

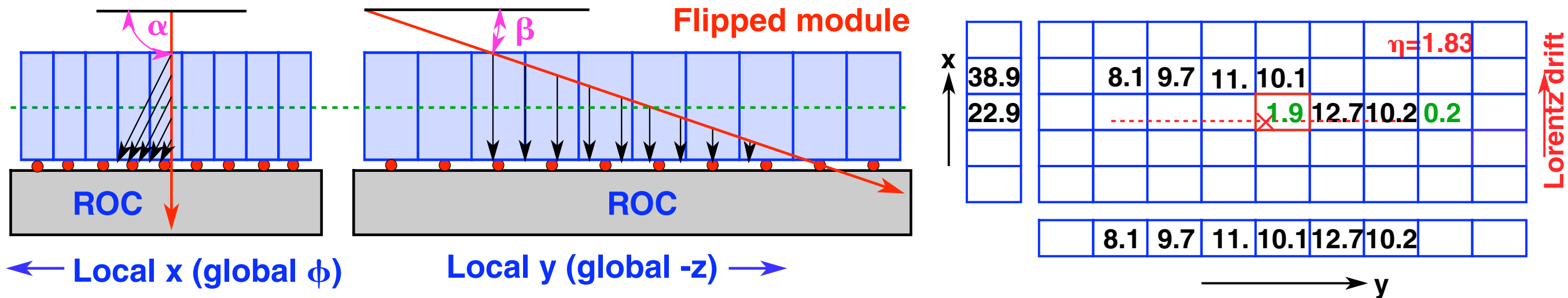
Calibration of Radiation Damage: Effects on Pixel Reconstruction

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Hit Reconstruction

Tracks deposit distinct patterns of charge on the pixel sensors



- Hit position estimation is based on 1D projections of the 2D cluster
 - factorizes due to field configurations and cell periodicity
 - projected shapes depend upon the projected angles α and β
 - * reconstruction algorithms use angle information iteratively
- Two techniques used in track reconstruction
 - "Generic" technique is η -like, uses end pixel charges of projection
 - * faster, less precise algorithm used for all but last tracking pass
 - * needs external Lorentz drift calibration
 - "Template" technique fits projections to simulated profiles
 - * slower, more precise algorithm used for final fitting pass
 - * needs full cluster shape calibration
 - * generates probabilities that test the consistency of the shapes

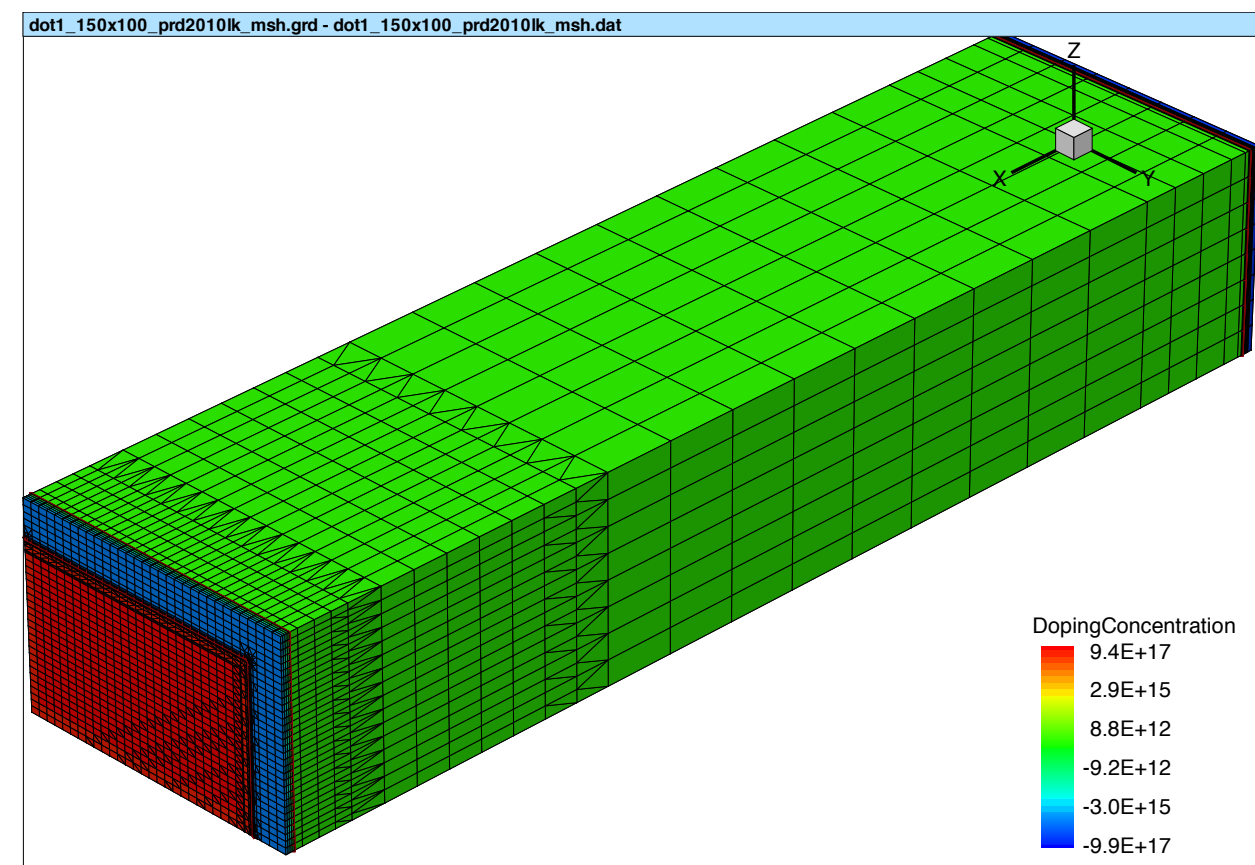
Pixelav Detailed Simulation

Created to interpret beam tests of irradiated sensors, now used to perform Lorentz calibrations and generate template profile shapes:

