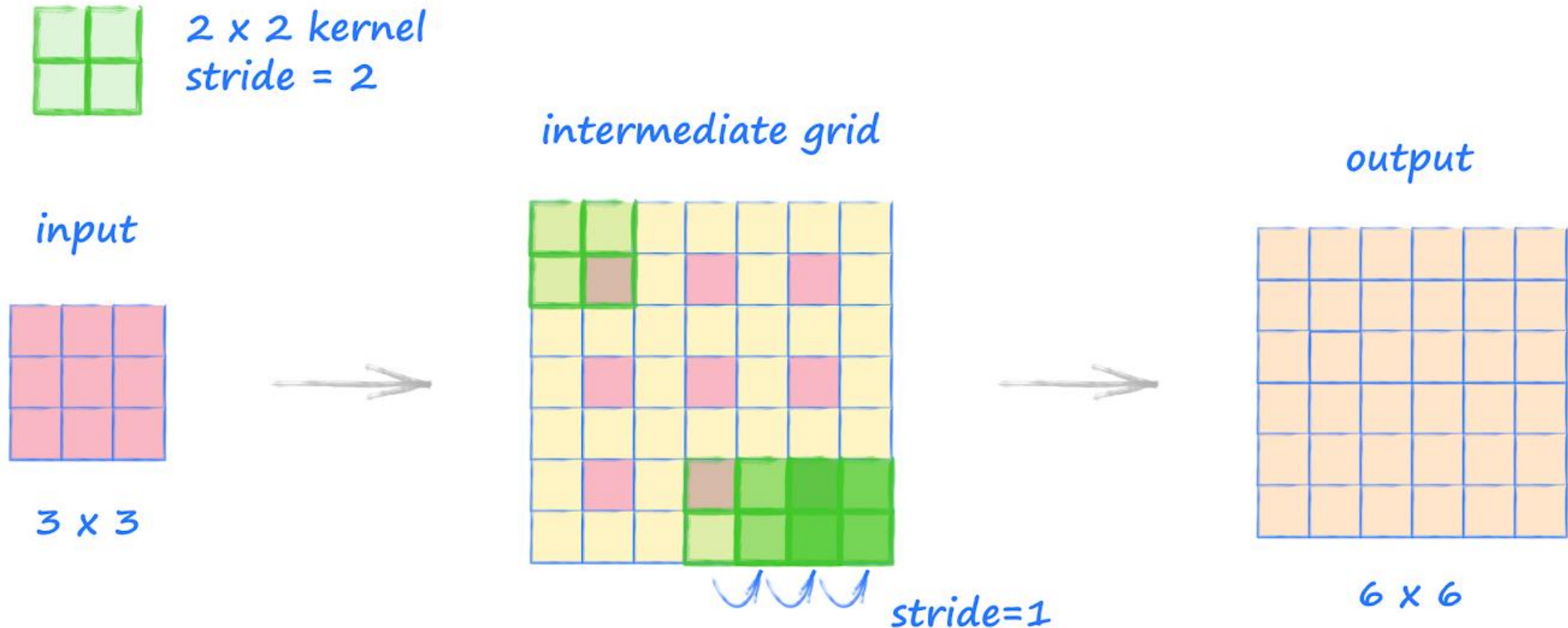
$$W_{out} = (W_{in} - 1) \times \text{stride}[1] - 2 \times \text{padding}[1] + \text{dilation}[1] \times (\text{kernel\_size}[1] - 1) + \text{output\_padding}[1] + 1$$

# Transposed Convolution

## Example 5: Transpose Convolution With Stride 2, No Padding

`nn.ConvTranspose2d(in_channels, out_channels, kernel_size=2, stride=2, padding=0)`

The transpose convolution is commonly used to expand a tensor to a larger tensor. This is the opposite of a normal convolution which is used to reduce a tensor to a smaller tensor.