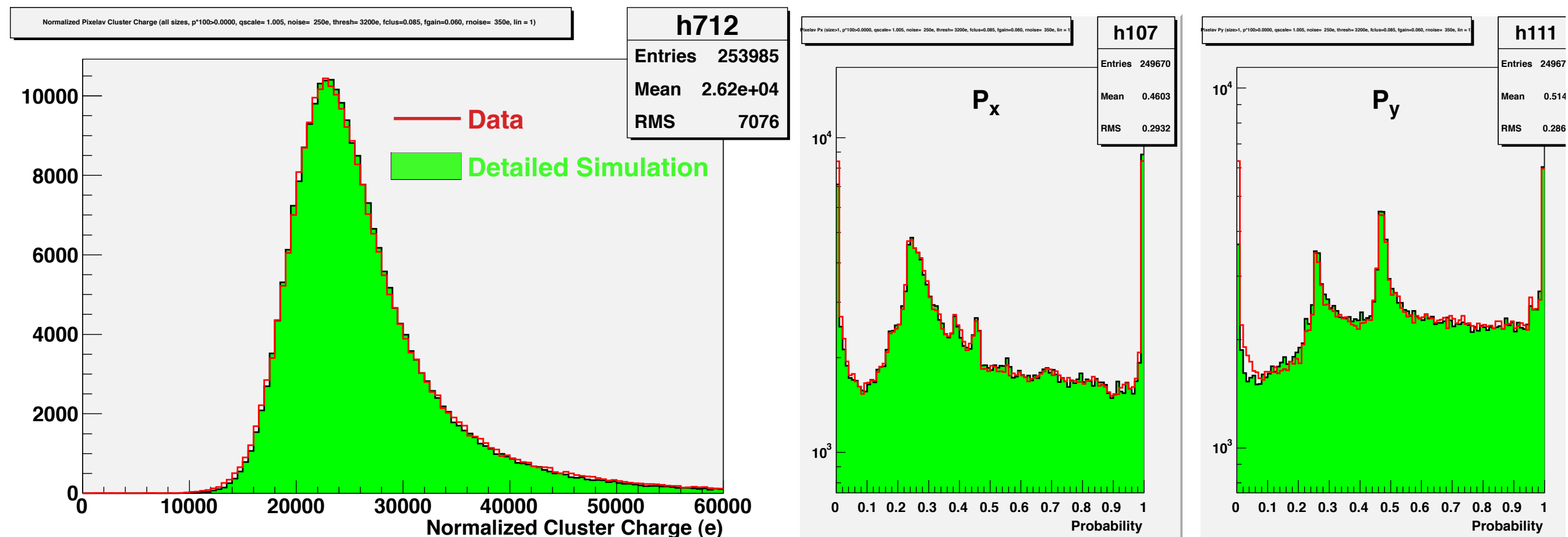
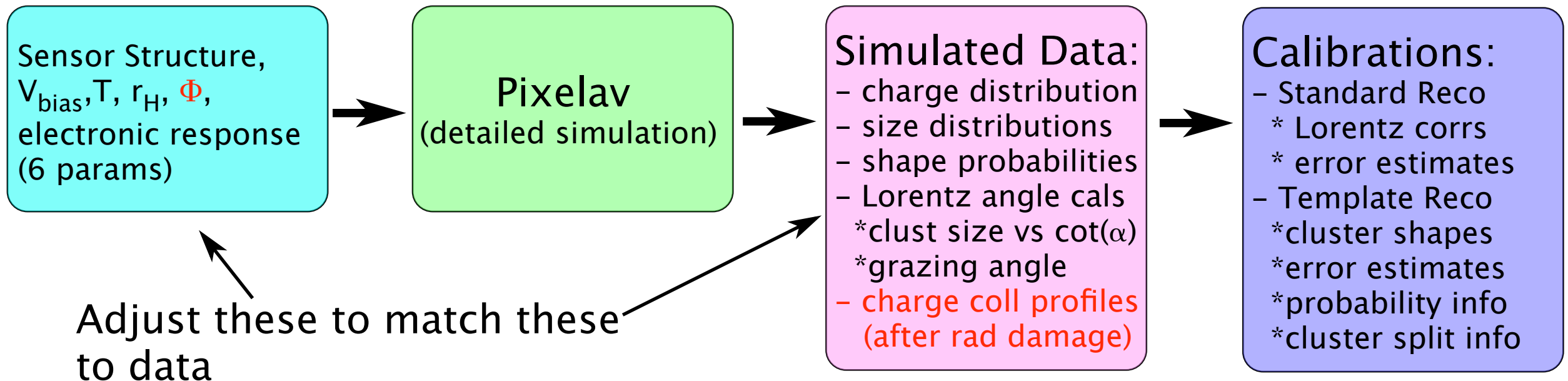
- Charge deposition model based on Bichsel π -Si x-sections
 - delta ray range: Continuous Slowing Down Approx + Nist Estar dedx
 - plural scattering and magnetic curvature of delta ray tracks
- Carrier transport from Runge-Kutta integration of saturated drift

$$\frac{d\vec{x}}{dt} = \vec{v} = \frac{\mu \left[q\vec{E} + \mu r_H \vec{E} \times \vec{B} + q\mu^2 r_H^2 (\vec{E} \cdot \vec{B}) \vec{B} \right]}{1 + \mu^2 r_H^2 |\vec{B}|^2}$$

- electric field map from ISE TCAD simulation of pixel cell
- includes diffusion, trapping, and charge induction on implants
- Electronic Simulation: noise, linearity, thresholds, mis-calibration



Calibration of Reconstruction Algs



Modeling of Irradiated Sensors

Space charge in irradiated sensors can be produced by ionized traps. The Shockley-Read-Hall (SRH) description is based on **ALL** trapping states:

$$\rho_{\text{eff}} = e \sum_D N_D f_D - e \sum_A N_A f_A + \rho_{\text{dopants}} \\ \simeq e [N_D f_D - N_A f_A] + \rho_{\text{dopants}}$$

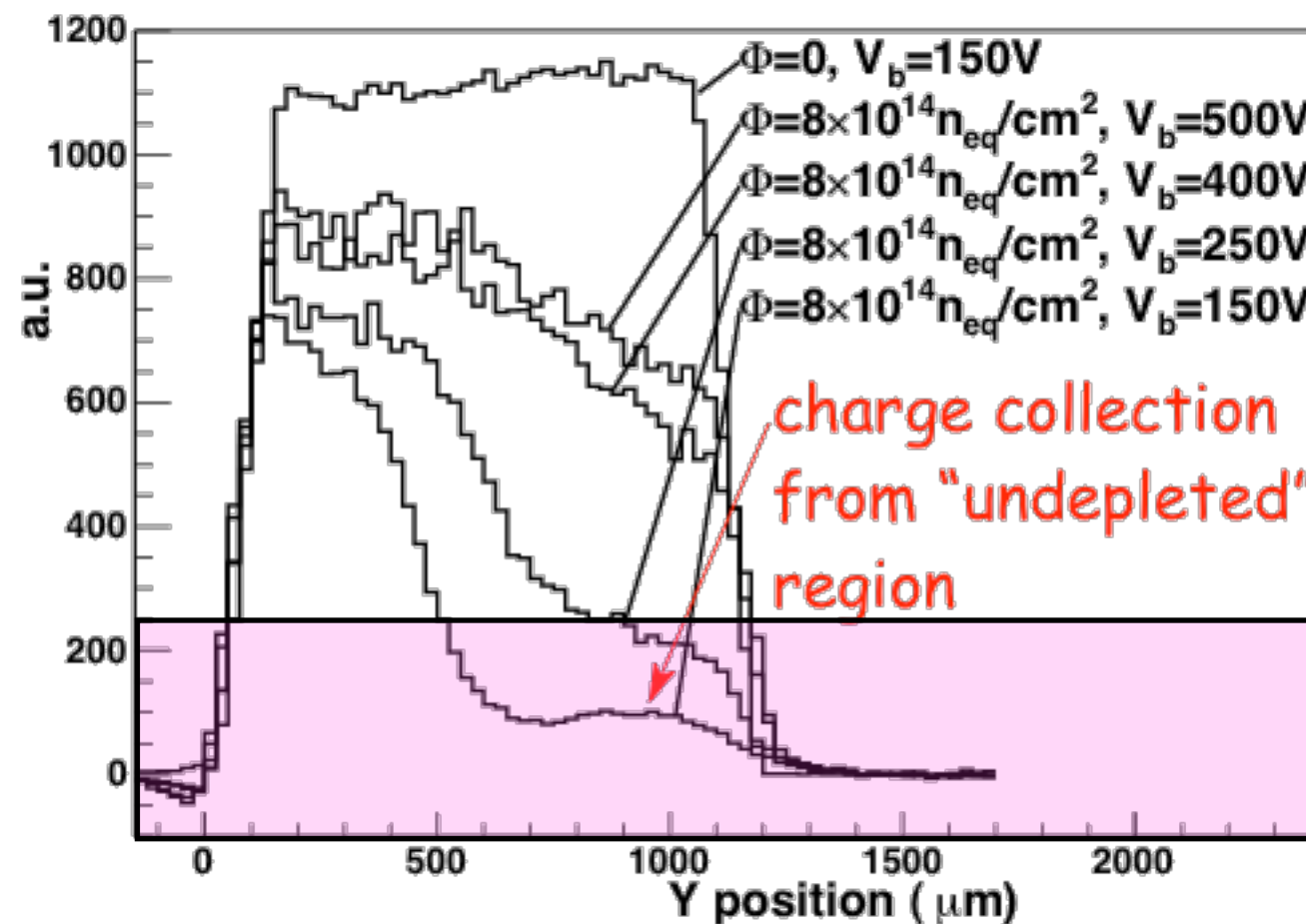
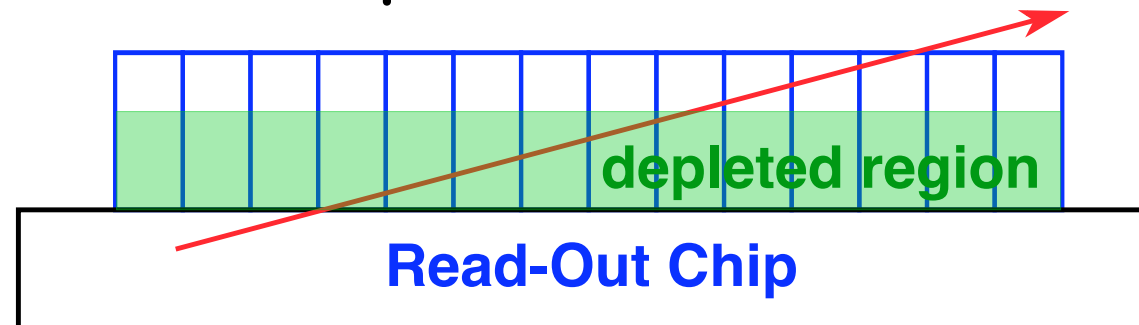
N_D and N_A are the densities of h- and e-traps