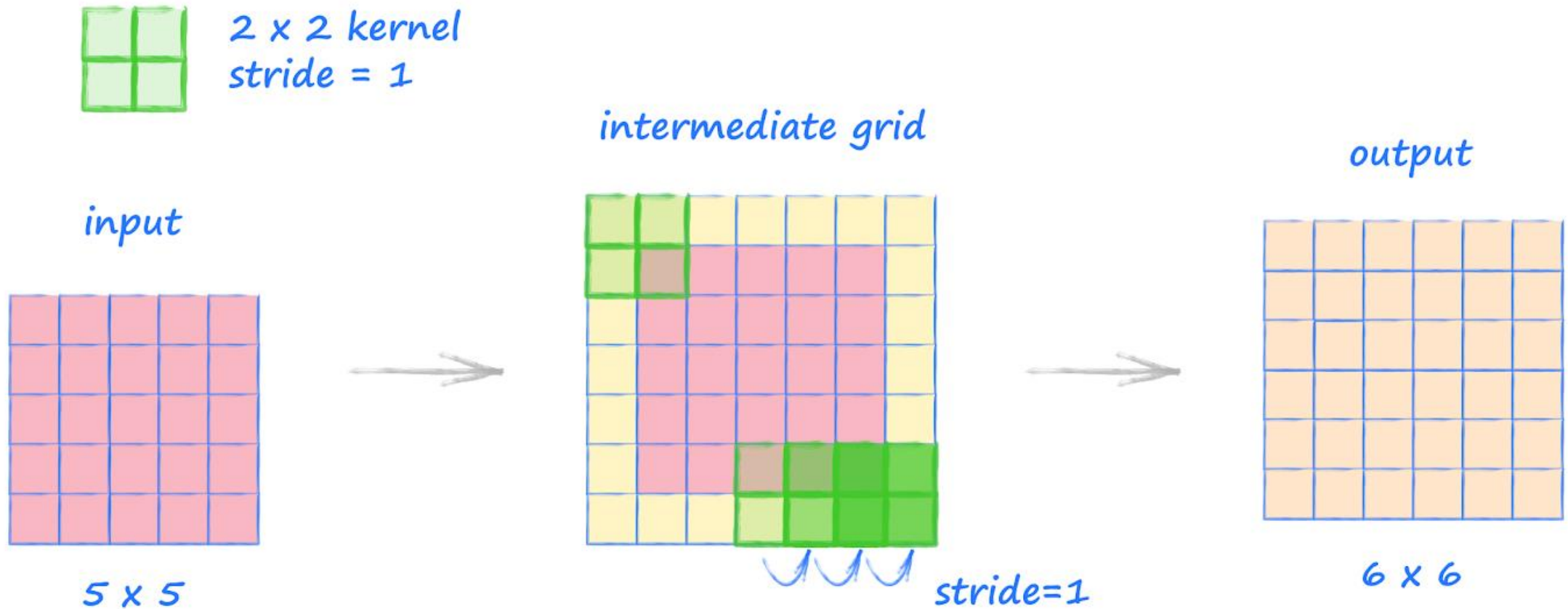


# Transposed Convolution

## Example 6: Transpose Convolution With Stride 1, No Padding

`nn.ConvTranspose2d(in_channels, out_channels, kernel_size=2, stride=1, padding=0)`

In the previous example we used a stride of 2 because it is easier to see how it is used in the process. In this example we use a stride of 1.