f_D and f_A are the trap occupation probabilities

- follow Eremin, Verbitskaya, Li (EVL): use single h/e-traps to model E-field
 - D and A states **don't have to be physical states: they represent average quantities!**
 - model parameters are not physical
- e/h trapping is modeled independently in Pixelav using measured trapping rates to relate them the fluence Φ

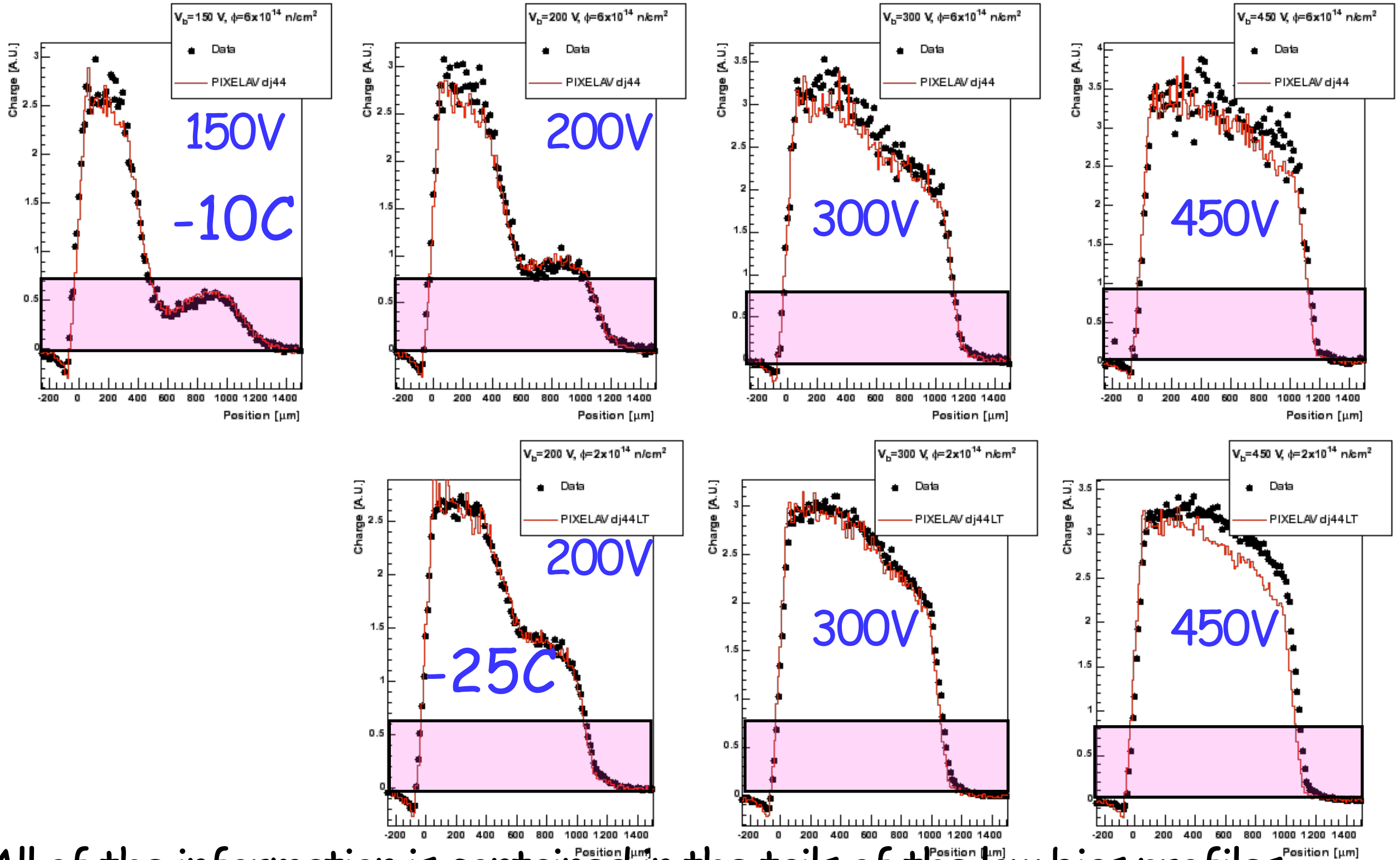
Tuning the Simulation

Compare the charge collection profiles of real and simulated data



- Our test beam experience was based upon reading all pixels (no threshold)
 - in CMS, we will not see the smallest $\sim 25\%$ of the signals

Successful tuning of sensor at $\Phi_1=5.9 \times 10^{14} \text{ n}_{eq}/\text{cm}^2$



- All of the information is contained in the tails of the low bias profiles
 - the “feature” corresponding to the field minimum is observable at some V and T !

Scale to lower fluences using an empirical set of relationships

$$\Gamma_{e/h}(\Phi_2) = R_\Gamma \cdot \Gamma_{e/h}(\Phi_1)$$

$$R_\Gamma = \Phi_2 / \Phi_1$$

$$N_A(\Phi_2) = R_A \cdot N_A(\Phi_1)$$

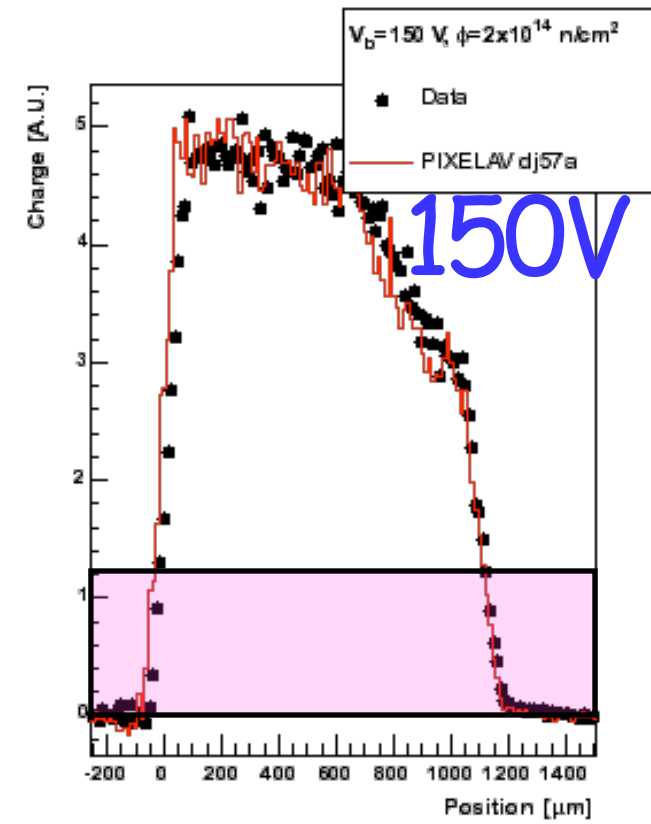
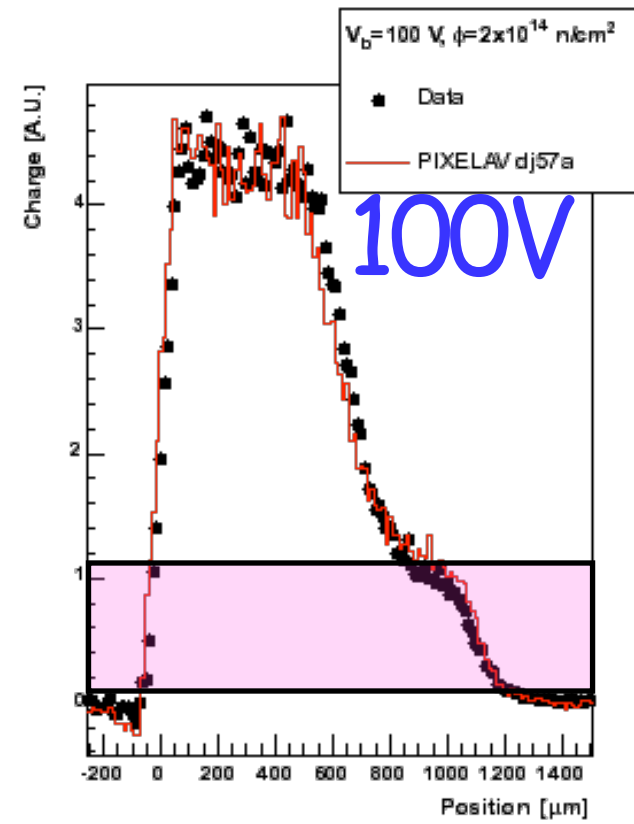
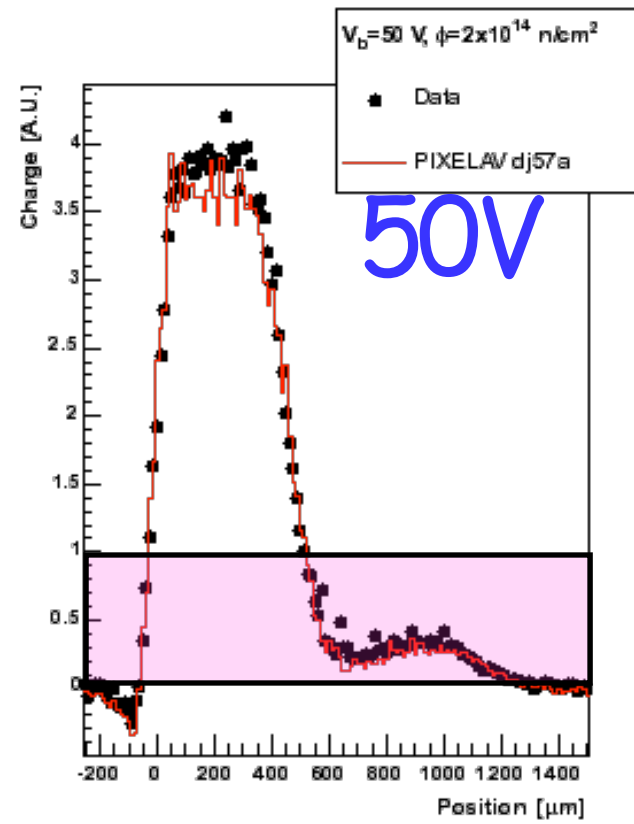
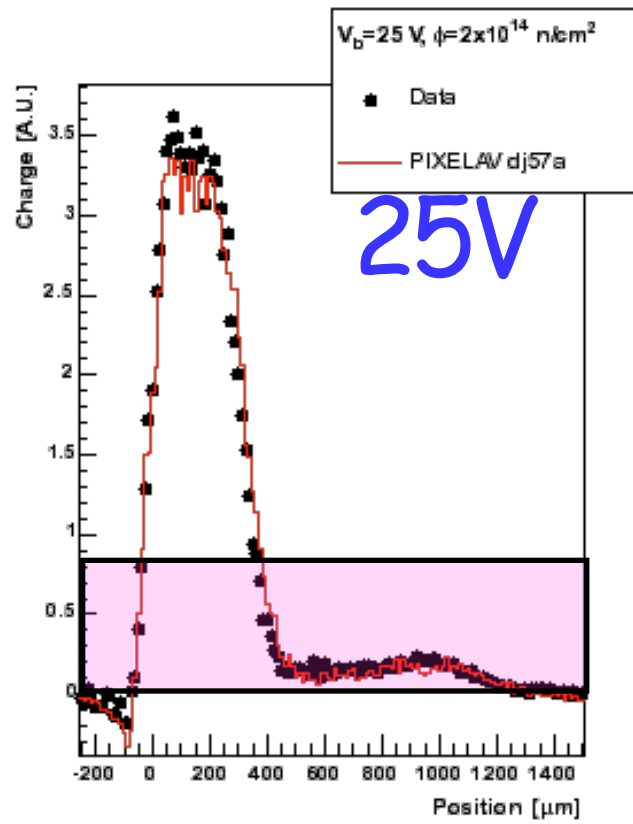
$$R_A = R_\Gamma (1 + \delta)$$