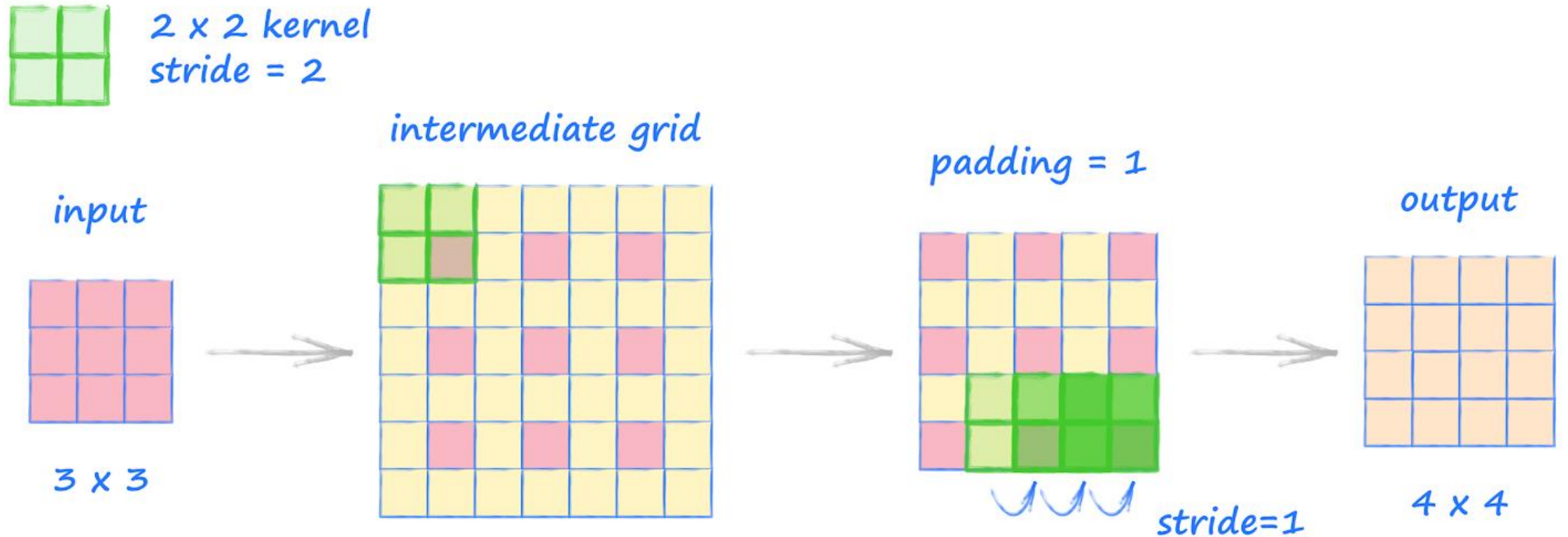


# Transposed Convolution

## Example 7: Transpose Convolution With Stride 2, With Padding

`nn.ConvTranspose2d(in_channels, out_channels, kernel_size=2, stride=2, padding=1)`

In this transpose convolution example we introduce padding. Unlike the normal convolution where padding is used to expand the image, here it is used to reduce it.





# Upconv Layers of Our Network

## First layer

Input ch = 64, output ch = 64,  $H_{in} = 11$ ,  $W_{in} = 21$ , kernel size = 4, stride = 2, dilation = 1, padding = 0, output padding = 0

$$\text{ConvTranse2d}(64, 64, 4, 2) : H_{out} = (11 - 1) \times 2 - 2 \times 0 + 1 \times (4 - 1) + 0 + 1 = 24$$
$$W_{out} = (21 - 1) \times 2 - 2 \times 0 + 1 \times (4 - 1) + 0 + 1 = 44$$

Input ch = 64, output ch = 64,  $H_{in} = 24$ ,  $W_{in} = 44$ , kernel size = 3, stride = 1, dilation = 1, padding = 0, output padding = 0

$$\text{Conv2d}(64, 64, 3) : H_{out} = [24 - 2 \times 0 - 1 \times (3 - 1) - 1] / 1 + 1 = 22$$
$$W_{out} = [44 - 2 \times 0 - 1 \times (3 - 1) - 1] / 1 + 1 = 42$$

# Upconv Layers of Our Network

## Second layer

Input ch = 64, output ch = 32,  $H_{in} = 22$ ,  $W_{in} = 42$ , kernel size = 4, stride = 2, dilation = 1, padding = 0, output padding = 0

$$\text{ConvTranse2d}(64, 32, 4, 2) : H_{out} = (22 - 1) \times 2 - 2 \times 0 + 1 \times (4 - 1) + 0 + 1 = 46$$
$$W_{out} = (42 - 1) \times 2 - 2 \times 0 + 1 \times (4 - 1) + 0 + 1 = 86$$

Input ch = 32, output ch = 32,  $H_{in} = 46$ ,  $W_{in} = 86$ , kernel size = 3, stride = 1, dilation = 1, padding = 0, output padding = 0

$$\text{Conv2d}(32, 32, 3) : H_{out} = [46 - 2 \times 0 - 1 \times (3 - 1) - 1] / 1 + 1 = 44$$
$$W_{out} = [86 - 2 \times 0 - 1 \times (3 - 1) - 1] / 1 + 1 = 84$$

# Upconv Layers of Our Network

## Third layer

Input ch = 32, output ch = 32,  $H_{in} = 44$ ,  $W_{in} = 84$ , kernel size = 4, stride = 2, dilation = 1, padding = 0, output padding = 0