$$N_D(\Phi_2) = R_D \cdot N_D(\Phi_1)$$

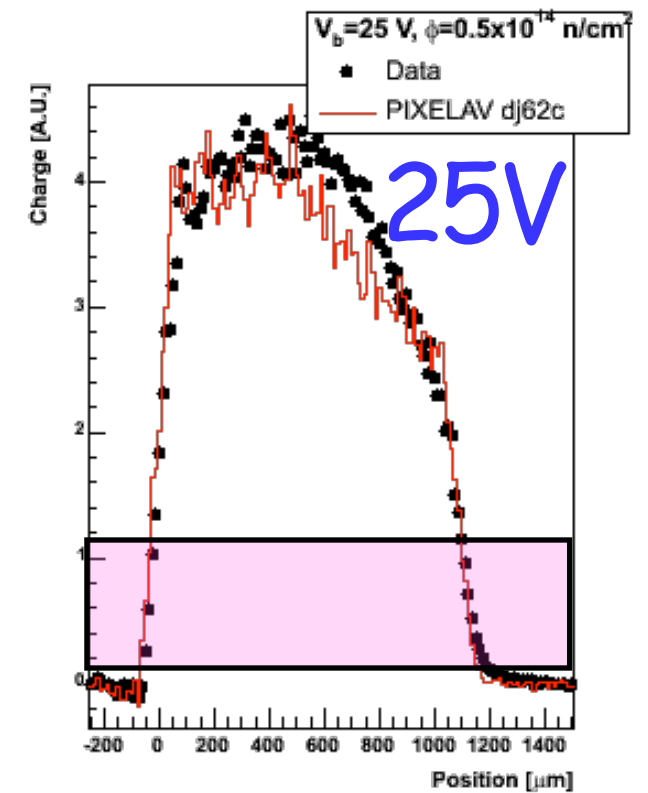
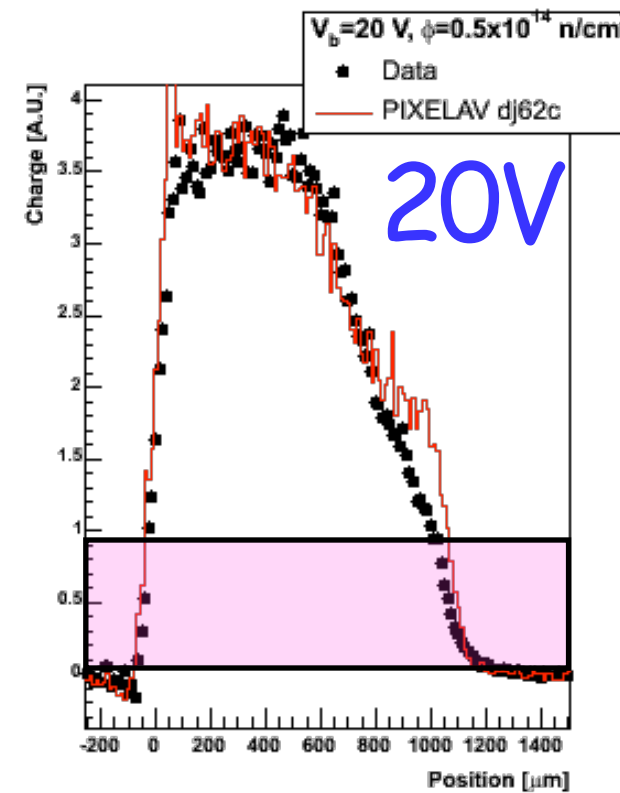
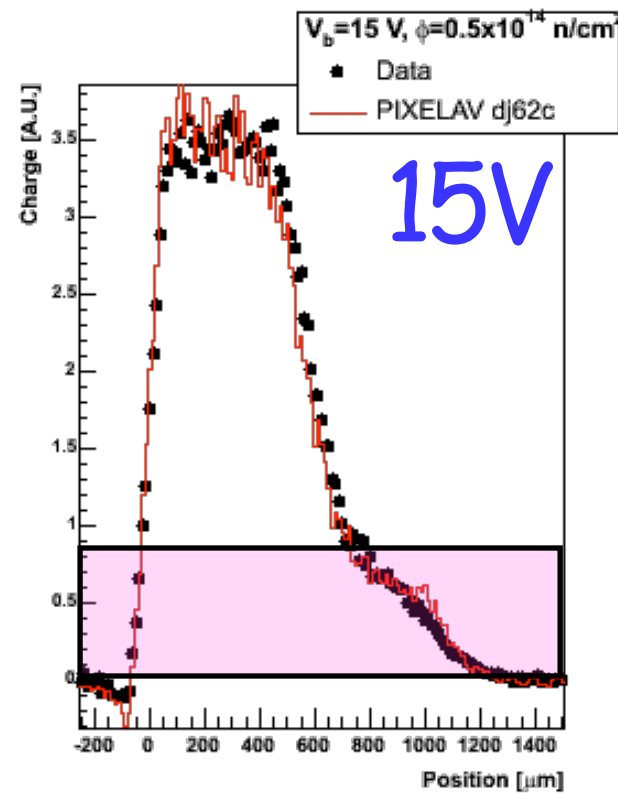
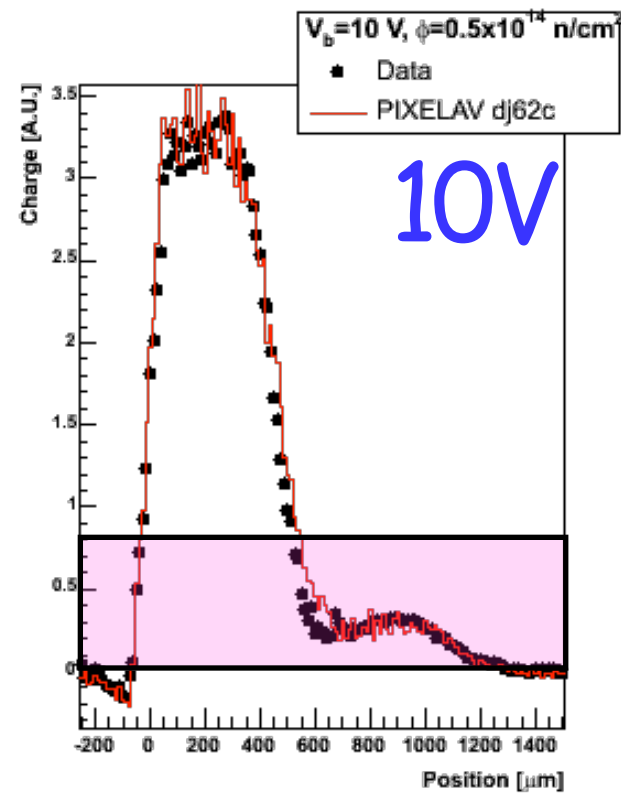
$$R_D = R_\Gamma (1 - \delta)$$

- Trapping rates are linear in the fluence (observed from direct measurements)
- Scale donor and acceptor densities to keep the average factor equal to the ratio of fluences
 - keeps leakage current approximately linear in fluence (also well established)
 - allows the ratio N_A/N_D to vary with fluence

$$\Phi_2 = 2.0 \times 10^{14} \text{ n}_{eq}/\text{cm}^2$$

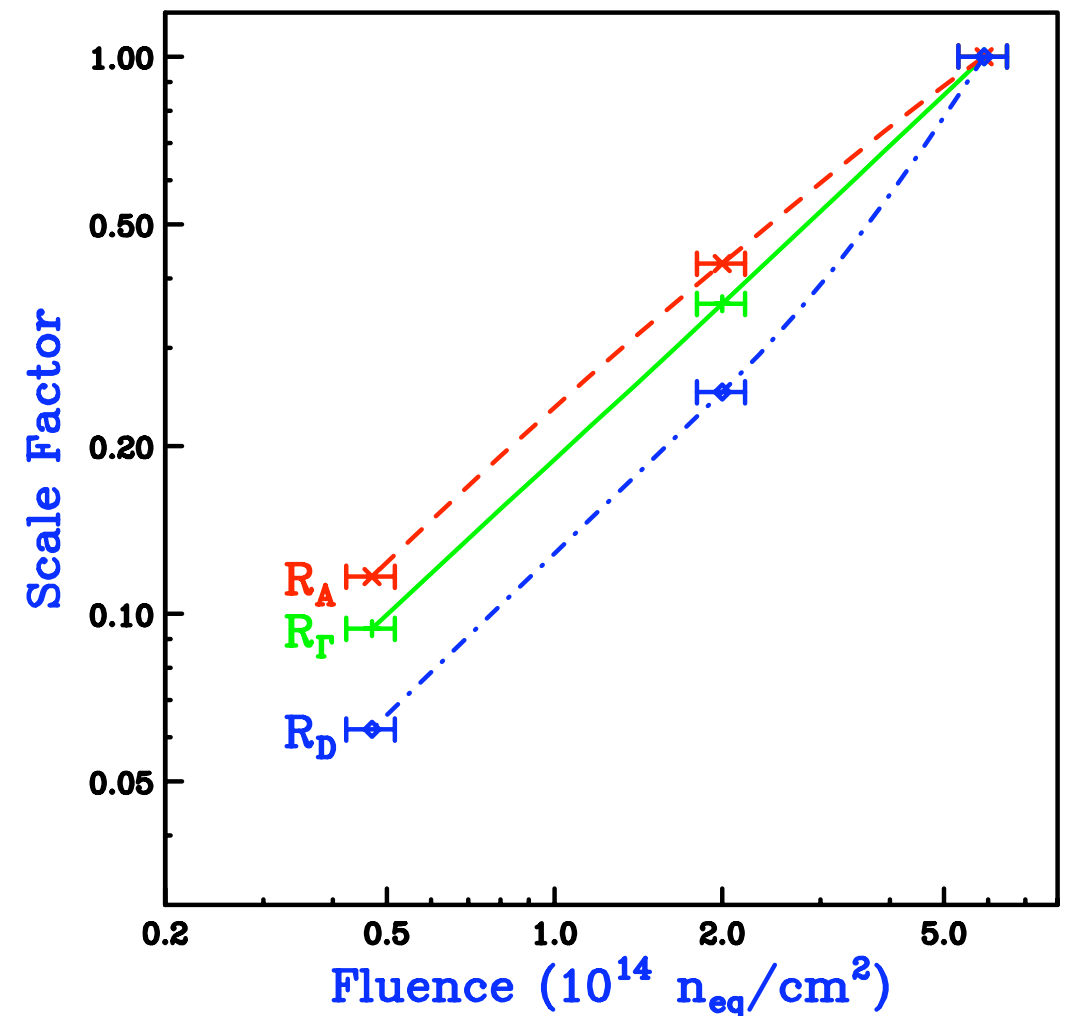


$$\Phi_3 = 0.5 \times 10^{14} \text{ n}_{eq}/\text{cm}^2$$



Scale factor summary:

- ♦ trapping rates are linear in Φ
- ♦ N_A/N_D increases from 0.40 at $\Phi_1 = 5.9 \times 10^{14} \text{ n}_{eq}/\text{cm}^2$ to 0.75 at $\Phi_3 = 0.47 \times 10^{14} \text{ n}_{eq}/\text{cm}^2$



The good news:

- ♦ We have a good understanding of the Φ dependence of the sensor response
 - depends upon only 1 parameter (Φ) modulo annealing effects

The bad news:

- ♦ ROC readout thresholds will limit ability to see the profile tails
 - need voltage points near transition to backside charge collection
- ♦ Poorer resolution of track entry point into sensor than test beam

Expected Effect of Fluence Calibrations

Use tuned simulation to predict performance after damage: **with** and **without** calibration

Generic Algorithm (Barrel)

Fluence Φ	Bias	x Bias	x Res (rms)	x Pull (rms)	y Bias	y Res (rms)	y Pull (rms)
0	150V	-0.6 μm	16.3 μm	1.00	0.1 μm	25.1 μm	1.02
$2 \times 10^{14} \text{ n}_{\text{eq}}/\text{cm}^2$ (no cal)	200V	-12.4 μm	17.0 μm	1.80	-0.1 μm	34.0 μm	1.51
$2 \times 10^{14} \text{ n}_{\text{eq}}/\text{cm}^2$ (w/ cal)	200V	0.8 μm	17.1 μm	0.94	0.0 μm	29.2 μm	0.98