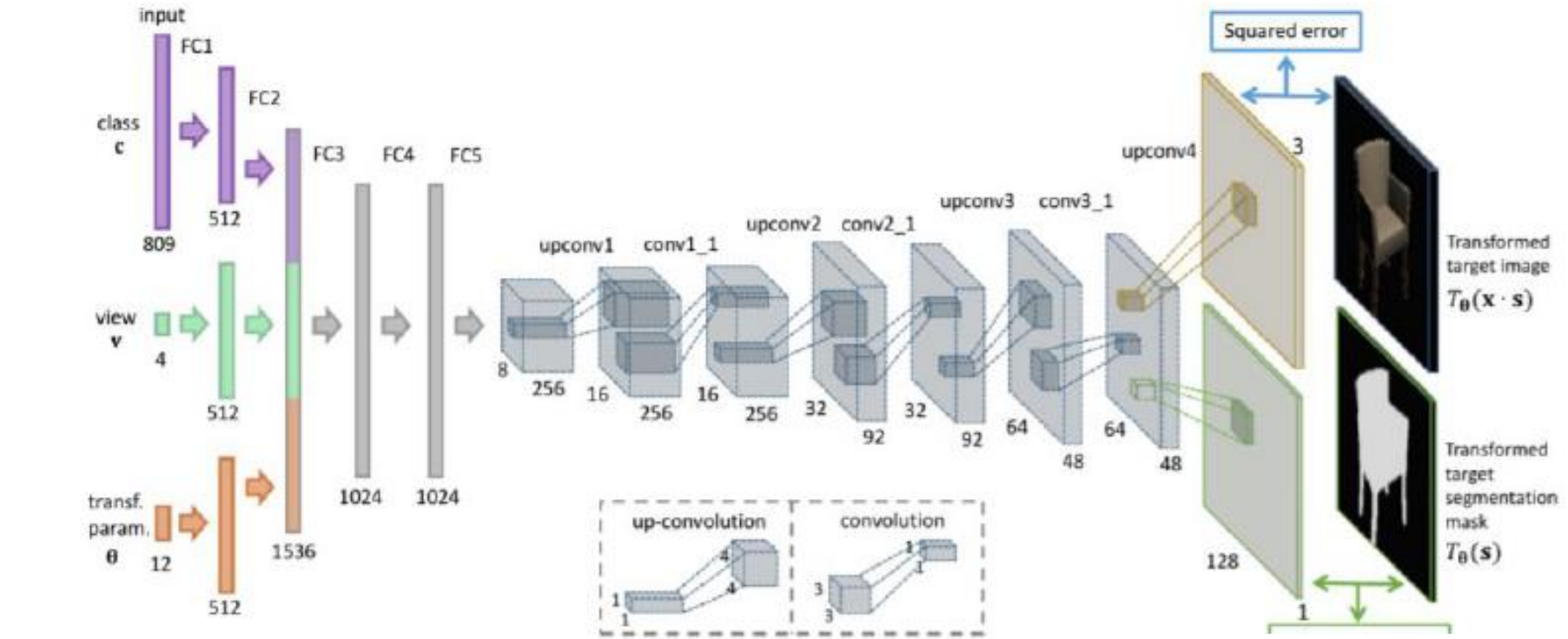
$$\text{ConvTranse2d}(64, 32, 4, 2) : H_{out} = (44 - 1) \times 2 - 2 \times 0 + 1 \times (4 - 1) + 0 + 1 = 90$$
$$W_{out} = (84 - 1) \times 2 - 2 \times 0 + 1 \times (4 - 1) + 0 + 1 = 170$$

Input ch = 32, output ch = 1,  $H_{in} = 90$ ,  $W_{in} = 170$ , kernel size = 3, stride = 1, dilation = 1, padding = 0, output padding = 0

$$\text{Conv2d}(32, 1, 3) : H_{out} = [90 - 2 \times 0 - 1 \times (3 - 1) - 1] / 1 + 1 = 88$$
$$W_{out} = [170 - 2 \times 0 - 1 \times (3 - 1) - 1] / 1 + 1 = 168$$

Note:  $88 \times 168 = 64 \times 11 \times 21 = 14784$

# Upconv Layers of Original Paper



Bed of nails upsampling

“Bed of Nails”

1	2
3	4

Input: 2 x 2

1	0	2	0
0	0	0	0
3	0	4	0
0	0	0	0

Output: 4 x 4

# Upsampling

## Nearest-Neighbor

### Nearest Neighbor

1	2
3	4



1	1	2	2
1	1	2	2
3	3	4	4
3	3	4	4

Input: 2 x 2

Output: 4 x 4

## Bed of Nails

### “Bed of Nails”

1	2
3	4



1	0	2	0
0	0	0	0
3	0	4	0
0	0	0	0

Input: 2 x 2

Output: 4 x 4

10	20
30	40

2x2



2x

10	12	17	20
15	17	22	25
25	27	32	35
30	32	37	40

4x4

## Interpolation

Bilinear,....

- The transposed convolution is the cause of the checkerboard artifacts in generated images.
- Some recommend an upsampling operation (i.e. interpolation method) followed by a convolution that preserves the image size to reduce such effects.
- The weights in the transposed convolution are learnable, while the upsampling operation is not learnable.



# References

- <https://arxiv.org/pdf/1603.07285.pdf>
- Slides by Karan Yang on 9/13/2019 (I will post it at CERN) at this meeting
- <https://distill.pub/2016/deconv-checkerboard/>
- <https://towardsdatascience.com/types-of-convolutions-in-deep-learning-717013397f4d>
- <https://makeyourownneuralnetwork.blogspot.com/2020/02/calculating-output-size-of-convolutions.html>
- <https://medium.com/jun-devpblog/dl-12-unsampling-unpooling-and-transpose-convolution-831dc53687ce>

# Our Network