$6 \times 10^{14} \text{ n}_{\text{eq}}/\text{cm}^2$ (no cal)	400V	-22.0 μm	17.4 μm	1.91	0.1 μm	35.1 μm	1.64
$6 \times 10^{14} \text{ n}_{\text{eq}}/\text{cm}^2$ (w/ cal)	400V	1.0 μm	17.1 μm	0.93	0.1 μm	30.6 μm	1.00

Template Algorithm (Barrel)

Fluence Φ	Bias	x Bias	x Res (rms)	x Pull (rms)	y Bias	y Res (rms)	y Pull (rms)
0	150V	-0.3 μm	12.0 μm	1.06	0.1 μm	23.0 μm	1.06
$2 \times 10^{14} \text{ n}_{\text{eq}}/\text{cm}^2$ (no cal)	200V	-13.5 μm	15.1 μm	2.13	-0.1 μm	34.0 μm	1.66
$2 \times 10^{14} \text{ n}_{\text{eq}}/\text{cm}^2$ (w/ cal)	200V	0.3 μm	13.2 μm	1.00	0.0 μm	27.2 μm	1.01
$6 \times 10^{14} \text{ n}_{\text{eq}}/\text{cm}^2$ (no cal)	400V	-22.3 μm	15.6 μm	2.30	0.1 μm	34.4 μm	1.79
$6 \times 10^{14} \text{ n}_{\text{eq}}/\text{cm}^2$ (w/ cal)	400V	0.3 μm	14.7 μm	0.98	0.1 μm	29.0 μm	1.01

Summary

- Bias scans are essential to tune the radiation damage parameters
 - measure charge profiles at a sequence of voltages
 - readout thresholds will hide interesting features
 - * may need fairly fine scan in voltage to see them
 - * can guess voltages from information already available
- Tuned radiation damage simulation is needed even to interpret Lorentz calibrations
 - already have a $\sim 10\%$ correction to account for implant focusing
 - trapping and charge induction change everything even more: can get large offsets
- Tuned simulation is essential to keep the template reco working
 - resolution is improved, biases eliminated
- Tuned simulation is essential to keep error estimates accurate
 - existing error calibration would produce large pulls in both techniques
 - * tracking and b-tagging would be significantly impacted